

Earth Observation  
Mission CFI Software  
  
EO\_POINTING  
SOFTWARE USER MANUAL

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<b>Prepared by:</b>	Fabrizio Pirondini	Project Engineer	
	José Antonio González Abeytua	Project Manager	
	Juan José Borrego	Project Engineer	
	Carlos Villanueva	Project Engineer	
	Rubén Castro	Project Engineer	
<b>Checked by:</b>	José Antonio González Abeytua	Project Manager	
<b>Approved by:</b>	José Antonio González Abeytua	Project Manager	

DEIMOS Space S.L.U.  
Ronda de Poniente, 19  
Edificio Fiteni VI, Portal 2, 2ª Planta  
28760 Tres Cantos (Madrid), SPAIN  
Tel.: +34 91 806 34 50  
Fax: +34 91 806 34 51  
E-mail: deimos@deimos-space.com

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## DOCUMENT INFORMATION

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## DOCUMENT STATUS LOG

Issue	Change Description	Date	Approval
0.1	First draft version	23/05/02	
1.0	First release	19/07/02	
2.0	Second release	29/11/02	
2.1	Maintenance release	13/05/03	
2.2	Added the following functions: <ul style="list-style-type: none"> <li>• xp_target_extra_aux</li> <li>• xp_target_extra_target_to_sun</li> <li>• xp_target_extra_ef_to_sat</li> </ul> Added the following functions: <ul style="list-style-type: none"> <li>• xp_target_extra_aux</li> <li>• xp_target_extra_target_to_sun</li> <li>• xp_target_extra_ef_to_sat</li> </ul> Added the following functions: <ul style="list-style-type: none"> <li>• xp_target_extra_aux</li> <li>• xp_target_extra_target_to_sun</li> <li>• xp_target_extra_ef_to_sat</li> <li>• xp_converter</li> </ul>	30/09/03	
3.0	Completely new initialization strategy and attitude functions.	21/07/04	
3.1	New attitude models implemented. New multitarget functions. New multitarget functions. New multitarget functions.	13/10/04	
3.2	DEM Model implementation. DEM Model implementation. DEM Model implementation.	15/11/04	
3.3	New features: <ul style="list-style-type: none"> <li>• xp_target_travel_time</li> <li>• New attitude models (Cryosat YSM, ADM model)</li> <li>• New attitude files for initialization</li> </ul> Identifier accessors New features: <ul style="list-style-type: none"> <li>• xp_target_travel_time</li> <li>• New attitude models (Cryosat YSM, ADM model)</li> <li>• New attitude files for initialization</li> </ul>	11/07/05	

	<ul style="list-style-type: none"> <li>• Identifier accessors</li> <li>• xp_target_travel_time</li> <li>• New attitude models (Cryosat YSM, ADM model)</li> <li>• New attitude files for initialization</li> <li>• Identifier accessors</li> </ul>		
3.4	<p>New features:</p> <ul style="list-style-type: none"> <li>• New attitude model for ADM</li> <li>• xp_dem_compute</li> <li>• xp_target_reflected and xp_target_extra_specular_reflection (only interface definition)</li> <li>• xp_target_extra_target_to_moon</li> <li>• New axis for the generic attitude models:                             <ul style="list-style-type: none"> <li>– XP_SC_EF_VEL_VEC</li> <li>– XP_ORBIT_POLE</li> </ul> </li> </ul> <p>New features:</p> <ul style="list-style-type: none"> <li>• New attitude model for ADM</li> <li>• xp_dem_compute</li> <li>• xp_target_reflected and xp_target_extra_specular_reflection (only interface definition)</li> <li>• xp_target_extra_target_to_moon</li> <li>• New axis for the generic attitude models:                             <ul style="list-style-type: none"> <li>– XP_SC_EF_VEL_VEC</li> <li>– XP_ORBIT_POLE</li> </ul> </li> </ul> <p>New features:</p> <ul style="list-style-type: none"> <li>• New attitude model for ADM</li> <li>• xp_dem_compute</li> <li>• xp_target_reflected and xp_target_extra_specular_reflection (only interface definition)</li> <li>• xp_target_extra_target_to_moon</li> <li>• New axis for the generic attitude models:                             <ul style="list-style-type: none"> <li>– XP_SC_EF_VEL_VEC</li> <li>– XP_ORBIT_POLE</li> </ul> </li> </ul>	18/11/05	
3.5	<p>Maintenance release</p> <p>New features:</p> <ul style="list-style-type: none"> <li>• Aberration correction for Cryosat attitude based on star-trackers</li> </ul> <p>Maintenance release</p> <p>New features:</p> <ul style="list-style-type: none"> <li>• Aberration correction for Cryosat attitude based on star-trackers</li> </ul> <p>Maintenance release</p> <p>New features:</p> <ul style="list-style-type: none"> <li>• Aberration correction for Cryosat attitude based on star-trackers</li> </ul>	26/05/06	

3.6	<p>Maintenance release</p> <p>New features:</p> <ul style="list-style-type: none"> <li>• New attitude models for SENTINEL 1A and 1B</li> <li>• New Axis defined: XP_INERTIAL_POS_VEC_CORRECTED and XP_INERTIAL_VEL_VEC_ROTATED</li> </ul> <p>Maintenance release</p> <p>New features:</p> <ul style="list-style-type: none"> <li>• New attitude models for SENTINEL 1A and 1B</li> <li>• New Axis defined: XP_INERTIAL_POS_VEC_CORRECTED and XP_INERTIAL_VEL_VEC_ROTATED</li> </ul> <p>Maintenance release</p> <p>New features:</p> <ul style="list-style-type: none"> <li>• New attitude models for SENTINEL 1A and 1B</li> <li>• New Axis defined: XP_INERTIAL_POS_VEC_CORRECTED and XP_INERTIAL_VEL_VEC_ROTATED</li> </ul>	24/11/06	
3.7	<p>Maintenance release</p> <p>New features:</p> <ul style="list-style-type: none"> <li>• Function expcfi_check_libs</li> <li>• Library version for MAC OS X on Intel (32 and 64-bits)</li> </ul> <p>Maintenance release</p> <p>New features:</p> <ul style="list-style-type: none"> <li>• Function expcfi_check_libs</li> <li>• Library version for MAC OS X on Intel (32 and 64-bits)</li> </ul> <p>Maintenance release</p> <p>New features:</p> <ul style="list-style-type: none"> <li>• Function expcfi_check_libs</li> <li>• Library version for MAC OS X on Intel (32 and 64-bits)</li> </ul>	13/07/07	
3.7.2	<p>Maintenance release</p> <p>New features:</p> <ul style="list-style-type: none"> <li>• Support for missalignment for attitude frame</li> <li>• Azimuth and Elevation definition for attitude frames</li> <li>• Improvement in the quaternion interpolation</li> </ul> <p>Maintenance release</p> <p>New features:</p> <ul style="list-style-type: none"> <li>• Support for missalignment for attitude frame</li> <li>• Azimuth and Elevation definition for attitude</li> </ul>	13/07/07	

	<p>frames</p> <ul style="list-style-type: none"> <li>Improvement in the quaternion interpolation</li> </ul> <p>Maintenance release</p> <p>New features:</p> <ul style="list-style-type: none"> <li>Support for missalignment for attitude frame</li> <li>Azimuth and Elevation definition for attitude frames</li> <li>Improvement in the quaternion interpolation</li> </ul>		
4.0	<p>Maintenance release</p> <p>Maintenance release</p> <p>Maintenance release</p>	19/01/09	
4.1	<p>Maintenance release.</p> <p>New features:</p> <ul style="list-style-type: none"> <li>Pointing functions support DEM GETASSEv2</li> <li>Sentinel-1 attitude model (roll steering)</li> <li>Instrument offsets for attitude computations</li> </ul>	07/05/10	
4.2	<p>Maintenance release.</p> <p>New features:</p> <ul style="list-style-type: none"> <li>Support to DEM ACE2 9SEC</li> </ul>		
4.3	<p>Maintenance release.</p> <p>New features:</p> <ul style="list-style-type: none"> <li>Raytracing model in target functions determined by input <code>atmos_id</code></li> <li>New attitude model for SENTINEL2 (XP_MODEL_SENTINEL2)</li> </ul>		
4.4	<p>Maintenance release.</p> <p>New features:</p> <ul style="list-style-type: none"> <li>Support for GEO satellites:           <ul style="list-style-type: none"> <li>New Yaw flip attitude</li> <li>New function <code>xp_target_sc</code></li> </ul> </li> <li>Option to use a memory cache for DEM computations. New function to configure cache</li> <li>New function <code>xp_target_list_inter</code></li> </ul>		

4.5	<p>Maintenance release</p> <p>New features:</p> <ul style="list-style-type: none"> <li>• New functions:           <ul style="list-style-type: none"> <li>- xp_target_list_extra_vector</li> <li>- xp_target_list_extra_main</li> <li>- xp_target_list_extra_aux</li> <li>- xp_target_list_extra_ef_target</li> <li>- xp_target_list_extra_specular_reflection</li> <li>- xp_target_list_extra_target_to_moon</li> <li>- xp_target_list_extra_target_to_sun</li> </ul> </li> <li>• New DEM algorithm of maximum heights</li> </ul>		
4.6	<p>Maintenance release</p> <p>New features:</p> <ul style="list-style-type: none"> <li>• New function xp_attitude_define.</li> <li>• Internal improvements for runtime performance in DEM computations.</li> </ul>		
4.7	Maintenance release	28/03/14	
4.8	<p>Maintenance release</p> <p>New features:</p> <ul style="list-style-type: none"> <li>• Added support for Earth Fixed input in initialization of satellite nominal attitude with harmonics.</li> </ul>	29/10/2014	
4.9	Maintenance release	23/04/2015	
4.10	<p>Maintenance release</p> <p>New features:</p> <ul style="list-style-type: none"> <li>• Support for DEM ACE2 30 secs</li> <li>• Target functions: possibility of considering light travel time in target computation</li> <li>• Run-time improvements in target functions</li> </ul>	29/10/2015	

4.11	Maintenance release New features: <ul style="list-style-type: none"> <li>• Support for DEM ACE2 3 secs</li> <li>• New functions xp_gen_attitude_data and xp_gen_attitude_file</li> </ul>		
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## 1 SCOPE

The EO\_POINTING Software User Manual provides a detailed description of usage of the CFI functions included within the EO\_POINTING CFI software library.

## 2 ACRONYMS, NOMENCLATURE AND TERMINOLOGY

### 2.1 Acronyms

ANX	Ascending Node Crossing
AOCS	Attitude and Orbit Control Subsystem
ASCII	American Standard Code for Information Interchange
CFI	Customer Furnished Item
CS	Coordinate System
DRS	Data Relay Satellite
ESA	European Space Agency
ESTEC	European Space Technology and Research Centre
GPL	GNU Public Library
GPS	Global Positioning System
GS	Ground Station
H/W	Hardware
IERS	International Earth Rotation Service
I/F	Interface
LOS	Line Of Sight
LUT	Look-Up Table
OBT	On-board Binary Time
OSF	Orbit Scenario File
RAM	Random Access Memory
SBT	Satellite Binary Time
SRAR	Satellite Relative Actual Reference
SSP	Sub Satellite Point
SUM	Software User Manual
S/W	Software
TAI	International Atomic Time
UTC	Coordinated Universal Time
UT1	Universal Time UT1
WGS[84]	World Geodetic System 1984

## 2.2 Nomenclature

<i>CFI</i>	A group of CFI functions, and related software and documentation that will be distributed by ESA to the users as an independent unit
<i>CFI function</i>	A single function within a CFI that can be called by the user
<i>Library</i>	A software library containing all the CFI functions included within a CFI plus the supporting functions used by those CFI functions (transparently to the user)

## 2.3 Note on Terminology

In order to keep compatibility with legacy CFI libraries, the Earth Observation Mission CFI Software makes use of terms that are linked with missions already or soon in the operational phase like the Earth Explorers.

This may be reflected in the rest of the document when examples of Mission CFI Software usage are proposed or description of Mission Files is given.



## 3 APPLICABLE AND REFERENCE DOCUMENTS

### 3.1 Applicable Documents

No applicable documents.

### 3.2 Reference Documents

[MCD]	Earth Observation Mission CFI Software. Conventions Document. EO-MA-DMS-GS-0001.
[MSC]	Earth Observation Mission CFI Software. Mission Specific Customizations. EO-MA- DMS-GS-0018.
[GEN_SUM]	Earth Observation Mission CFI Software. General Software User Manual. EO-MA- DMS-GS-0002.
[F_H_SUM]	Earth Observation Mission CFI Software. EO_FILE_HANDLING Software User Manual. EO-MA-DMS-GS-0008.
[D_H_SUM]	Earth Observation Mission CFI Software. EO_DATA_HANDLING Software User Manual. EO-MA-DMS-GS-007.
[LIB_SUM]	Earth Observation Mission CFI Software. EO_LIB Software User Manual. EO-MA-DMS-GS-003.
[LOS_ALG]	LOS Intersection. PE-TN-ESA-SY-0043

The latest applicable version of [MCD], [GEN\_SUM], [F\_H\_SUM], [D\_H\_SUM], [LIB\_SUM] is v4.10 and can be found at: [http://eop-cfi.esa.int/REPO/PUBLIC/DOCUMENTATION/CFI/EOCFI/BRANCH\\_4X/](http://eop-cfi.esa.int/REPO/PUBLIC/DOCUMENTATION/CFI/EOCFI/BRANCH_4X/)

## 4 INTRODUCTION

### 4.1 Functions Overview

This software library contains the CFI functions required to perform accurate computation of pointing parameters from and to a satellite for various types of targets.

It includes a set of functions to initialize the attitude of the platform and the instruments. The values provided by these functions are later used by all the other functions of the library.

A detailed description of each function is provided in Section 7.

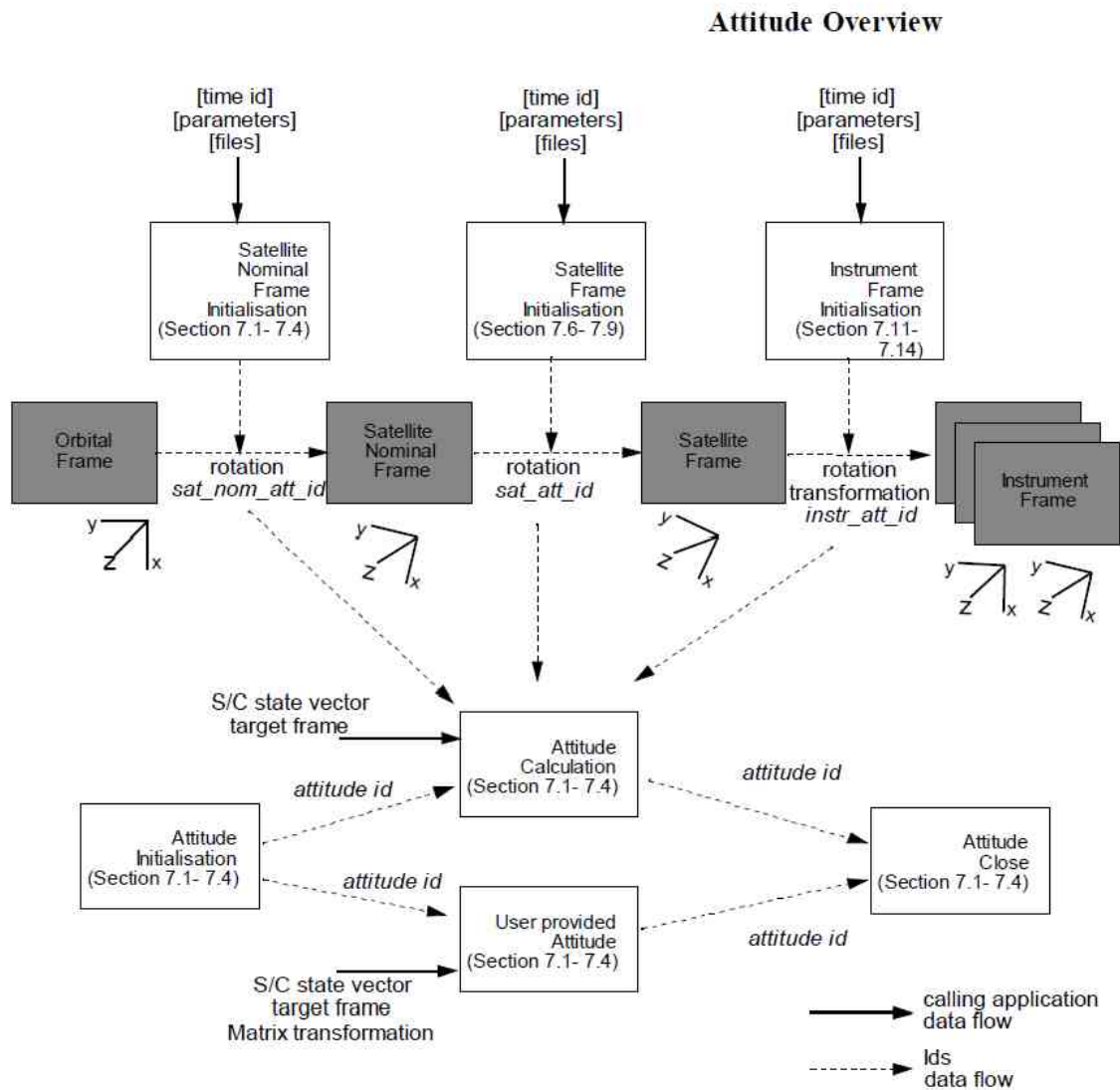
Please refer also to:

[MCD] for a detailed description of the time references and formats, coordinate systems, parameters and models used in this document

[GEN\_SUM] for a complete overview of the CFI, and in particular the detailed description of the *Id* concept and usage and the error handling functions.

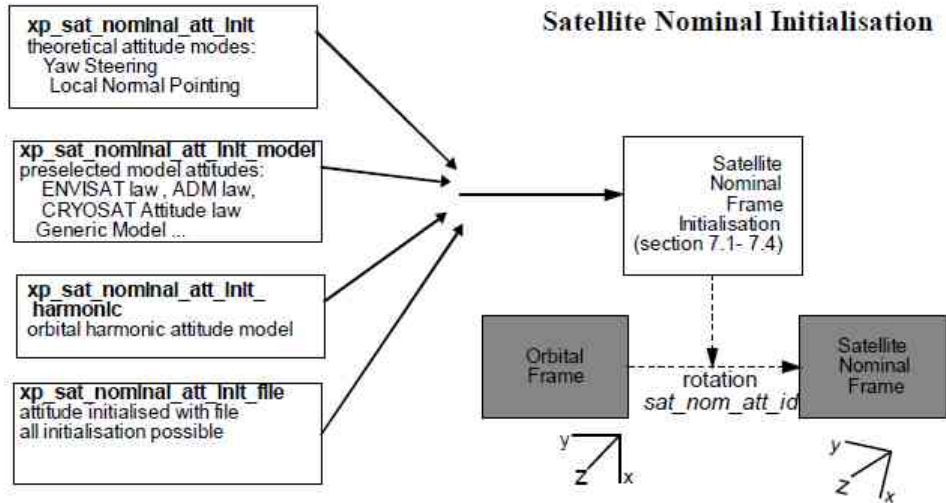
### 4.1.1 Attitude Data Flow

The following figure shows the typical data flow for the attitude functions. First, the different transformations between the various reference frames are initialised. Then, given the spacecraft position, the attitude is calculated:

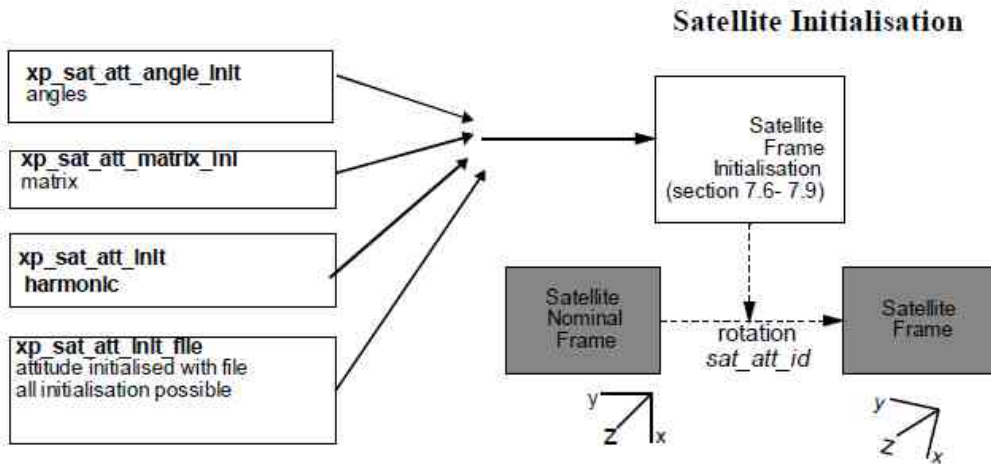


**Figure 1: Attitude Initialization Overview**

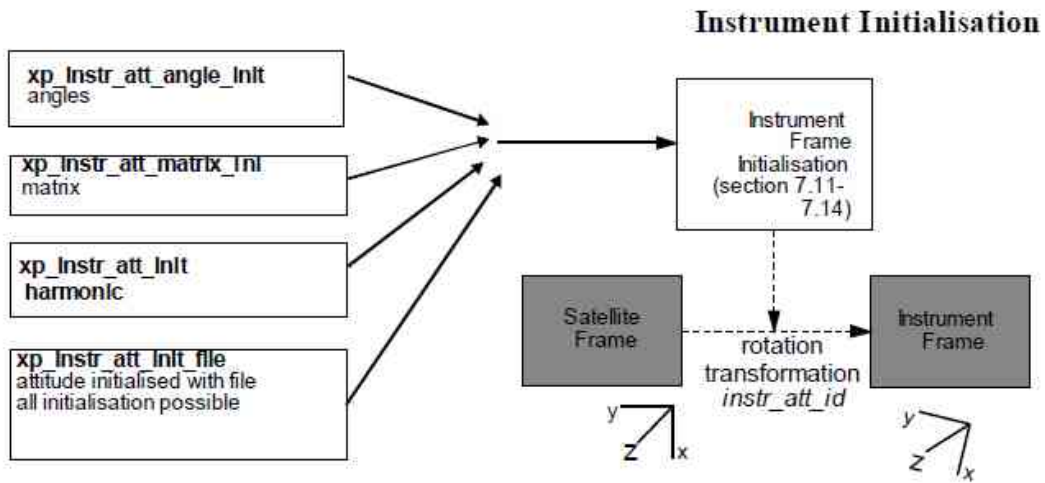
Each different transformation can be initialised with different models (note that all the attitudes can be initialized at the same time using the function `xp_attitude_define` (see section 7.47) and an Attitude definition file):



**Figure 2: Satellite Nominal Initialization**



**Figure 3: Satellite Initialization**



**Figure 4: Instrument Initialization**

### 4.1.2 Geolocation Routines Data Flow

The following figure shows the typical data flow for the geolocation routines functions. First, the attitude should be calculated, and, if needed, the refraction and Digital Elevation Models initialised.

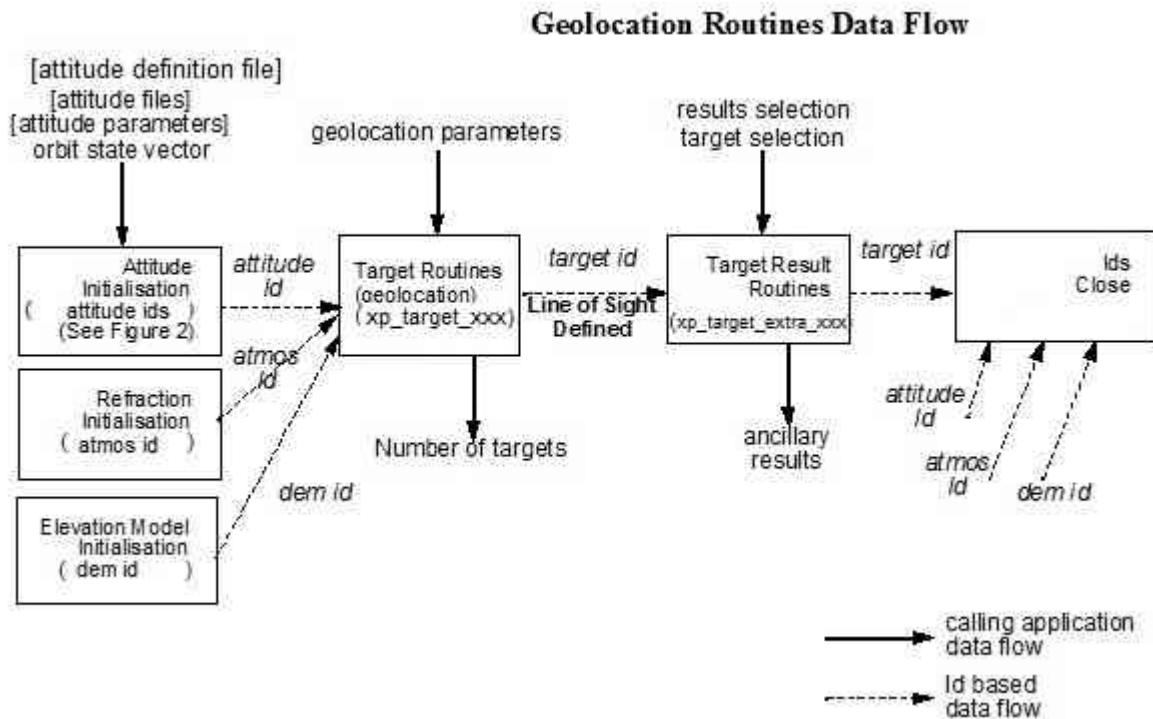
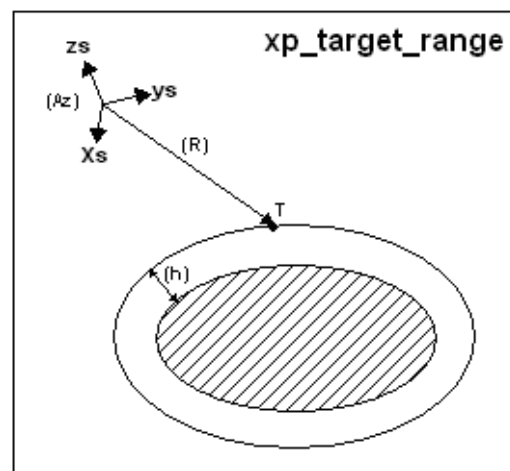
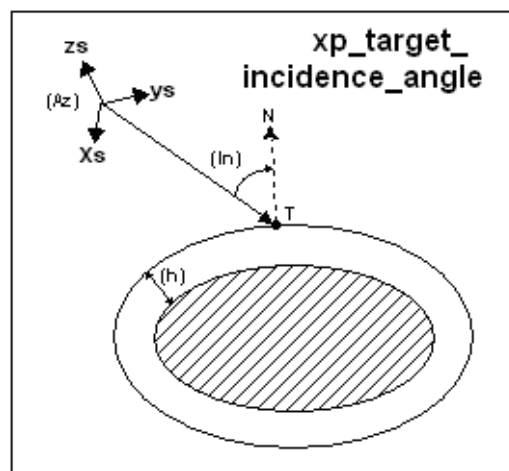
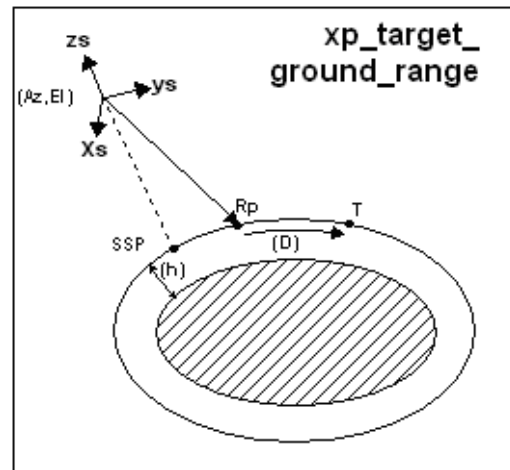
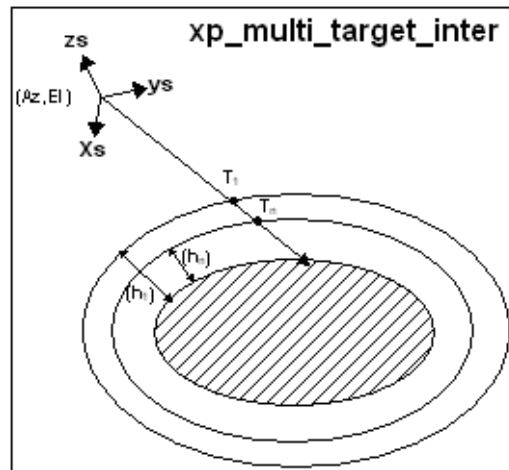
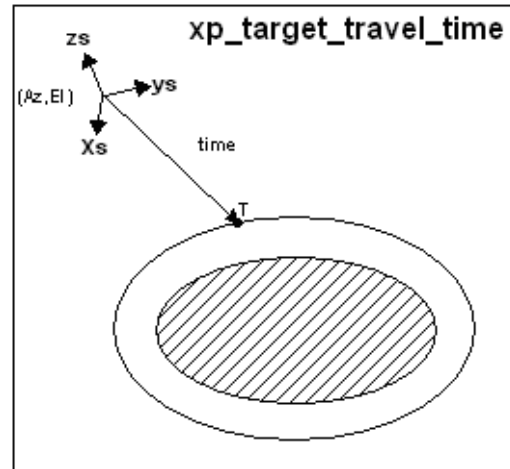
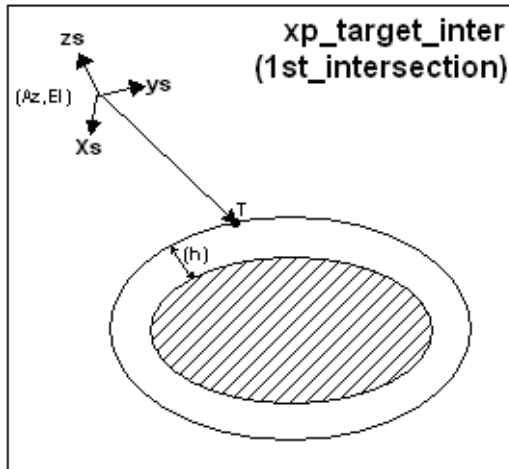


Figure 5: Geolocation Routines Calling Sequence

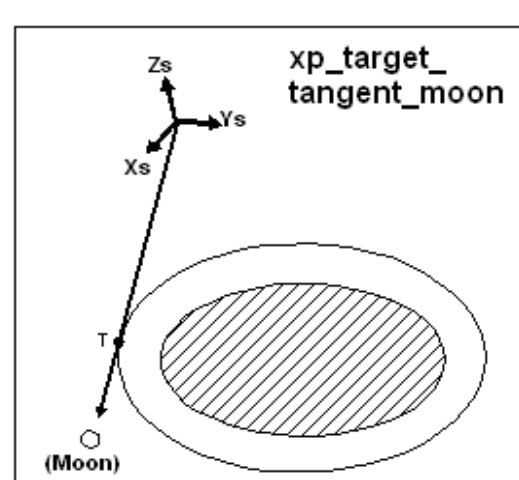
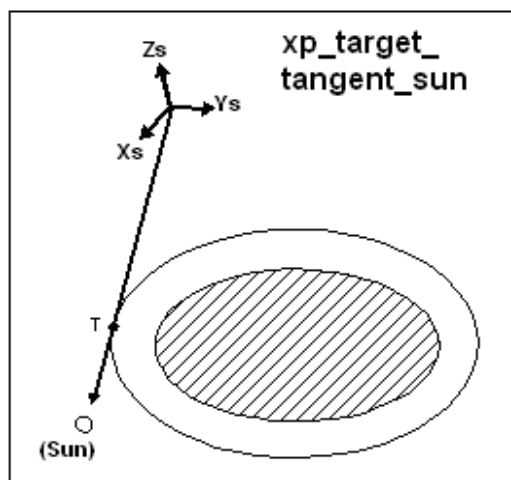
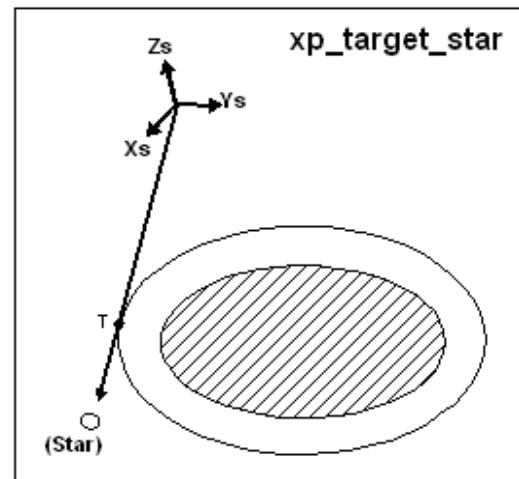
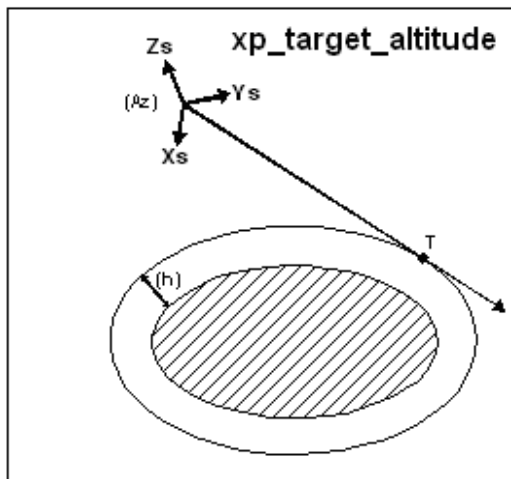
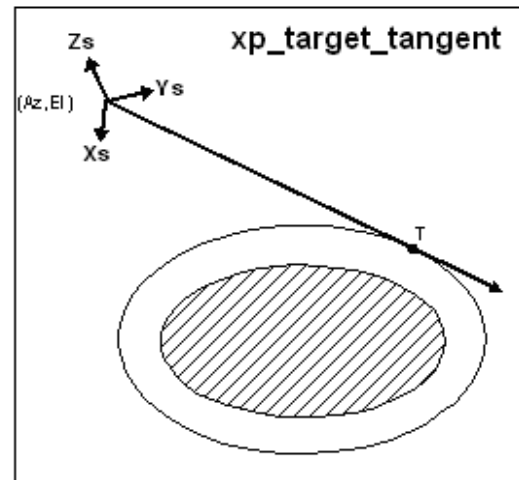
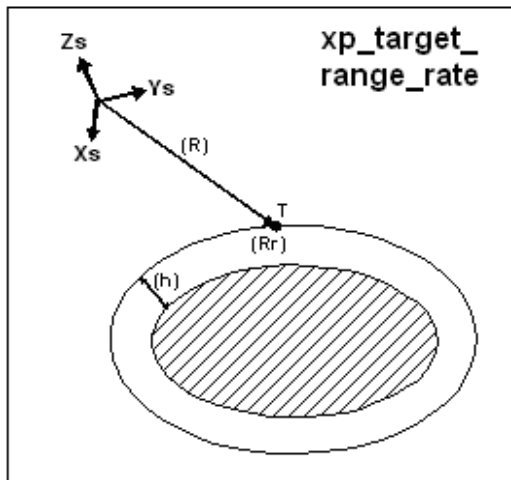
The table below and the diagrams on the next pages describe the various **xp\_target\_<function>**.

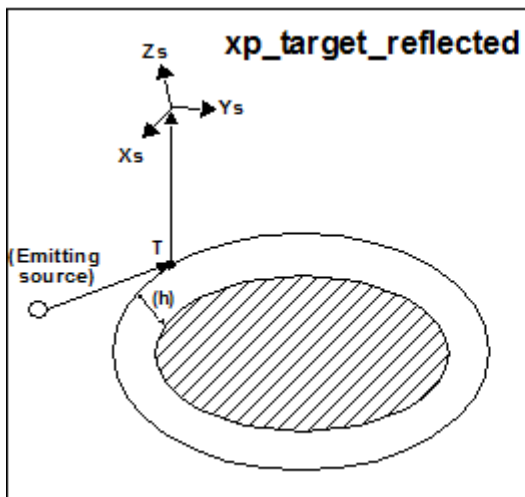
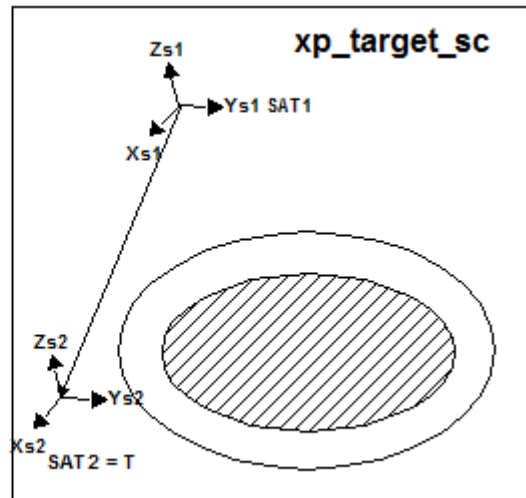
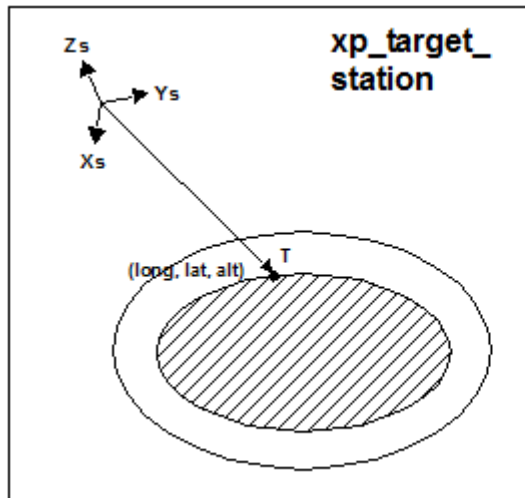
**Table 1: xp\_target functions**

<b>xp_target_&lt;function&gt;</b>	<b>Description</b>
xp_(multi)_target_inter xp_target_list_inter	It calculates the intersection point(s) of the line of sight defined by an elevation and an azimuth angle (or a set of them) expressed in the input Attitude frame, with a surface(s) located at a certain geodetic altitude(s) over the Earth.
xp_(multi)_target_travel_time	It calculates the point of the line or sight from the satellite (defined by an elevation and an azimuth angle expressed in the selected Attitude Frame) at a given travel time(s) along the (curved) line of sight.
xp_target_ground_range	It calculates the location of a point that is placed on a surface at a certain geodetic altitude over the Earth, that lays on the plane defined by the S/C position, the nadir and a reference point, and that is at a certain distance or ground range measured along that surface from that reference point. This reference point is calculated being the intersection of the previous surface with the line of sight defined by an elevation and azimuth angle in the input Attitude coordinate system.
xp_target_incidence_angle	It calculates the location of a point that is placed on a surface at a certain geodetic altitude over the Earth and that is seen from the S/C on a line of sight that forms a certain azimuth angle in the input Attitude frame and that intersects that surface with a certain incidence angle.
xp_target_range	It calculates the location of a point that is placed on a surface at a certain geodetic altitude over the Earth, that is seen from the S/C on a line of sight that forms a certain azimuth angle in the input Attitude frame, and that is at a certain range or slant-range from the S/C.
xp_target_range_rate	It calculates the location of a point that is placed on a surface at a certain geodetic altitude over the Earth, that is at a certain range from S/C, and whose associated Earth-fixed target has a certain range-rate value.
xp_target_tangent	It calculates the location of the tangent point over the Earth that is located on the line of sight defined by an elevation and azimuth angles expressed in the input Attitude frame.
xp_target_altitude	It calculates the location of the tangent point over the Earth that is located on a surface at a certain geodetic altitude over the Earth and that is on a line of sight that forms a certain azimuth angle in the input Attitude frame.
xp_target_star	It calculates the location of the tangent point over the Earth that is located on the line of sight that points to a star defined by its right ascension and declination coordinates.
xp_target_generic	The cartesian state vector of the target is taken as an input.
xp_target_tangent_sun	It calculates the location of the tangent point over the Earth that is located on the line of sight that points to the Sun
xp_target_tangent_moon	It calculates the location of the tangent point over the Earth that is located on the line of sight that points to the Moon
xp_target_station	It calculates the most relevant observation parameters of the link between the satellite and a ground station
xp_target_sc	It calculates the most relevant observation parameters of the link between one satellite and another Satellite.









$[X_s, Y_s, Z_s]$  = Attitude Frame

( ) = Input data to the mode

(Az, El) = Azimuth + Elevation of the LOS

(h) = Geodetic altitude of the target

(R) = Range Satellite  $\leftrightarrow$  Reference Point/Target

(D) = Distance or Ground range Ref. Point  $\leftrightarrow$  Target

(In) = Incidence angle of the LOS

(Rr) = Range-rate of the Earth-fixed target

T = Target

SSP = Sub Satellite Point = Nadir of the satellite

Rp = Reference Point

N = Normal vector to the surface at a geodetic altitude = h

As it can be seen from the list of functions, there are some functions that calculate several targets (`xp_multi_target_xxxx`, `xp_target_list_inter`). The number of targets found by the functions is returned through the interface.

In addition to these “user” targets, two other categories of targets can be defined, “LOS” targets and “DEM” targets.

#### 4.1.2.1 LOS targets

The idea is to get information about all the ray path points computed by a specific target routine along the Line of Sight (LOS) trajectory.

For every target routine, the output parameter `num_los_target` will return the number of points in the path.

It applies when the variable "target\_type" is equal to `XP_LOS_TARGET_TYPE`.

##### 1. Start point of LOS

The spacecraft position (Instrument CS) shall be considered as the start point for the LOS path.

## 2. Stop point of LOS

The stop point for the LOS path will be different depending on the selected target function; nominally it will be the resulting target point.

- `xp_target_inter`, `xp_target_list_inter` and `xp_multi_target_inter`: 1st or 2nd intersection point (Point corresponding to the last altitude for the `multi_target` routine)
- `xp_target_ground_range`: Target point
- `xp_target_incidence_angle`: Target point
- `xp_target_range`: Target point
- `xp_target_range_rate`: Target point
- `xp_target_tangent`: Two different cases to consider depending on whether refraction is selected or not:
  - No refraction mode: Tangent point
  - Refraction mode:
    - The 2nd intersection point with a surface located at Refraction Model Maximum Height (geodetic altitude) over the Earth if tangent height  $\leq$  Refraction Model Maximum Height
    - The tangent point if tangent height  $>$  Refraction Model Maximum Height
- `xp_target_altitude`: Point at selected altitude
- `xp_target_star`: Two different cases to consider depending on whether refraction is selected or not:
  - No refraction mode: Tangent point
  - Refraction mode:
    - The 2nd intersection point with a surface located at Refraction Model Maximum Height (geodetic altitude) over the Earth if tangent height  $\leq$  Refraction Model Maximum Height
    - The tangent point if tangent height  $>$  Refraction Model Maximum Height
- `xp_target_station`: Ground Station position
- `xp_target_generic`: Target position
- `xp_target_reflected`: Reflection point
- `xp_target_travel_time` and `xp_multi_target_travel_time`: Point at selected travel time (Point corresponding to the last travel time for the `multi_target` routine)
- `xp_target_tangent_sun`: Tangent point
- `xp_target_tangent_moon`: Tangent point
- `xp_target_sc`: Target position.

### 4.1.2.2 DEM targets

A DEM Target is defined as the intersection of a line of sight with the Earth Surface defined using a digital elevation model (DEM).

A DEM Target is calculated using as line of sight the LOS targets that has been computed previously with a target routine (Note that such LOS consist in a polygonal line, no necessarily a straight line). Consequently, to get a DEM target it is necessary to follow these steps:

- Initialize the DEM model using the `xp_dem_init` routine and a configuration file (Section 7.60).
- One call to the target routine for getting the LOS targets.
- One call to the target extra routine requesting the DEM target.

The digital elevation model of the Earth consists in a set of points defining a grid for which a measure of the altitude over the Earth reference ellipsoid is given. The altitude of the points within each cell of the grid is computed by the CFI using a bilinear interpolation with the points of the corner of the cell. Details about the bilinear algorithm used to compute the intersection can be seen in [LOS\_ALG].

#### 4.1.2.3 Light propagation model

When the light propagation model is enabled, the target functions keep into account the time spent by a generic signal traveling at the speed of light to:

- in the TRANSMITTER mode: go from the satellite to the target;
- in the RECEIVER mode: go from the target to the satellite.

Two distinct times are considered:

1) The satellite time ( $T$ ) is the time provided as input to the target function. It is:

- in the TRANSMITTER mode: the time at which the satellite (instrument) emits the signal towards the target;
- in the RECEIVER mode: the time at which the satellite (instrument) receives the signal emitted by the target.

2) The target time is the satellite time  $T$  plus or minus the light travel time between satellite and target ( $dT$ ). It is:

- in the TRANSMITTER mode:  $T+dT$ , i.e. the target receives the signal sent by the satellite with a delay  $dT$ ;
- in the RECEIVER mode:  $T-dT$ , i.e. the satellite receives the signal emitted by the target with a delay  $dT$ .

$dT$  is calculated as the light travel time from the satellite to target calculated with  $dT=0$ . When the light propagation model is not activated, it is assumed  $dT=0$ , therefore target and satellite are considered at the same time  $T$ .

According to the definitions above, the Line of Sight (LOS) can be defined as the segment joining satellite and target at their correspondent times.

For the following functions the calculation method is slightly different:

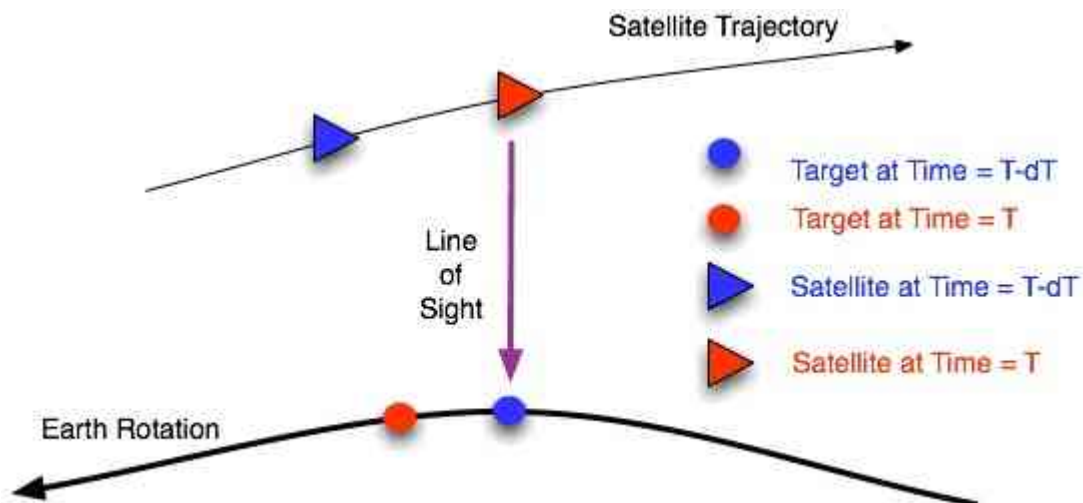
- `xp_target_range`: the input range is used to calculate the light travel time;
- `xp_target_travel_time`: the input travel time is used as  $dT$ ;

- `xp_target_generic`, `xp_target_sc`: in this case the input is the target at time  $T \pm dT$ . The function estimates the target at  $T$  to compute the line of sight parameters also considering (if provided as inputs) velocity and acceleration of the target.

Target geometric properties (returned by the extra functions) are evaluated considering the two distinct times, for example:

- The target position (i.e. position in EF co-ordinates and geodetic co-ordinates) is evaluated at time  $T-dT$ ;
- Direction from satellite to target and viceversa are evaluated considering the satellite position at time  $T$  and target position at time  $T \pm dT$ ;
- Direction from target to e.g. sun/moon take into account the target position at  $T \pm dT$  and other celestial bodies at the same time.

Following figure 6. shows an example using the `xp_target_inter` function.



**Figure 6: Example of light travel time with `xp_target_inter`**

The light propagation mode is set to RECEIVER and input azimuth,elevation are **0, 90 deg** (assuming a local normal pointing). The signal is emitted by the target at time  $T-dT$  (blue point, let's assume at geodetic co-ordinates **(lon,lat,h)** and EF co-ordinates **(X,Y,Z)** ) and is received by the satellite at time  $T$  (red triangle). Due to Earth rotation, at time  $T$  the observed target has moved to the red point.

Here are some examples of results from `xp_target_extra...` functions:

- `xp_target_extra_vector`:
  - Target position: the vector **(X,Y,Z)**, i.e. the target point considered at  $T-dT$ ;

- Direction LOS: the vector corresponding to the purple line in Fig. X (it is the line joining satellite position at time T and target position at time T-dT);
- `xp_target_extra_main`:
  - Target geodetic co-ordinates: **(lon,lat,h)**
  - Satellite to target azimuth, elevation: **0,90**, i.e. the same azimuth and elevation used as input for `xp_target_inter`.
  - Target to satellite azimuth, elevation: **0,90**, this is the view direction from the target at time T-dT to the satellite at time T.

The same results are given by the `xp_target_extra...` functions if the `xp_target_generic` is called with input target at EF co-ordinates **(X,Y,Z)** and velocity set to zero.

To activate the light propagation mode the `model_id` structure must be initialized using the function `xl_model_init` as follow:

1) for TRANSMITTER mode:

```
#include <explorer_lib.h>
{
    long mode, models[XL_NUM_MODEL_TYPES_ENUM];
    xl_model_id model_id = {NULL};
    long ierr[XL_NUM_ERR_MODEL_INIT], status;

    mode = XL_MODEL_CONFIG;
    ...
    models[XL_MODEL_TYPE_LIGHT_PROPAGATION] = XL_MODEL_LIGHT_PROPAGATION_TRANSMITTER;

    status = xl_model_init (&mode, models,
                           &model_id,
                           ierr)
}
```

2) for RECEIVER mode:

```
#include <explorer_lib.h>
{
    long mode, models[XL_NUM_MODEL_TYPES_ENUM];
    xl_model_id model_id = {NULL};
```

```
long ierr[XL_NUM_ERR_MODEL_INIT], status;  
  
mode = XL_MODEL_CONFIG;  
...  
models[XL_MODEL_TYPE_LIGHT_PROPAGATION] = XL_MODEL_LIGHT_PROPAGATION_RECEIVER;  
  
status = xl_model_init (&mode, models,  
                        &model_id,  
                        ierr)  
}
```

## 5 LIBRARY INSTALLATION

For a detailed description of the installation of any CFI library, please refer to [GEN\_SUM].



## 6 LIBRARY USAGE

The EO\_POINTING software library has the following dependencies:

- Other EO\_CFI libraries:
  - EO\_FILE\_HANDLING (See [F\_H\_SUM]).
  - EO\_DATA\_HANDLING (See [D\_H\_SUM]).
  - EO\_LIB (See [LIB\_SUM]).
- Third party libraries:
  - POSIX thread library: libpthread.so (Note: this library is normally pre-installed in Linux and MacOS platforms. For Windows platforms, pthread.lib is included in the distribution package, with license LGPL);
  - GEOTIFF, TIFF, PROJ, LIBXML2 libraries (these libraries are included in the distribution package. Their usage terms and conditions are available in the file "TERMS\_AND\_CONDITIONS.TXT" which is part of the distribution package).

In order to improve run-time performance, some functions (e.g. `xp_target_list_extra_vector`, `xp_target_list_extra_main`, `xp_target_list_extra_aux`, `xp_target_list_extra_ef_target`, `xp_target_list_extra_target_to_sun`, `xp_target_list_extra_target_to_moon`, `xp_target_list_extra_specular_reflection`) perform their computations in multi-threading mode.

The multi-threading code of the Pointing functions uses the OpenMP API (see <http://en.wikipedia.org/wiki/OpenMP>).

OpenMP is not supported in the clang compiler, therefore such functions work in single-thread mode in MacOS.

The following is required to compile and link a Software application that uses the EO\_POINTING software library functions (it is assumed that the required EO\_CFI and third-part libraries are located in directory `cfi_lib_dir` and the required header files are located in `cfi_include`, see [GEN\_SUM] for installation procedures):

1) include the following header files in the source code:

- `explorer_pointing.h` (for a C application)

2) use the following compile and link options:

Linux platforms:

`-Icfi_include_dir -Lcfi_lib_dir -lexplorer_pointing`

`-lexplorer_lib -lexplorer_data_dandling -lexplorer_file_handling -lgeotiff -ltiff -lproj -lxml2 -lm -lc -lpthread -fopenmp`

MacOS platforms (openmp is not supported):

`-Icfi_include_dir -Lcfi_lib_dir -lexplorer_pointing`

-lexplorer\_lib - lexplorer\_data\_dandling -lexplorer\_file\_handling -lgeotiff -ltiff -lproj -lxml2 -lm -lc -lpthread

Windows platforms:

/I "cfi\_include\_dir" /libpath:"cfi\_lib\_dir" libexplorer\_pointing.lib

libexplorer\_lib.lib libexplorer\_data\_handling.lib libexplorer\_file\_handling.lib libgeotiff.lib libtiff.lib libproj.lib libxml2.lib pthread.lib Ws2\_32.lib /openmp

All functions described in this document have a name starting with the prefix xp\_

To avoid problems in linking a user application with the EO\_POINTING software library due to the existence of names multiple defined, the user application should avoid naming any global software item beginning with either the prefix XP\_ or xp\_.

It is possible to call the following CFI functions from a user application.

**Table 2: CFI functions included within EO\_POINTING library**

Function Name	Enumeration value	Long
Main CFI Functions		
xp_sat_nominal_att_init	XP_SAT_NOMINAL_ATT_INIT_ID	0
xp_sat_nominal_att_init_model	XP_SAT_NOMINAL_ATT_INIT_MODEL_ID	1
xp_sat_nominal_att_init_harmonic	XP_SAT_NOMINAL_ATT_INIT_HARMONIC_ID	2
xp_sat_nominal_att_init_file	XP_SAT_NOMINAL_ATT_INIT_FILE_ID	3
xp_sat_nominal_att_close	XP_SAT_NOMINAL_ATT_CLOSE_ID	4
xp_sat_att_angle_init	XP_SAT_ATT_ANGLE_INIT_ID	5
xp_sat_att_matrix_init	XP_SAT_ATT_MATRIX_INIT_ID	6
xp_sat_att_init_harmonic	XP_SAT_ATT_INIT_HARMONIC_ID	7
xp_sat_att_init_file	XP_SAT_ATT_INIT_FILE_ID	8
xp_sat_att_quat_plus_matrix_init	XP_SAT_ATT_QUAT_PLUS_MATRIX_INIT_ID	9
xp_sat_att_quat_plus_angle_init	XP_SAT_ATT_QUAT_PLUS_ANGLE_INIT_ID	10
xp_sat_att_close	XP_SAT_ATT_CLOSE_ID	11
xp_instr_att_angle_init	XP_INSTR_ATT_ANGLE_INIT_ID	12
xp_instr_att_matrix_init	XP_INSTR_ATT_MATRIX_INIT_ID	13
xp_instr_att_init_harmonic	XP_INSTR_ATT_INIT_HARMONIC_ID	14
xp_instr_att_init_file	XP_INSTR_ATT_INIT_FILE_ID	15
xp_instr_att_close	XP_INSTR_ATT_CLOSE_ID	16
xp_change_frame	XP_CHANGE_FRAME_ID	17
xp_attitude_init	XP_ATTITUDE_INIT_ID	18
xp_attitude_compute	XP_ATTITUDE_COMPUTE_ID	19

xp_attitude_user_set	XP_ATTITUDE_USER_SET_ID	20
xp_attitude_close	XP_ATTITUDE_CLOSE_ID	21
xp_set_az_el_definition	XP_SET_AZ_EL_DEFINITION_ID	22
xp_atmos_init	XP_ATMOS_INIT_ID	23
xp_atmos_close	XP_ATMOS_CLOSE_ID	24
xp_dem_init	XP_DEM_INIT_ID	25
xp_dem_compute	XP_DEM_COMPUTE_ID	26
xp_dem_close	XP_DEM_CLOSE_ID	27
xp_dem_get_info	XP_DEM_GET_INFO_ID	28
xp_dem_id_configure	XP_DEM_ID_CONFIGURE_ID	29
xp_target_inter	XP_TARGET_INTER_ID	30
xp_target_travel_time	XP_TARGET_TRAVEL_TIME_ID	31
xp_target_ground_range	XP_TARGET_GROUND_RANGE_ID	32
xp_target_incidence_angle	XP_TARGET_INCIDENCE_ANGLE_ID	33
xp_target_range	XP_TARGET_RANGE_ID	34
xp_target_range_rate	XP_TARGET_RANGE_RATE_ID	35
xp_target_tangent	XP_TARGET_TANGENT_ID	36
xp_target_altitude	XP_TARGET_ALTITUDE_ID	37
xp_target_star	XP_TARGET_STAR_ID	38
xp_target_station	XP_TARGET_STATION_ID	39
xp_target_drs	XP_TARGET_DRS_ID	40
xp_target_generic	XP_TARGET_GENERIC_ID	41
xp_target_reflected	XP_TARGET_REFLECTED_ID	42
xp_target_sc	XP_TARGET_SC_ID	43
xp_multi_target_inter	XP_MULTI_TARGET_INTER_ID	44
xp_multi_target_travel_time	XP_MULTI_TARGET_TRAVEL_TIME_ID	45
xp_target_list_inter	XP_TARGET_LIST_INTER_ID	46
xp_target_extra_vector	XP_TARGET_EXTRA_VECTOR_ID	47
xp_target_extra_main	XP_TARGET_EXTRA_MAIN_ID	48
xp_target_extra_aux	XP_TARGET_EXTRA_AUX_ID	49
xp_target_extra_ef_target	XP_TARGET_EXTRA_EF_TARGET_ID	50
xp_target_extra_target_to_sun	XP_TARGET_EXTRA_TARGET_TO_SUN_ID	51
xp_target_extra_target_to_moon	XP_TARGET_EXTRA_TARGET_TO_MOON_ID	52
xp_target_extra_specular_reflection	XP_TARGET_EXTRA_SPECULAR_REFLECTION_ID	53
xp_target_list_extra_vector	XP_TARGET_LIST_EXTRA_VECTOR_ID	54

xp_target_list_extra_main	XP_TARGET_LIST_EXTRA_MAIN_ID	55
xp_target_list_extra_aux	XP_TARGET_LIST_EXTRA_AUX_ID	56
xp_target_list_extra_ef_target	XP_TARGET_LIST_EXTRA_EF_TARGET_ID	57
xp_target_list_extra_specular_reflection	XP_TARGET_LIST_EXTRA_SPECULAR_REFLECTION_ID	58
xp_target_list_extra_target_to_moon	XP_TARGET_LIST_EXTRA_TARGET_TO_MOON_ID	59
xp_target_list_extra_target_to_sun	XP_TARGET_LIST_EXTRA_TARGET_TO_SUN_ID	60
xp_target_tangent_sun	XP_TARGET_TANGENT_SUN_ID	61
xp_target_tangent_moon	XP_TARGET_TANGENT_MOON_ID	62
xp_target_close	XP_TARGET_CLOSE_ID	63
xp_gen_dem_max_attitude	XP_GEN_DEM_MAX_ALTITUDE_ID	64
xp_gen_dem_altitude_from_ellipsoid	XP_GEN_DEM_ALTITUDE_FROM_ELLIPSOID_ID	65
xp_attitude_define	XP_ATTITUDE_DEFINE_ID	66
xp_attitude_transform	XP_ATTITUDE_TRANSFORM_ID	67
xp_run_init	XP_RUN_INIT_ID	68
<b>Error Handling Functions</b>		
xp_verbose	not applicable	
xp_silent		
xp_get_code		
xp_get_msg		
xp_print_msg		

Notes about the table:

- To transform the extended status flag returned by a CFI function to either a list of error codes or list of error messages, the enumeration value (or the corresponding long value) described in the table must be used
- The error handling functions have no enumerated values

Whenever available **it is strongly recommended to use enumeration values rather than integer values.**

## 6.1 Usage hints

The runtime performances of some of the CFI functions are improved to a large extent if they are called two consecutive times keeping constant some of their inputs.

Nevertheless, although the user may not need to call the CFI functions two consecutive times with the same inputs, there are internal functions that are actually called in those conditions, and thus improving the runtime performances of the former.

Thus, the runtime improvement is achieved with any sequence of calls to those CFI functions, not only with a sequence of calls to the same function.

In fact, the time, position, velocity, acceleration vectors, AOCS and mispointing angles do not need to keep exactly constant as long as the difference between two consecutive calls lays within the following thresholds:

- Time: 0.0864 microsec
- Position vector: 0.6e-3 m
- Velocity vector: 0.6e-6 m/s
- Acceleration vector: 0.6e-9 m/s<sup>2</sup>
- AOCS: 5e-9 deg
- Mispointing angles: 5e-9 deg
- Mispointing angles-rate: 5e-12 deg
- Mispointing angles-rate-rate: 5e-15 deg

Every CFI function has a different length of the Error Vector, used in the calling I/F examples of this SUM and defined at the beginning of the library header file. In order to provide the user with a single value that could be used as Error Vector length for every function, a generic value has been defined (XP\_ERR\_VECTOR\_MAX\_LENGTH) as the maximum of all the Error Vector lengths. This value can therefore be safely used for every call of functions of this library.

## 6.2 General Enumerations

The aim of the current section is to present the enumeration values that can be used rather than integer parameters for some of the input parameters of the EO\_POINTING routines, as shown in the table below. The enumerations presented in [GEN\_SUM], [F\_H\_SUM] and [LIB\_SUM] are also applicable.

**Table 3: Enumerations within EO\_POINTING library**

Input	Description	Enumeration value	Long
Time Initialization Mode	Initialization from file (data-driven)	XP_SEL_FILE	0
	Initialization within a time range	XP_SEL_TIME	1
	Initialization within a range of orbits	XP_SEL_ORBIT	2
	(not used in POINTING)	XP_SEL_DEFAULT	3
Earth Intersection Mode	No intersection with Earth geoid	XP_NO_INTER	0
	First intersection with Earth geoid	XP_INTER_1ST	1
	Second intersection with Earth geoid	XP_INTER_2ND	2
AOCS mode	Geocentric pointing	XP_AOCS_GPM	0
	Local normal pointing	XP_AOCS_LNP	1
	Yaw steering + local normal pointing	XP_AOCS_YSM	2
	Zero-Doppler YSM	XP_AOCS_ZDOPPLER	3
Satellite Nominal Attitude Model	Generic model	XP_MODEL_GENERIC	0
	Envisat model	XP_MODEL_ENVISAT	1

	Cryosat model	XP_MODEL_CRYOSAT	2
	ADM model	XP_MODEL_ADM	3
	SENTINEL 1 model	XP_MODEL_SENTINEL1	4
	SENTINEL 2 model	XP_MODEL_SENTINEL2	5
	Geostationary satellite model	XP_MODEL_GEO	6
Axis enumeration	X axis	XP_X_AXIS	0
	-X axis	XP_NEG_X_AXIS	1
	Y axis	XP_Y_AXIS	2
	-Y axis	XP_NEG_Y_AXIS	3
	Z axis	XP_Z_AXIS	4
	-Z axis	XP_NEG_Z_AXIS	5
Axis target	Sun pointing	XP_SUN_VEC	0
	Moon pointing	XP_MOON_VEC	1
	Earth pointing	XP_EARTH_VEC	2
	Nadir pointing	XP_NADIR_VEC	3
	Inertial velocity pointing	XP_INERTIAL_VEL_VEC	4
	Earth Fixed velocity pointing	XP_EF_VEL_VEC	5
	Inertial target pointing	XP_INERTIAL_TARGET_VEC	6
	Spacecraft Earth Fixed velocity	XP_EF_TARGET_VEC	7
	Earth Fixed target pointing	XP_SC_EF_VEL_VEC	8
	Orbit Pole	XP_ORBIT_POLE	9
	Corrected Satellite Position (ToD)	XP_INERTIAL_POS_VEC_CORRECTED	10
	Rotated Inertial velocity vector (ToD)	XP_INERTIAL_VEL_VEC_ROTATED	11
	North (EF)	XP_EF_NORTH	12
	South (EF)	XP_EF_SOUTH	13
Mode Flag	Flag for location calculus	XP_MODE_FLAG_LOCATION	0
	Flag for direction calculus	XP_MODE_FLAG_DIRECTION	1
Frame Flag	Selection of coordinate frame	XP_FRAME_FLAG_EXT	0
	Selection of attitude frame	XP_FRAME_FLAG_SAT	1
Angle Type	True Latitude (TOD)	XP_ANGLE_TYPE_TRUE_LAT_TOD	1
	Mean Latitude (TOD)	XP_ANGLE_TYPE_MEAN_LAT_TOD	2
	True latitude (EF)	XP_ANGLE_TYPE_TRUE_LAT_EF	3
Attitude Frame ID	No attitude frame defined	XP_NONE_ATTITUDE	-1
	Satellite Orbital Reference Frame	XP_SAT_ORBITAL_REF	0
	Satellite Nominal Attitude Frame	XP_SAT_NOMINAL_ATT	1
	Satellite Attitude Frame	XP_SAT_ATT	2

	Instrument(s) Attitude Frame(s)	XP_INSTR_ATT	3
Target Type	User Target	XP_USER_TARGET_TYPE	0
	Line of Sight Target	XP_LOS_TARGET_TYPE	1
	DEM Target	XP_DEM_TARGET_TYPE	2
Source Type	Star	XP_SOURCE_STAR	0
	Sun	XP_SOURCE_SUN	1
	Moon	XP_SOURCE_MOON	2
	Generic source	XP_SOURCE_GENERIC	3
Atmosphere Initialization Mode	No refraction mode	XP_NO_REF_INIT	0
		XP_STD_INIT	1
	User defined mode (n-z table, see section 10)	XP_USER_INIT	2
	Predefined LUT mode	XP_PRED_INIT	3
	Standard refraction mode (US76)	XP_STD_INIT_N	10
	User defined mode (n-z table, see section 10))	XP_USER_INIT_N	20
	Predefined LUT mode	XP_PRED_INIT_N	30
	User's predefined refraction LUTs	XP_US76_INIT	300
		XP_TROPIC_INIT	301
		XP_MID_SUM_INIT	302
		XP_MID_WIN_INIT	303
		XP_SUBAR_SUM_INIT	304
		XP_SUBAR_WIN_INIT	305
		XP_LUT_INIT	400
		XP_US76_INIT_N	3000
		XP_TROPIC_INIT_N	3001
		XP_MID_SUM_INIT_N	3002
XP_MID_WIN_INIT_N	3003		
XP_SUBAR_SUM_INIT_N	3004		
XP_SUBAR_WIN_INIT_N	3005		
XP_LUT_INIT_N	4000		
Attitude file type	Attitude generic file containing a list for angles or quaternions	XP_ATTITUDE_GENERIC_FILE_MODEL	0
	CryoSat Star Tracker File	XP_ATTITUDE_STAR_TRACKER_FILE_MODEL	1
	Frame based on satellite initialized with quaternions and a rotation to the satellite frame (rotation matrix or angles),	XP_ATTITUDE_QUATERNION_NO_FILE_MODEL	2

	not from a file.		
Target extra main results choice	Geocentric longitude and latitude. Geodetic altitude and latitude.	XP_TARG_EXTRA_MAIN_GEO	1
	Geocentric longitude and latitude rates. Geodetic altitude and latitude rates.	XP_TARG_EXTRA_MAIN_GEO_D	2
	Geocentric longitude and latitude rate rates. Geodetic altitude and latitude rate rates.	XP_TARG_EXTRA_MAIN_GEO_2D	4
	Target to satellite azimuth and elevation (Topocentric CS)	XP_TARG_EXTRA_MAIN_TARG2SAT_TOP	8
	Target to satellite azimuth and elevation rates (Topocentric CS)	XP_TARG_EXTRA_MAIN_TARG2SAT_TOP_D	16
	Target to satellite azimuth and elevation rate rates (Topocentric CS)	XP_TARG_EXTRA_MAIN_TARG2SAT_TOP_2D	32
	Satellite to target azimuth and elevation (Topocentric CS)	XP_TARG_EXTRA_MAIN_SAT2TARGET_TOP	64
	Satellite to target azimuth and elevation rates (Topocentric CS)	XP_TARG_EXTRA_MAIN_SAT2TARGET_TOP_D	128
	Satellite to target azimuth and elevation rate rates (Topocentric CS)	XP_TARG_EXTRA_MAIN_SAT2TARGET_TOP_2D	256
	Satellite to target azimuth and elevation (Attitude Frame)	XP_TARG_EXTRA_MAIN_SAT2TARGET_ATTITUDE	512
	Satellite to target azimuth and elevation rates (Attitude Frame)	XP_TARG_EXTRA_MAIN_SAT2TARGET_ATTITUDE_D	1024
	Satellite to target azimuth and elevation rate rates (Attitude Frame)	XP_TARG_EXTRA_MAIN_SAT2TARGET_ATTITUDE_2D	2048
	Target to satellite azimuth and elevation (Attitude Frame). Only meaningful for xp_target_sc	XP_TARG_EXTRA_MAIN_TARG2SAT_ATTITUDE	4096
	Target to satellite azimuth and elevation rates (Attitude Frame). Only meaningful for xp_target_sc	XP_TARG_EXTRA_MAIN_TARG2SAT_ATTITUDE_D	8192
	Target to satellite azimuth and elevation rate rates (Attitude Frame). Only meaningful for xp_target_sc	XP_TARG_EXTRA_MAIN_TARG2SAT_ATTITUDE_2D	16384
All parameters	XP_TARG_EXTRA_MAIN_ALL	32767	
Target extra aux results choice	Minimum distance from the nadir of the target to the ground track.	XP_TARG_EXTRA_AUX_DIST_NAD_TARG_GT	1
	Radius of curvature in the look direction at the nadir of the target.	XP_TARG_EXTRA_AUX_RAD_CUR	2
	Minimum distance rate from the nadir of the target to the ground track.	XP_TARG_EXTRA_AUX_DIST_NAD_TARG_GT_D	4



	Minimum distance rate rate from the nadir of the target to the ground track.	XP_TARG_EXTRA_AUX_DIST_NAD_TARG_GT_2D	8
	Radius of curvature rate in the look direction at the nadir of the target.	XP_TARG_EXTRA_AUX_RAD_CUR_D	16
	Radius of curvature rate rate in the look direction at the nadir of the target.	XP_TARG_EXTRA_AUX_RAD_CUR_2D	32
	Target Nadir Velocity relative to the Earth. (Topocentric CS)	XP_TARG_EXTRA_AUX_TARGET_NADIR_VEL	64
	Mean Local Solar Time at target.	XP_TARG_EXTRA_AUX_MLST	128
	True Local Solar Time at target.	XP_TARG_EXTRA_AUX_TLST	256
	Distance from the nadir of the target to the satellite nadir (Earth fixed CS)	XP_TARG_EXTRA_AUX_DIST_NAD_TARG_SAT_NAD	512
	Distance rate from the nadir of the target to the satellite nadir (Earth fixed CS)	XP_TARG_EXTRA_AUX_DIST_NAD_TARG_SAT_NAD_D	1024
	Distance rate rate from the nadir of the target to the satellite nadir (Earth fixed CS)	XP_TARG_EXTRA_AUX_DIST_NAD_TARG_SAT_NAD_2D	2048
	R.A. and declination at which the look direction from the satellite to the target point after crossing the atmosphere.	XP_TARG_EXTRA_AUX_LOOK_DIR	4096
	Distance from the SSP to the point on the ground track nearest to the nadir of the target. (Earth fixed CS)	XP_TARG_EXTRA_AUX_DIST_SSP_MIN_DIST_GT	8192
	Distance rate from the SSP to the point on the ground track nearest to the nadir of the target. (Earth fixed CS)	XP_TARG_EXTRA_AUX_DIST_SSP_MIN_DIST_GT_D	16384
	Distance rate rate from the SSP to the point on the ground track nearest to the nadir of the target. (Earth fixed CS)	XP_TARG_EXTRA_AUX_DIST_SSP_MIN_DIST_GT_2D	32768
	All parameters	XP_TARG_EXTRA_AUX_ALL	65535
Satellite Nominal Attitude Mode	Satellite Nominal Attitude initialised with AOCS mode	XP_SAT_NOMINAL_ATT_INIT_MODE	0
	Satellite Nominal Attitude initialised with Model	XP_SAT_NOMINAL_ATT_INIT_MODEL_MODE	1
	Satellite Nominal Attitude initialised with Harmonics	XP_SAT_NOMINAL_ATT_INIT_HARMONIC_MODE	2
	Satellite Nominal Attitude initialised with a File	XP_SAT_NOMINAL_ATT_INIT_FILE_MODE	3
Satellite Attitude Mode	Satellite Attitude initialised with angles	XP_SAT_ATT_ANGLE_INIT_MODE	0
	Satellite Attitude initialised with matrices	XP_SAT_ATT_MATRIX_INIT_MODE	1
	Satellite Attitude initialised with Har	XP_SAT_ATT_INIT_HARMONIC_MO	2

	monics	DE	
	Satellite Attitude initialised with a File	XP_SAT_ATT_INIT_FILE_MODE	3
Instrument Attitude Mode	Instrument Attitude initialised with angles	XP_INSTR_ATT_ANGLE_INIT_MODE	0
	Instrument Attitude initialised with matrices	XP_INSTR_ATT_MATRIX_INIT_MODE	1
	Instrument Attitude initialised with Harmonics	XP_INSTR_ATT_INIT_HARMONIC_MODE	2
	Instrument Attitude initialised with a File	XP_INSTR_ATT_INIT_FILE_MODE	3
	Attitude Mode	Attitude not calculated	XP_ATTITUDE_INIT_NO_DATA_MODE
	Attitude calculated	XP_ATTITUDE_COMPUTE_MODE	1
	Attitude defined by the user	XP_ATTITUDE_USER_SET_MODE	2
Target Mode	Target calculated with Inter (1st) function	XP_TARGET_INTER_1ST_MODE	0
	Target calculated with Inter (2nd) function	XP_TARGET_INTER_2ND_MODE	1
	Target calculated with Travel Time (1st) function	XP_TARGET_TRAVEL_TIME_1ST_MODE	2
	Target calculated with Travel Time (2nd) function	XP_TARGET_TRAVEL_TIME_2ND_MODE	3
	Target calculated with Ground Range function	XP_TARGET_GROUND_RANGE_MODE	4
	Target calculated with Incidence Angle function	XP_TARGET_INCIDENCE_ANGLE_MODE	5
	Target calculated with Range function	XP_TARGET_RANGE_MODE	6
	Target calculated with Range Rate function	XP_TARGET_RANGE_RATE_MODE	7
	Target calculated with Tangent function	XP_TARGET_TANGENT_MODE	8
	Target calculated with Altitude function	XP_TARGET_ALTITUDE_MODE	9
	Target calculated with Star function	XP_TARGET_STAR_MODE	10
	Target calculated with Tangent to Sun function	XP_TARGET_TANGENT_SUN_MODE	11
	Target calculated with Tangent to Moon function	XP_TARGET_TANGENT_MOON_MODE	12
	Target calculated with Station function	XP_TARGET_STATION_MODE	13
	Target calculated with DRS function	XP_TARGET_DRS_MODE	14
	Target calculated with Generic function	XP_TARGET_GENERIC_MODE	15
	Target calculated with S/C function	XP_TARGET_SC_MODE	16
Target calculated with Multi Inter (1st)	XP_MULTI_TARGET_INTER_1ST_M	17	

	function	ODE	
	Target calculated with Multi Inter (2nd) function	XP_MULTI_TARGET_INTER_2ND_MODE	18
	Target calculated with Multi Travel Time (1st) function	XP_MULTI_TARGET_TRAVEL_TIME_1ST_MODE	19
	Target calculated with Multi Travel Time (2nd) function	XP_MULTI_TARGET_TRAVEL_TIME_2ND_MODE	20
	Target calculated with Target reflected function	XP_TARGET_REFLECTED_MODE	21
	Target calculated with Target List Inter (1st) function	XP_TARGET_LIST_INTER_1ST_MODE	22
	Target calculated with Target List Inter (2nd) function	XP_TARGET_LIST_INTER_2ND_MODE	23
DEM configuration operations	XP_LOAD_TILE_SET	Load a set of tiles identified by a rectangular region	0
	XP_CLEAR_CACHE	Unload all the tiles in cache but do not free memory	1
	XP_FREE_CACHE	Unload all the tiles in cache but and free memory	2
	XP_SET_MAX_SIZE	Set new maximum size for cache	3
Azimuth elevation type	XP_AZ_EL_LIST	List of azimuth/elevation points	0
	XP_AZ_EL_STRIP	Strip of points with fixed azimuth	1
	XP_AZ_EL_GRID	Grid of azimuth/elevation points	2
Yaw flip attitude configuration	XP_AUTOMATIC_FLIP_MODE	The mode will be updated automatically to Winter or Summer mode	0
	XP_WINTER_MODE	Yaw flip Winter mode	1
	XP_SUMMER_MODE	Yaw flip Summer mode	2
Set of DEM selection	XP_ALL_DEM	All DEM tiles will be computed	0
	XP_DEM_SET	Only tiles in input range will be computed	1

## 6.3 Data Structures

The aim of the current section is to present the data structures that are used in the EO\_POINTING library. The structures are currently used for the CFI Identifiers accessor functions. The following table show the structures with their names and the data that contain:

**Table 4: EO\_POINTING structures**

Structure name	Data		
	Variable Name	C type	Description
xp_param_model_str	model_param	double [XP_NUM_MODEL_PARAM]	Model Parameters
	model_enum	long	Model type
xp_harmonic_data	num_terms	long [3]	Number of harmonics coefficient(pitch, roll and yaw)
	harmonic_type_pitch	long [XP_MAX_NUM_HARMONIC]	Harmonic type
	harmonic_type_roll	long [XP_MAX_NUM_HARMONIC]	Harmonic type
	harmonic_type_yaw	long [XP_MAX_NUM_HARMONIC]	Harmonic type
	harmonic_coef_pitch	double [XP_MAX_NUM_HARMONIC]	Harmonic coefficient
	harmonic_coef_roll	double [XP_MAX_NUM_HARMONIC]	Harmonic coefficient
	harmonic_coef_yaw	double [XP_MAX_NUM_HARMONIC]	Harmonic coefficient
xp_harmonic_model_str	angle_type	long	Angle type
	harmonic	xp_harmonic_data	Harmonic data
xp_att_data_rec	time_ref	long	Time reference
	time	double	Time for the quaternions/angles
	quaternion	double [4]	Quaternions
	angles	double [3]	Angles
	file_model	long	File model
xp_sat_nom_att_fil	val_time0	double	Validity start time

e_model_str	val_time1	double	Validity stop time
	data_type	long	0 = quaternions 1 = angles
	inertial_frame	long	initial reference frame: Inertial reference frame
	lines	long	number of records in the attitude lists
	max_gap	double	Maximum gap between consecutive data
	att_data	xp_att_data_rec*	array with the angle/quaternion records
xp_angle_model_str	pitch	double	Pitch
	roll	double	Roll
	yaw	double	Yaw
xp_matrix_model_str	att_matrix	double [3][3]	Attitude matrix
xp_star_tracker	quaternion[4]	float	Quaternions
	time	double	Quaternion time in TAI
	status	unsigned char	Quaternions status
xp_star_tracker_aux	star_tr_id	long	Star tracker Id (1,2 or 3)
	aberr_correction	long	Aberration correction flag: -1 = Aberration correction with transposed matrix 0 = No aberration 1 = Aberration correction
	str_att_rot	double [3][3]	Satellite attitude frame to star tracker rotation matrix
xp_sat_att_file_model_str	file_model	long	file model
	val_time0	double	Validity start time
	val_time1	double	Validity stop time
	data_type	long	0 = quaternions 1 = angles
	inertial_frame	long	initial reference frame
	lines	long	number of records in the attitude lists
	max_gap	double	Maximum time gap between angles or quaternions
	att_data	xp_att_data_rec*	Array with the angle/quaternion records
	aux_data	xp_star_tracker_aux	Data from the auxiliary file
	tm_data	xp_star_tracker*	Cryosat Star Tracker attitude data
	rot_to_sat	double**	Matrix with the rotation from the frame

			based on the satellite to the satellite frame.
xp_instr_att_file_model_str	file_model	long	File model
	val_time0	double	Validity start time
	val_time1	double	Validity stop time
	data_type	long	0 = quaternions 1 = angles
	inertial_frame	long	initial reference frame
	lines	long	number of records in the attitude lists
	max_gap	double	Maximum gap between quaternions/angles
	att_data	xp_att_data_rec*	array with the angle/quaternion records
xp_quat_plus_angle_model_str	inertial_frame	long	Inertial reference frame
	num_quat	long	Number of quaternions
	quat	xd_att_rec*	List of quaternions
	angles	double[3]	Rotation angles
xp_quat_plus_matrix_model_str	inertial_frame	long	Inertial reference frame
	num_quat	long	Number of quaternions
	quat	xd_att_rec*	List of quaternions
	rot_matrix	double[3][3]	Rotation matrix
xp_attitude_id_data	model	long	Attitude model
	time_ref	long	Time reference
	time	double	Time
	sat_vector	xl_cord	Satellite vector (EF)
	source_frame	long	Source reference frame (according to the extended reference frames enumeration in [LIB_SUM])
	target_frame	long	Target reference frame according to the Attitude Frame ID enumeration, defined in the current document (see Table 3 )
	sat_mat	xl_cs_tra	Attitude matrix. Provides transformation from source to target frame
	offset	double [3]	Instrument offset from initial reference frame
	attitude_EF	xl_cs_tra	Attitude matrix in EF: position and orientation of the instrument/satellite frame.
xp_atmos_id_data	atm_max_alt_std	double	Standard atmosphere geometric

			altitude
	atm_max_alt_user	double	User atmosphere geometric altitude
xp_dem_ace (deprecated)	dir	char [100]	Directory for the the DEM files
	res_X	double	Interval between points along X-axis
	res_Y	double	Interval between points along Y-axis
	res_unit	double	Conversion factor from x,y units to the res_X, res_Y units. for example if res_X is given in seconds and X in degrees => res_unit=3600
	X_num_points	long	Number of points along X-axis (columns)
	Y_num_points	long	Number of points along Y-axis (lines)
	x_range	double	Longitude of the x-axis for one file (grid)
	y_range	double	longitude of the y-axis for one file (grid)
	data_size	long	Size in bytes of the data stored in the files
	data_type	long	data type (int, long, float, double)
	north_alt	double[4]	Altitude at the North pole cell
	south_alt	double[4]	Altitude at the South pole cell
xp_dem_id_data	model	long	DEM model
	dem_data	xp_dem_ace *	DEM configuration data (deprecated)
	dem_user_params	xd_dem_user_params	DEM user parameters (see [D_H_SUM])
	dem_metadata	xd_dem_metadata	DEM metadata (see [D_H_SUM])
xp_dem_info	dem_model	long	DEM model (according to XD_Dem_model_enum in [D_H_SUM])
	data_source	long	Source flag. According to the dem_model, the value is one of the following enumerations (see [D_H_SUM]): <ul style="list-style-type: none"> <li>• DEM Data Source Types for GETASSE30 v1, v2 and v3</li> <li>• DEM Data Source Types for ACE2</li> <li>• DEM Data Source Types for GDEM v2</li> </ul>
xp_generic_data	time_ref	long	Time reference
	time	double	Time
	sat_vector	xl_cord	Satellite state vector (see [LIB_SUM])

	iray	long	Refraction model
	freq	double	Frequency
	deriv	long	Derivative flag according to derivatives enumeration in [LIB_SUM]
xp_target_data	tar_vector	xl_cord	target vector
	z_tan	xl_par_der	Tangent altitude
	range	xl_par_der	target range
	time	xl_par_der	time
	tar_sat_vector	xl_cord	target to satellite vector
	sat_tar_vector	xl_cord	satellite to target vector
xp_target_str	num_target	long	Number of targets
	target	xp_target_data *	target data
xp_target_id_data	generic_data	xp_generic_data	Target generic data
	earth_crossed	long	Flag to indicate if the Earth is crossed
	atm_crossed	long	Flag to indicate if the atmosphere is crossed
	user	xp_target_str	User target
	los	xp_target_str	LOS target
	earth	xp_target_str	Earth target
	exit_atm_vector	xl_cord	Pointing vector at exit from atmosphere
xp_latlon_area	lon_min	double	Minimum longitude of rectangular area
	lon_max	double	Maximum longitude of rectangular area
	lat_min	double	Minimum latitude of rectangular area
	lat_max	double	Maximum latitude of rectangular area
xp_dem_id_config	command	long	Operation to be executed (DEM configuration enum)
	max_cache_size	long	Maximum cache size (MegaBytes)
	area	xp_latlon_area	Rectangular area
xp_azimuth_elevation	azimuth	double	Azimuth [deg]
	elevation	double	Elevation [deg]
	azimuth_rate	double	Azimuth rate [deg/s]
	elevation_rate	double	Elevation rate [deg/s]
xp_azimuth_elevation_list	num_rec	long	Number of azimuth/elevation points
	az_el_list	xp_azimuth_elevation*	Array of azimuth/elevation points
xp_azimuth_elevation_strip	azimuth	double	Fixed azimuth of strip [deg]
	min_elevation	double	Lower elevation of strip points [deg]



	max_elevation	double	Maximum elevation of strip points [deg]
	step_elevation	double	Step between elevation points [deg]
xp_azimuth_elevation_grid	min_azimuth	double	Lower azimuth of grid points [deg]
	max_azimuth	double	Maximum azimuth of grid points [deg]
	step_azimuth	double	Step between azimuth points [deg]
	min_elevation	double	Lower elevation of grid points [deg]
	max_elevation	double	Maximum elevation of grid points [deg]
	step_elevation	double	Step between elevation points [deg]
xp_azimuth_elevation_input_union	azimuth_elevation_list	xp_azimuth_elevation_list	List of points
	azimuth_elevation_strip	xp_azimuth_elevation_strip	Strip of points
	azimuth_elevation_grid	xp_azimuth_elevation_grid	Grid of points
xp_instrument_data	type	long	Type of instrument data (see Azimuth elevation type enumeration)
	azimuth_elevation_input_union	xp_azimuth_elevation_input_union	Azimuth/elevation points
	signal_frequency	double	Signal frequency
xp_target_output	num_user_target	long	Number of user targets
	num_los_target	long*	Array of length num_user_targets with the number of LOS targets corresponding to every user target
xp_target_list_input_info	input_type	long	List/Grid/Strip (see XP_Az_el_type_enum)
	azimuth	double	Azimuth used as input to compute the target
	elevation	double	Elevation used as input to compute the target
	azimuth_idx	long	Azimuth index in azimuth/elevation grid
	elevation_idx	long	Elevation index in azimuth/elevation grid
xp_target_input_info_union	target_list_input_info	xp_target_list_input_info	Target input information union
xp_target_input_info	target_function	long	It defines the function used to compute the target
	target_input_info_union	xp_target_input_info_union	Target input information

xp_target_extra_vector_results	status	long	Target computation status
	target_input_info	xp_target_input_info	Input information used to compute the target
	vector_results	double[]	Results
	vector_results_rate	double[]	Results rate
xp_target_extra_main_results	status	long	Target computation status
	target_input_info	xp_target_input_info	Input information used to compute the target
	main_results	double[]	Results
	main_results_rate	double[]	Results rate
xp_target_extra_aux_results	status	long	Target computation status
	target_input_info	xp_target_input_info	Input information used to compute the target
	aux_results	double[]	Results
	aux_results_rate	double[]	Results rate
xp_target_extra_ef_target_results	status	long	Target computation status
	target_input_info	xp_target_input_info	Input information used to compute the target
	ef_target_results	double[]	Results
	ef_target_results_rate	double[]	Results rate
xp_target_extra_vector_results_list	num_rec	long	Number of targets computed
	extra_vector_results	xp_target_extra_vector_results*	Array with results for every target
	vector_results_rate	double[]	Results rate
	vector_results_rate_rate	double[]	Results rate rate
xp_target_extra_main_results_list	num_rec	long	Number of targets computed
	extra_main_results	xp_target_extra_main_results*	Array with results for every target
	main_results_rate	double[]	Results rate
	main_results_rate_rate	double[]	Results rate rate
xp_target_extra_aux_results_list	num_rec	long	Number of targets computed
	extra_aux_results	xp_target_extra_aux_results*	Array with results for every target
	aux_results_rate	double[]	Results rate
	aux_results_rate_rate	double[]	Results rate rate
xp_target_extra_ef_target_results_list	num_rec	long	Number of targets computed
	extra_ef_target_results	xp_target_extra_ef_target_results*	Array with results for every target
	ef_target_results_rate	double[]	Results rate
	ef_target_results_rate_rate	double[]	Results rate rate
xp_target_extra_sp	status	long	Target computation status

ec_reflec_target_results	target_input_info	xp_target_input_info	Input information used to compute the target
	spec_reflec_results	double[]	Results
	spec_reflec_results_rate	double[]	Results rate
	spec_reflec_results_rate_rate	double[]	Results rate rate
xp_target_extra_spec_reflec_target_results_list	num_rec	long	Number of targets computed
	extra_spec_reflec_target_results	xp_target_extra_spec_reflec_target_results*	Array with results for every target
xp_target_extra_moon_target_results	status	long	Target computation status
	target_input_info	xp_target_input_info	Input information used to compute the target
	moon_results	double[]	Results
	moon_rate	double[]	Results rate
xp_target_extra_moon_target_results_list	num_rec	long	Number of targets computed
	extra_moon_target_results	xp_target_extra_moon_target_results*	Array with results for every target
xp_target_extra_sun_target_results	status	long	Target computation status
	target_input_info	xp_target_input_info	Input information used to compute the target
	sun_results	double[]	Results
	sun_rate	double[]	Results rate
xp_target_extra_sun_target_results_list	num_rec	long	Number of targets computed
	extra_sun_target_results	xp_target_extra_sun_target_results*	Array with results for every target
xp_gen_dem_alt_from_ellipsoid_inputs	set_type	long	DEM set selected for computation (see DEM set enum)
	lon_min	double	Minimum longitude of DEM set
	lon_max	double	Maximum longitude of DEM set
	lat_min	double	Minimum latitude of DEM set
	lat_max	double	Maximum latitude of DEM set
	verbose	long	If == 0, no log message will be printed. If > 0, a log message will be printed every "verbose" points processed in DEM.
xp_attitude_def	type	long	Attitude type. Possible values: XP_NONE_ATTITUDE: No attitude defined

			XP_SAT_NOMINAL_ATT: Satellite Nominal attitude target. XP_SAT_ATT: Satellite attitude target. XP_INSTR_ATT: Instrument attitude target.
	sat_nom_trans_id	xp_sat_nom_trans_id	Satellite Nominal attitude
	sat_trans_id	xp_sat_trans_id	Satellite attitude target
	instr_trans_id	xp_instr_trans_id	Instrument attitude target
xp_transform_cfg	ref_frame	long	New reference frame. See enumeration "Reference frame" in [D_H_SUM]
	time_id	xl_time_id	Time Id.
	model_id	xl_model_id	Model Id.

## 7 CFI FUNCTIONS DESCRIPTION

The following sections describe each CFI function.

The calling interfaces are described for C users.

Input and output parameters of each CFI function are described in tables, where C programming language syntax is used to specify:

- Parameter types (e.g. long, double)
- Array sizes of N elements (e.g. param[N])
- Array element M (e.g. [M])

## 7.1 xp\_sat\_nominal\_att\_init

### 7.1.1 Overview

The `xp_sat_nominal_att_init` CFI function initialises the AOCS mode for a given satellite. The initialised mode will be stored in the `sat_nom_trans_id` output structure.

### 7.1.2 Calling Interface

The calling interface of the `xp_sat_nominal_att_init` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long aocs_mode;
    xp_sat_nom_trans_id sat_nom_trans_id = {NULL};
    long ierr[XP_NUM_ERR_NOM_ATT_INIT_DEF], status;

    status = xp_sat_nominal_att_init(&aocs_mode,
                                    &sat_nom_trans_id, ierr);
}
```

The `XP_NUM_ERR_SAT_NOM_ATT_INIT` constant is defined in the file `explorer_pointing.h`.

### 7.1.3 Input Parameters

The `xp_sat_nominal_att_init` CFI function has the following input parameters:

*Table 5: Input parameters of `xp_sat_nominal_att_init` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>aocs_mode</code>	<code>long *</code>	-	AOCS Mode ID	-	Complete

It is possible to use enumeration values rather than integer values for some of the input arguments: AOCS Mode ID: `aocs_mode`. See current document, Table 3.

### 7.1.4 Output Parameters

The output parameters of the `xp_sat_nominal_att_init` CFI function are:

*Table 6: Output parameters of `xp_sat_nominal_att_init`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>sat_nom_trans_id</code>	<code>xp_sat_nom_trans_id*</code>	-	Structure that contains the Satellite nominal Transformation	-	-
<code>ierr</code>	<code>long</code>	-	Error vector	-	-

### 7.1.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_sat_nominal_att_init` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_sat_nominal_att_init` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

*Table 7: Error messages of `xp_sat_nominal_att_init` function*

Error type	Error message	Cause and impact	Error code	Error No
ERR	Memory allocation error	No calculation performed	XP_CFI_SAT_NOMINAL_ATT_INIT_MEMORY_ERR	0

## 7.2 xp\_sat\_nominal\_att\_init\_model

### 7.2.1 Overview

The `xp_sat_nominal_att_init_model` CFI function initialises the satellite nominal attitude model for a given satellite. The initialised model will be stored in the `sat_nom_trans_id` output structure.

### 7.2.2 Calling Interface

The calling interface of the `xp_sat_nominal_att_init_model` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long model_enum;
    double model_param[XP_NUM_MODEL_PARAM];
    xp_sat_nom_trans_id sat_nom_trans_id = {NULL};
    long ierr[XP_NUM_ERR_SAT_NOM_ATT_INIT_MODEL], status;

    status = xp_sat_nominal_att_init_model(&model_enum,
                                           model_param,
                                           &sat_nom_trans_id, ierr);
}
```

The `XP_NUM_ERR_SAT_NOM_ATT_INIT_MODEL` and `XP_NUM_MODEL_PARAM` constants are defined in the file `explorer_pointing.h`.



### 7.2.3 Input Parameters

The `xp_sat_nominal_att_init_model` CFI function has the following input parameters:

**Table 8: Input parameters of `xp_sat_nominal_att_init_model` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>model_enum</code>	long *	-	Sat Nom Attitude Model ID	-	Complete
<code>model_param</code>	double	-	Model dependant parameters	-	Complete

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Satellite Nominal Attitude Model ID: `model_enum`. See current document, Table 3.
- Model dependant parameters: `model_param`. See current document, Table 9.

**Table 9: Model parameters depending on the attitude model**

Attitude Model	Array Element	Description (Reference)	Unit (Format)
XP_MODEL_GENERIC	[0]	First Axis enumeration value	-
	[1]	First Target enumeration value	-
	[2]	First Vector[0]	- or deg
	[3]	First Vector[1]	- or deg
	[4]	First Vector[2]	- or deg
	[5]	Second Axis enumeration value	
	[6]	Second Target enumeration value	
	[7]	Second Vector[0]	- or deg
	[8]	Second Vector[1]	- or deg
XP_MODEL_ENVISAT	[9]	Second Vector[2]	- or deg
	[0]	AOCS Cx parameter [pitch]	deg
	[1]	AOCS Cy parameter [roll]	deg
XP_MODEL_CRYOSAT	[2]	AOCS Cz parameter [yaw]	deg
	[0]	Local Normal Z Coefficient	-
XP_MODEL_ADM	[0]	Scan Angle	deg
	[1]	Scan Limit	deg
	[2]	Velocity Offset	m/s
XP_MODEL_SENTINEL1	[0]	Local Normal Coefficient	-
	[1]	Earth's angular velocity vector	rad/s
	[2]	Antenna bore sight off nadir angle at reference altitude ( $\Theta_{ref}$ )	deg

	[3]	Reference altitude ( $H_{ref}$ )	km
	[4]	Roll steering sensitivity versus altitude ( $\alpha_{roll}$ )	deg/km
	[5]	$h_0$	m
	[6]	$h_1$	m
	[7]	$h_2$	m
	[8]	$h_3$	m
	[9]	$h_4$	m
	[10]	$\varphi_1$	rad
	[11]	$\varphi_2$	rad
	[12]	$\varphi_3$	rad
	[13]	$\varphi_4$	rad
XP_MODEL_SENTINEL2	[0]	Earth's angular velocity vector	rad/s
XP_MODEL_GEO	[0]	Flag (enumeration values can be used): XP_AUTOMATIC_FLIP_MODE = enable the automatic Yaw Flip XP_WINTER_MODE = Winter XP_SUMMER_MODE = Summer	-

### 7.2.3.1 Generic Model description

The generic model builds the reference frames from the specified direction vectors.

The model parameters are:

- **first\_axis**: It can be any of {XP\_X\_AXIS, XP\_NEG\_X\_AXIS, XP\_Y\_AXIS, XP\_NEG\_Y\_AXIS, XP\_Z\_AXIS, XP\_NEG\_Z\_AXIS}
- **first\_target**: It can be any of {XP\_SUN\_VEC, XP\_MOON\_VEC, XP\_EARTH\_VEC, XP\_NADIR\_VEC, XP\_INERTIAL\_VEL\_VEC, XP\_EF\_VEL\_VEC, XP\_INERTIAL\_TARGET\_VEC, XP\_EF\_TARGET\_VEC, XP\_SC\_EF\_VEL\_VEC, XP\_ORBIT\_POLE, XP\_INERTIAL\_POS\_VEC\_CORRECTED, XP\_INERTIAL\_VEL\_VEC\_ROTATED, XP\_EF\_NORTH, XP\_EF\_SOUTH}
- **first\_vector[3]**: contains either:
  - dummies
  - [long, lat, alt] if first target = XP\_EF\_TARGET\_VEC
  - [ra, decl, parallax] if first target = XP\_INERTIAL\_TARGET\_VEC
  - correction coefficients if first target = XP\_INERTIAL\_POS\_VEC\_CORRECTED
  - rotation vector if first target = XP\_INERTIAL\_VEL\_VEC\_ROTATED
- **second\_axis**: It can be any of {XP\_X\_AXIS, XP\_NEG\_X\_AXIS, XP\_Y\_AXIS, XP\_NEG\_Y\_AXIS, XP\_Z\_AXIS, XP\_NEG\_Z\_AXIS}
- **second\_target**: It can be any of {XP\_SUN\_VEC, XP\_MOON\_VEC, XP\_EARTH\_VEC, XP\_NADIR\_VEC, XP\_INERTIAL\_VEL\_VEC, XP\_EF\_VEL\_VEC}

XP\_INERTIAL\_TARGET\_VEC, XP\_EF\_TARGET\_VEC, XP\_SC\_EF\_VEL\_VEC,  
XP\_ORBIT\_POLE, XP\_INERTIAL\_POS\_VEC\_CORRECTED,  
XP\_INERTIAL\_VEL\_VEC\_ROTATED, XP\_EF\_NORTH, XP\_EF\_SOUTH}

- second\_vector[3]: contains either:
  - dummies
  - [long, lat, alt] if second target= XP\_EF\_TARGET\_VEC
  - [ra, decl, parallax] if fsecond target=XP\_INERTIAL\_TARGET\_VEC
  - correction coefficients if second target=XP\_INERTIAL\_POS\_VEC\_CORRECTED
  - rotation vector if second target = XP\_INERTIAL\_VEL\_VEC\_ROTATED

It is necessary to define a convention for each target type (e.g, always from Satellite to XXX):

- XP\_SUN\_VEC: Unit direction vector from Satellite to Sun
- XP\_MOON\_VEC: Unit direction vector from Satellite to Moon
- XP\_EARTH\_VEC: Unit direction vector from Satellite to Earth centre (opposite to Satellite Position Vector)
- XP\_NADIR\_VEC: Unit direction vector from Satellite to Nadir point
- XP\_INERTIAL\_VEL\_VEC: Inertial Velocity vector (in TOD)
- XP\_EF\_VEL\_VEC: Earth Fixed Velocity vector
- XP\_INERTIAL\_TARGET\_VEC: Unit direction vector from Satellite to a target defined by a given [ra, decl, parallax]. The annual parallax is used in case we are pointing to a close object (for instance, the Moon), in order to get the distance. For stars, parallax=0 shall be used, meaning infinite distance. Units: degrees
- XP\_EF\_TARGET\_VEC: Unit direction vector from Satellite to a target defined by a given [long, lat, alt]
- XP\_SC\_EF\_VEL\_VEC: Satellite Earth Fixed Velocity vector
- XP\_ORBIT\_POLE: Unit direction vector normal to the orbital plane (computed as the cross product of the Satellite Position vector and its Velocity vector)
- XP\_INERTIAL\_POS\_VEC\_CORRECTED: Unit Satellite position vector in ToD corrected by coefficients (e.g to approximate the local normal direction)
- XP\_INERTIAL\_VEL\_VEC\_ROTATED: Inertial Velocity vector in ToD rotated (e.g correcting for the Earth rotation)
- XP\_EF\_NORTH: Unit direction vector pointing North (in Earth Fixed)
- XP\_EF\_SOUTH: Unit direction vector pointing South (in Earth Fixed)

With these parameters, the calculation is done as follows:

- Compute the unit direction vector specified by first\_target
  - Assign the calculated first target vector to the first axis vector
- Compute the unit direction vector specified by second\_target
  - Cross-product of the first axis vector and the second target vector
  - Assign the resulting vector to the second axis vector
  - Complete the right-handed frame

The following are some examples:

***Sun-Fixed Reference Frame***

- model\_param = {XP\_X\_AXIS, XP\_SUN\_VEC, 0.0, 0.0, 0.0, XP\_Z\_AXIS, XP\_EARTH\_VEC, 0.0, 0.0, 0.0}

Then:

- X-axis = Unit vector from Satellite to Sun (Sun Vector)
- Z-axis = Unit cross product: X-axis x (Unit vector from Satellite to Earth (Earth Vector))
- Y-axis = Z-axis x X-axis (completing the right-handed frame)

***Yaw Steering Mode***

- model\_param={XP\_NEG\_Z\_AXIS, XP\_NADIR\_VEC, 0.0, 0.0, 0.0, XP\_X\_AXIS, XP\_SC\_EF\_VEL\_VEC, 0.0, 0.0, 0.0}

Then:

- Z-axis = -(Unit vector from Satellite to Nadir (Nadir Vector))
- X-axis = Unit cross product: Z-axis x (Satellite Earth-Fixed Velocity Vector)
- Y-axis = Z-axis x X-axis (completing the right-handed frame)

**7.2.3.2 Sentinel-1 Model parameters description**

The parameters for the Sentinel-1 attitude model corresponds to the roll steering law:

$$\theta_{\text{offNadir}} = \theta_{\text{ref}} - \alpha_{\text{roll}} (H - H_{\text{ref}})$$

where the actual altitude of the satellite is approximated by the harmonic function:

$$H(t) = h_0 + \sum_{n=1}^N h_n \cdot \sin(n \cdot \omega_{\text{orb}} \cdot (t - t_{\text{ANX}}) + \phi_n)$$

The first fourth terms of the series are considered.

Consult [MSC] for more information.

**7.2.3.3 Sentinel-2 Model description**

Sentinel 2 model is implemented as generic model with the following definitions:

- First axis: XP\_NEG\_Z\_AXIS; first target = XP\_EARTH\_VEC.
- Second axis: XP\_X\_AXIS; second target = XP\_INERTIAL\_VEL\_VEC\_ROTATED

**7.2.3.4 Yaw flip attitude Model description**

Yaw Flip model is implemented as generic model with the following definitions:

1. For WINTER mode:

- First axis: XP\_NEG\_Z\_AXIS; first target = XP\_NADIR\_VEC.
- Second axis: XP\_X\_AXIS; second target = XP\_EF\_SOUTH

2. For SUMMER mode:

- First axis: XP\_NEG\_Z\_AXIS; first target = XP\_NADIR\_VEC.
- Second axis: XP\_X\_AXIS; second target = XP\_EF\_NORTH

3. For AUTOMATIC Yaw Flip, the attitude is set to WINTER or SUMMER mode depending on the Sun position: if the Sun position is above the equatorial plane, SUMMER mode is selected; if the Sun position is below the equatorial plane, WINTER mode is selected.

## 7.2.4 Output Parameters

The output parameters of the `xp_nominal_att_init_model` CFI function are:

*Table 10: Output parameters of `xp_sat_nominal_att_init_model`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_nom_trans_id	xp_sat_nom_trans_id*	-	Structure that contains the Satellite nominal Transformation	-	-
ierr	long	-	Error vector	-	-

## 7.2.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_sat_nominal_att_init_model` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_sat_nominal_att_init_model` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

*Table 11: Error messages of `xp_sat_nominal_att_init_model` function*

Error type	Error message	Cause and impact	Error code	Error No
ERR	Memory allocation error	No calculation performed	XP_CFI_SAT_NOMINAL_ATT_INIT_MODEL_MEMORY_ERR	0

## 7.3 xp\_sat\_nominal\_att\_init\_harmonic

### 7.3.1 Overview

The `xp_sat_nominal_init_harmonic` CFI function initialises the satellite orbital to satellite nominal attitude mispointing angles (i.e. roll, pitch, yaw) for a given satellite with a user-provided set of values. The initialised values will be stored in the `sat_nom_trans_id` output structure.

The mispointing angle (attitudeangle in the formula) will be calculated by functions using such `sat_nominal_trans_id` (i.e. `xp_attitude_compute` or `xp_change_frame`) according to the following formula (the "angle" variable will be calculated as in `xl_position_on_orbit` (see [LIB\_SUM]), using as inputs:

- the input state vector in EF passed to such functions;
- the `angle_type` passed as input to `xp_sat_nominal_att_init_harmonic`.

### 7.3.2 Calling Interface

The calling interface of the `xp_sat_nominal_att_init_harmonic` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long angle_type, num_terms[3];
    long harmonic_type_pitch[XP_MAX_NUM_HARMONIC],
        harmonic_type_roll[XP_MAX_NUM_HARMONIC],
        harmonic_type_yaw[XP_MAX_NUM_HARMONIC];
    double harmonic_coef_pitch[XP_MAX_NUM_HARMONIC],
        harmonic_coef_roll[XP_MAX_NUM_HARMONIC],
        harmonic_coef_yaw[XP_MAX_NUM_HARMONIC];
    xp_sat_nom_trans_id sat_nom_trans_id = {NULL};
    long ierr[XP_NUM_ERR_SAT_NOM_ATT_INIT_HARMONIC], status;

    status = xp_sat_nominal_att_init_harmonic(&angle_type,
                                             num_terms,
                                             harmonic_type_pitch,
                                             harmonic_type_roll,
                                             harmonic_type_yaw,
                                             harmonic_coef_pitch,
                                             harmonic_coef_roll,
                                             harmonic_coef_yaw,
                                             &sat_nom_trans_id,
                                             ierr);
}
```

}

The `XP_NUM_ERR_SAT_NOM_ATT_INIT_HARMONIC` and `XP_MAX_NUM_HARMONIC` constants are defined in the file *explorer\_pointing.h*.

### 7.3.3 Input Parameters

The `xp_sat_nominal_att_init_harmonic` CFI function has the following input parameters:

*Table 12: Input parameters of `xp_sat_nominal_att_init_harmonic` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>angle_type</code>	<code>long *</code>	-	Type of angle	-	XP_ANGLE_TYPE_TRUE_LAT_TOD XP_ANGLE_TYPE_MEAN_LAT_TOD XP_ANGLE_TYPE_TRUE_LAT_EF
<code>num_terms[3]</code>	<code>long</code>	[0]	Number of elements used in vectors <code>harmonic_type_pitch</code> and <code>harmonic_coef_pitch</code>	-	$\geq 0$
		[1]	Number of elements used in vectors <code>harmonic_type_roll</code> and <code>harmonic_coef_roll</code>	-	$\geq 0$
		[2]	Number of elements used in vectors <code>harmonic_type_yaw</code> and <code>harmonic_coef_yaw</code>	-	$\geq 0$
<code>harmonic_type_pitch</code>	<code>long[XP_MAX_NUM_HARMONIC]</code>	all	Type of coefficients: =0 for the bias parameter <0 for the sinus coefficients (-n means that corresponds to the sinus coefficient of order n) >0 for the cosinus coefficients (+n means that corresponds to the cosinus coefficient of order n)	-	
<code>harmonic_type_roll</code>	<code>long[XP_MAX_NUM_HARMONIC]</code>	all	Type of coefficients: =0 for the bias parameter <0 for the sinus coefficients (-n means that corresponds to the sinus coefficient of order n) >0 for the cosinus coefficients (+n means that corresponds to the cosinus coefficient of order n)	-	-
<code>harmonic_type_yaw</code>	<code>long[XP_MAX_NUM_HARMONIC]</code>	all	Type of coefficients: =0 for the bias parameter <0 for the sinus coefficients (-n means that corresponds to the	-	-



			sinus coefficient of order n) >0 for the cosinus coefficients (+n means that corresponds to the cosinus coefficient of order n)		
harmonic_coef _pitch	dou ble[XP_MA X_NUM_HA RMONIC]	all	Bias, sinus and cosinus coefi cients for the pitch angle	deg	-
harmonic_coef _roll	dou ble[XP_MA X_NUM_HA RMONIC]	all	Bias, sinus and cosinus coefi cients for the roll angle	deg	-
harmonic_coef _yaw	dou ble[XP_MA X_NUM_HA RMONIC]	all	Bias, sinus and cosinus coefi cients for the yaw angle	deg	-

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Angle Type: See current document, Table 3.

### 7.3.4 Output Parameters

The output parameters of the `xp_sat_nominal_att_init_harmonic` CFI function are:

**Table 13: Output parameters of `xp_sat_nominal_att_init_harmonic`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_nom_trans_id	xp_sat_nom _trans_id*	-	Structure that contains the Satellite nominal Transformation	-	-
ierr	long	-	Error vector	-	-

### 7.3.5 Example

For the satellite ERS:

`pitch = -0.16725*cos(true_lat)*sin(true_lat)*2=-0.16725*sin(2*true_lat)`

`num_terms[0]=1`

`harmonic_type_pitch={-2} harmonic_coef_pitch={-0.16725}`

`roll = 0.05012*sin(true_lat)`

`num_terms[1]=1`

`harmonic_type_roll={-1} harmonic_coef_roll={0.05012}`

```
yaw= 3.9163*cos(true_lat)
num_terms[2]=1
harmonic_type_yaw={+1} harmonic_coef_yaw={3.9163}
```

### 7.3.6 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_sat_nominal_att_init_harmonic` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_sat_nominal_att_init_harmonic` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM])

**Table 14: Error messages of `xp_sat_nominal_att_init_harmonic` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Memory allocation error	No calculation performed	XP_CFI_SAT_NOMINAL_ATT_INIT_HARMONIC_MEMORY_ERROR	0

## 7.4 xp\_sat\_nominal\_att\_init\_file

### 7.4.1 Overview

The `xp_sat_nominal_att_init_file` CFI function initialises the satellite nominal attitude angles for a given satellite reading values from the attitude file(s). The validity time or orbital range for the attitude angles can be specified by the user. The initialised values will be stored in the `sat_nom_trans_id` output structure.

In order to read files, `xp_sat_nominal_att_init_file` function internally uses Data Handling functions. Please refer to [D\_H\_SUM], in particular sections 4.2 and 4.3, for further details.

### 7.4.2 Calling Interface

The calling interface of the `xp_sat_nominal_att_init_file` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    xl_time_id time_id = {NULL};
    long n_files, time_init_mode, time_ref;
    char **attitude_file;
    double time0, time1;
    double val_time0, val_time1;
    xp_sat_nom_trans_id sat_nom_trans_id = {NULL};
    long ierr[XP_NUM_ERR_SAT_NOM_ATT_INIT_FILE], status;

    status = xp_sat_nominal_att_init_file(&time_id, &n_files,
        attitude_file, &time_init_mode, &time_ref, &time0, &time1,
        &val_time0, &val_time1, &sat_nom_trans_id, ierr);
}
```

The `XP_NUM_ERR_SAT_NOM_ATT_INIT_FILE` constant is defined in the file `explorer_pointing.h`.

### 7.4.3 Input Parameters

The `xp_sat_nominal_att_init_file` CFI function has the following input parameters:

**Table 15: Input parameters of `xp_sat_nominal_att_init_file` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>time_id</code>	<code>xl_time_id*</code>	-	Structure that contains the time correlations.	-	-
<code>n_files</code>	<code>long *</code>	-	Number of reference data files	-	> 0
<code>attitude_file</code>	<code>char **</code>	-	Filenames of the reference data files. In case multiple files are used, the files should be time ordered. The supported Attitude File format is the Generic Attitude File as described in Error: Reference source not found.	-	-
<code>time_init_mode</code>	<code>long *</code>	-	Flag for selecting the time range of the initialization.	-	Select either: · <code>XP_SEL_TIME</code> · <code>XP_SEL_FILE</code>
<code>time_ref</code>	<code>long *</code>	-	Time reference ID	-	Complete
<code>time0</code>	<code>double*</code>	-	If: <code>time_init_mode=XP_SEL_TIME</code> S Start of the time range defined by <code>[time0,time1]</code>	Decimal days (Processing format)	<code>[-18262.0,36524.0]</code>
<code>time1</code>	<code>double*</code>	-	If: <code>time_init_mode=XP_SEL_TIME</code> End of the time range defined by <code>[time0,time1]</code>	Decimal days (Processing format)	<code>[-18262.0,36524.0]</code> > <code>time0</code>

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Time Reference ID: `time_ref`. See [GEN\_SUM].
- Time Init Mode ID: `time_init_mode`. See current document, Table 3.

## 7.4.4 Output Parameters

The output parameters of the `xp_sat_nominal_att_init_file` CFI function are:

**Table 16: Output parameters of `xp_sat_nominal_att_init_file`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>val_time0</code>	<code>double*</code>	-	Validity start time of the initialization	Decimal days (Processing format)	[-18262.0,36524.0]
<code>val_time1</code>	<code>double*</code>	-	Validity end time of the initialization	Decimal days (Processing format)	[-18262.0,36524.0]
<code>sat_nom_trans_id</code>	<code>xp_sat_nom_trans_id*</code>	-	Structure that contains the Satellite nominal Transformation	-	-
<code>ierr</code>	<code>long</code>	-	Error vector	-	-

## 7.4.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_sat_nominal_att_init_file` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_sat_nominal_att_init_file` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 17: Error messages of `xp_sat_nominal_att_init_file` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Memory allocation error	No calculation performed	XP_CFI_SAT_NOMINAL_ATT_INIT_FILE_MEMORY_ERR	0
ERR	Wrong input time reference	No calculation performed	XP_CFI_SAT_NOMINAL_ATT_INIT_FILE_WRONG_TIME_REF_ERR	1
ERR	Error opening attitude file: %s	No calculation performed	XP_CFI_SAT_NOMINAL_ATT_INIT_FILE_OPEN_FILES_ERR	2
ERR	Error reading generic attitude files	No calculation performed	XP_CFI_SAT_NOMINAL_ATT_INIT_FILE_READ_ATT_FI	3

			LES_ERR	
ERR	Could not perform a time transformation	No calculation performed	XP_CFI_SAT_NOMINAL_AT T_INIT_FILE_TIME_CONV_ERR	4

## 7.5 xp\_sat\_nominal\_att\_close

### 7.5.1 Overview

The `xp_sat_nominal_att_close` CFI function cleans up any memory allocation performed by the satellite nominal attitude initialization functions.

### 7.5.2 Calling Interface

The calling interface of the `xp_sat_nominal_att_close` CFI function is the following (input parameters are underlined>):

```
#include <explorer_pointing.h>
{
    xp_sat_nom_trans_id sat_nom_trans_id = {NULL};
    long ierr[XP_NUM_ERR_SAT_NOM_ATT_CLOSE], status;

    status = xp_sat_nominal_att_close(&sat_nom_trans_id, ierr);
}
```

The `XP_NUM_ERR_SAT_NOM_ATT_CLOSE` constant is defined in the file *explorer\_pointing.h*.

### 7.5.3 Input Parameters

The `xp_sat_nominal_att_close` CFI function has the following input parameters:

*Table 18: Input parameters of `xp_sat_nominal_att_close` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>sat_nom_trans_id</code>	<code>xp_sat_nom_trans_id*</code>	-	Structure that contains the Satellite Nom. Trans.	-	-

### 7.5.4 Output Parameters

The output parameters of the `xp_sat_nominal_att_close` CFI function are:

*Table 19: Output parameters of `xp_sat_nominal_att_close`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>ierr</code>	<code>long</code>	-	Error vector	-	-

### 7.5.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_sat_nominal_att_close` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_sat_nominal_att_close` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

*Table 20: Error messages of `xp_sat_nominal_att_close` function*

Error type	Error message	Cause and impact	Error code	Error No
ERR	Could not close the Id. as it is not initialized or it is being used	No calculation performed	XP_CFI_SAT_NOMINAL_ATT_CLOSE_WRONG_ID_ERR	0



## 7.6 xp\_sat\_nominal\_att\_get\_aocs

### 7.6.1 Overview

The `xp_sat_nominal_att_get_aocs` CFI function returns AOCS mode used for the satellite nominal attitude initialization.

### 7.6.2 Calling interface

The calling interface of the `xp_sat_nominal_att_get_aocs` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    xp_sat_nom_trans_id sat_nom_trans_id;
    long status, aocs_model;
    status = xp_sat_nominal_att_get_aocs (&sat_nom_trans_id,
                                         &aocs_model);
}
```

### 7.6.3 Input parameters

The `xp_sat_nominal_att_get_aocs` CFI function has the following input parameters:

*Table 21: Input parameters of xp\_sat\_nominal\_att\_get\_aocs function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_nom_trans_id	xp_sat_nom_trans_id *	-	Satellite nominal transformation ID.	-	-

### 7.6.4 Output parameters

The output parameters of the `xp_sat_nominal_att_get_aocs` CFI function are:

*Table 22: Output parameters of xp\_sat\_nominal\_att\_get\_aocs function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xp_sat_nominal_att_get_aocs	long	-	Status flag	-	-
aocs_model	long	-	AOCS model	-	-

### **7.6.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The `sat_nom_trans_id` was not initialised.
- The `sat_nom_trans_id` initialization does not allow the use of this function.

## 7.7 xp\_sat\_nominal\_att\_set\_aocs

### 7.7.1 Overview

The `xp_sat_nominal_att_set_aocs` CFI function changes the AOCS mode used for the satellite nominal attitude initialization.

### 7.7.2 Calling interface

The calling interface of the `xp_sat_nominal_att_set_aocs` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    xp_sat_nom_trans_id sat_nom_trans_id;
    long status, aocs_model;
    status = xp_sat_nominal_att_set_aocs (&sat_nom_trans_id,
                                         &aocs_model);
}
```

### 7.7.3 Input parameters

The `xp_sat_nominal_att_set_aocs` CFI function has the following input parameters:

*Table 23: Input parameters of xp\_sat\_nominal\_att\_set\_aocs function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_nom_trans_id	xp_sat_nom_trans_id *	-	Satellite nominal transformation ID (input / output parameter)	-	-
aocs_model	long	-	AOCS model	-	-

### 7.7.4 Output parameters

The output parameters of the `xp_sat_nominal_att_set_aocs` CFI function are:

*Table 24: Output parameters of xp\_sat\_nominal\_att\_set\_aocs function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xp_sat_nominal_att_set_aocs	long	-	Status flag	-	-

sat_nom_trans_id	xp_sat_nom_trans_id *	-	Satellite nominal transformation ID (input / output parameter)	-	-
------------------	-----------------------	---	--	---	---

### **7.7.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The sat\_nom\_trans\_id was not initialised.
- The sat\_nom\_trans\_id initialization does not allow the use of this function.

## 7.8 xp\_sat\_nominal\_att\_get\_param

### 7.8.1 Overview

The `xp_sat_nominal_att_get_param` CFI function returns parameters used for the satellite nominal attitude initialization.

### 7.8.2 Calling interface

The calling interface of the `xp_sat_nominal_att_get_param` CFI function is the following (input parameters are underlined>):

```
#include <explorer_lib.h>
{
    xp_sat_nom_trans_id sat_nom_trans_id;
    long status;
    xp_param_model_str data;
    status = xp_sat_nominal_att_get_param (&sat_nom_trans_id,
                                          &data);
}
```

### 7.8.3 Input parameters

The `xp_sat_nominal_att_get_param` CFI function has the following input parameters:

*Table 25: Input parameters of xp\_sat\_nominal\_att\_get\_param function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_nom_trans_id	xp_sat_nom_trans_id *	-	Satellite nominal transformation ID.	-	-

### 7.8.4 Output parameters

The output parameters of the `xp_sat_nominal_att_get_param` CFI function are:

*Table 26: Output parameters of xp\_sat\_nominal\_att\_get\_param function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xp_sat_nominal_att_get_param	long	-	Status flag	-	-
data	xp_param_mode	-	Attitude initialization	-	-

---

	I_str		data		
--	-------	--	------	--	--

### **7.8.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The sat\_nom\_trans\_id was not initialised.
- The sat\_nom\_trans\_id initialization does not allow the use of this function.

## 7.9 xp\_sat\_nominal\_att\_set\_param

### 7.9.1 Overview

The `xp_sat_nominal_att_set_param` CFI function changes the parameters used for the satellite nominal attitude initialization.

### 7.9.2 Calling interface

The calling interface of the `xp_sat_nominal_att_set_param` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    xp_sat_nom_trans_id sat_nom_trans_id;
    long status;
    xp_param_model_str data;
    status = xp_sat_nominal_att_set_param (&sat_nom_trans_id,
                                         &data);
}
```

### 7.9.3 Input parameters

The `xp_sat_nominal_att_set_param` CFI function has the following input parameters:

*Table 27: Input parameters of xp\_sat\_nominal\_att\_set\_param function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_nom_trans_id	xp_sat_nom_trans_id *	-	Satellite nominal transformation ID (input / output parameter)	-	-
data	xp_param_model_str	-	Attitude initialization data	-	-

### 7.9.4 Output parameters

The output parameters of the `xp_sat_nominal_att_set_param` CFI function are:

*Table 28: Output parameters of xp\_sat\_nominal\_att\_set\_param function*

C name	C type	Array	Description	Unit	Allowed Range
--------	--------	-------	-------------	------	---------------

		Element	(Reference)	(Format)	
xp_sat_nominal_att_set_param	long	-	Status flag	-	-
sat_nom_trans_id	xp_sat_nom_trans_id *	-	Satellite nominal transformation ID (input / output parameter)	-	-

### **7.9.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The sat\_nom\_trans\_id was not initialised.
- The sat\_nom\_trans\_id initialization does not allow the use of this function.



## 7.10 xp\_sat\_nominal\_att\_get\_harmonic

### 7.10.1 Overview

The `xp_sat_nominal_att_get_harmonic` CFI function returns harmonic data used for the satellite nominal attitude initialization.

### 7.10.2 Calling interface

The calling interface of the `xp_sat_nominal_att_get_harmonic` CFI function is the following (input parameters are underlined>):

```
#include <explorer_lib.h>
{
    xp_sat_nom_trans_id sat_nom_trans_id;
    long status;
    xp_harmonic_model_str data;
    status = xp_sat_nominal_att_get_harmonic (&sat_nom_trans_id,
                                             &data);
}
```

### 7.10.3 Input parameters

The `xp_sat_nominal_att_get_harmonic` CFI function has the following input parameters:

*Table 29: Input parameters of xp\_sat\_nominal\_att\_get\_harmonic function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_nom_trans_id	xp_sat_nom_trans_id *	-	Satellite nominal transformation ID.	-	-

### 7.10.4 Output parameters

The output parameters of the `xp_sat_nominal_att_get_harmonic` CFI function are:

*Table 30: Output parameters of xp\_sat\_nominal\_att\_get\_harmonic function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xp_sat_nominal_att_get_harmonic	long	-	Status flag	-	-
data	xp_harmonic_m	-	Attitude initialization	-	-

---

	odel_str		data		
--	----------	--	------	--	--

### **7.10.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The `sat_nom_trans_id` was not initialised.
- The `sat_nom_trans_id` initialization does not allow the use of this function.

## 7.11 xp\_sat\_nominal\_att\_set\_harmonic

### 7.11.1 Overview

The `xp_sat_nominal_att_set_harmonic` CFI function changes the harmonic data used for the satellite nominal attitude initialization.

### 7.11.2 Calling interface

The calling interface of the `xp_sat_nominal_att_set_harmonic` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    xp_sat_nom_trans_id sat_nom_trans_id;
    long status;
    xp_harmonic_model_str data;
    status = xp_sat_nominal_att_set_harmonic (&sat_nom_trans_id,
                                             &data);
}
```

### 7.11.3 Input parameters

The `xp_sat_nominal_att_set_harmonic` CFI function has the following input parameters:

*Table 31: Input parameters of xp\_sat\_nominal\_att\_set\_harmonic function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_nom_trans_id	xp_sat_nom_trans_id *	-	Satellite nominal transformation ID (input / output parameter)	-	-
data	xp_harmonic_model_str	-	Attitude initialization data	-	-

### 7.11.4 Output parameters

The output parameters of the `xp_sat_nominal_att_set_harmonic` CFI function are:

*Table 32: Output parameters of xp\_sat\_nominal\_att\_set\_harmonic function*

C name	C type	Array	Description	Unit	Allowed Range
--------	--------	-------	-------------	------	---------------

		Element	(Reference)	(Format)	
xp_sat_nominal_att_set_harmonic	long	-	Status flag	-	-
sat_nom_trans_id	xp_sat_nom_trans_id *	-	Satellite nominal transformation ID (input / output parameter)	-	-

### **7.11.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The sat\_nom\_trans\_id was not initialised.
- The sat\_nom\_trans\_id initialization does not allow the use of this function.

## 7.12 xp\_sat\_nominal\_att\_get\_file

### 7.12.1 Overview

The `xp_sat_nominal_att_get_file` CFI function returns initialization data from the satellite nominal attitude Id. when it was initialised with a file.

### 7.12.2 Calling interface

The calling interface of the `xp_sat_nominal_att_get_file` CFI function is the following (input parameters are underlined>):

```
#include <explorer_lib.h>
{
    xp_sat_nom_trans_id sat_nom_trans_id;
    long status;
    xp_file_model_str data;
    status = xp_sat_nominal_att_get_file (&sat_nom_trans_id,
                                         &data);
}
```

### 7.12.3 Input parameters

The `xp_sat_nominal_att_get_file` CFI function has the following input parameters:

*Table 33: Input parameters of xp\_sat\_nominal\_att\_get\_file function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_nom_trans_id	xp_sat_nom_trans_id *	-	Satellite nominal transformation ID.	-	-

### 7.12.4 Output parameters

The output parameters of the `xp_sat_nominal_att_get_file` CFI function are:

*Table 34: Output parameters of xp\_sat\_nominal\_att\_get\_file function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xp_sat_nominal_att_get_file	long	-	Status flag	-	-
data	xp_file_model_str	-	Attitude initialization	-	-

---

			data		
--	--	--	------	--	--

### **7.12.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The `sat_nom_trans_id` was not initialised.
- The `sat_nom_trans_id` initialization does not allow the use of this function.

## 7.13 xp\_sat\_nominal\_att\_set\_file

### 7.13.1 Overview

The `xp_sat_nominal_att_set_file` CFI function changes the initialization data for the satellite nominal attitude Id, when it was initialised with a file.

If quaternions are introduced, it is checked that they are normalized.

### 7.13.2 Calling interface

The calling interface of the `xp_sat_nominal_att_set_file` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    xp_sat_nom_trans_id sat_nom_trans_id;
    long status;
    xp_file_model_str data;
    status = xp_sat_nominal_att_set_file (&sat_nom_trans_id,
                                         &data);
}
```

### 7.13.3 Input parameters

The `xp_sat_nominal_att_set_file` CFI function has the following input parameters:

*Table 35: Input parameters of xp\_sat\_nominal\_att\_set\_file function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_nom_trans_id	xp_sat_nom_trans_id *	-	Satellite nominal transformation ID (input / output parameter)	-	-
data	xp_file_model_str	-	Attitude initialization data	-	-

### 7.13.4 Output parameters

The output parameters of the `xp_sat_nominal_att_set_file` CFI function are:

**Table 36: Output parameters of *xp\_sat\_nominal\_att\_set\_file* function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<i>xp_sat_nominal_att_set_file</i>	long	-	Status flag	-	-
<i>sat_nom_trans_id</i>	<i>xp_sat_nom_trans_id</i> *	-	Satellite nominal transformation ID (input / output parameter)	-	-

### **7.13.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The *sat\_nom\_trans\_id* was not initialised.
- The *sat\_nom\_trans\_id* initialization does not allow the use of this function.



## 7.14 xp\_sat\_att\_angle\_init

### 7.14.1 Overview

The `xp_sat_att_angle_init` CFI function initialises the satellite nominal attitude to satellite attitude mispointing angles for a given satellite with a user-provided set of values. The initialised values will be stored in the `sat_trans_id` output structure.

### 7.14.2 Calling Interface

The calling interface of the `xp_sat_att_angle_init` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    double ang[3];
    xp_sat_trans_id sat_trans_id = {NULL};
    long ierr[XP_NUM_ERR_MISP_ANGLE_INIT_DEF], status;

    status = xp_sat_att_angle_init(ang, &sat_trans_id, ierr);
}
```

The `XP_NUM_ERR_SAT_ATT_ANGLE_INIT` constant is defined in the file `explorer_pointing.h`.

### 7.14.3 Input Parameters

The `xp_sat_att_angle_init` CFI function has the following input parameters:

**Table 37: Input parameters of `xp_sat_att_angle_init` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
ang	double[3]	[0]	Pitch mispointing angle (Satellite Nominal Attitude Frame)	deg	If no better value, assume 0.0
		[1]	Roll mispointing angle (Satellite Nominal Attitude Frame)	deg	If no better value, assume 0.0
		[2]	Yaw mispointing angle (Satellite Nominal Attitude Frame)	deg	If no better value, assume 0.0

### 7.14.4 Output Parameters

The output parameters of the `xp_sat_att_angle_init` CFI function are:

**Table 38: Output parameters of `xp_sat_att_angle_init`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_trans_id	xp_sat_trans_id*	-	Structure that contains the Satellite Transformation	-	-
ierr	long	-	Error vector	-	-

### 7.14.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_sat_att_angle_init` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_sat_att_angle_init` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 39: Error messages of `xp_sat_att_angle_init` function**

Error	Error message	Cause and impact	Error code	Error
-------	---------------	------------------	------------	-------

type				No
ERR	Memory allocation error	No calculation performed	XP_CFI_SAT_ATT_ANGLE_IN IT_MEMORY_ERR	0

## 7.15 xp\_sat\_att\_matrix\_init

### 7.15.1 Overview

The `xp_sat_att_matrix_init` CFI function initializes misalignment matrix between the satellite nominal attitude frame and satellite attitude frame with a user-provided matrix. The initialized values will be stored in the `sat_trans_id` output structure. It is checked that the input matrix is orthonormal.

#### Note on matrix notation:

If XYZ are the axes of the original reference frame, and X'Y'Z' are the axes of the rotated frame, the rows of the rotation matrix are respectively X, Y and Z axes expressed in X'Y'Z' system.

In the C representation, `M[0][[]]`, `M[1][[]]`, `M[2][[]]` are respectively 1st, and and 3rd row of a rotation matrix M.

The rotation matrix M satisfies the following equivalence:

$$\mathbf{V} = \mathbf{M} * \mathbf{V}'$$

where  $\mathbf{V}'$  is a vector expressed in the X'Y'Z' reference system and  $\mathbf{V}$  is expressed in the XYZ reference system.

### 7.15.2 Calling Interface

The calling interface of the `xp_sat_att_matrix_init` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    double att_matrix[3][3];
    xp_sat_trans_id sat_trans_id = {NULL};
    long ierr[XP_NUM_ERR_SAT_ATT_MATRIX_INIT], status;

    status = xp_sat_att_matrix_init(att_matrix,
                                   &sat_trans_id, ierr);
}
```

The `XP_NUM_ERR_SAT_ATT_MATRIX_INIT` constant is defined in the file `explorer_pointing.h`.

### 7.15.3 Input Parameters

The `xp_sat_att_matrix_init` CFI function has the following input parameters:

*Table 40: Input parameters of `xp_sat_att_matrix_init` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
att_matrix	double[3][3]	all	Mispointing Matrix	-	-

### 7.15.4 Output Parameters

The output parameters of the `xp_sat_att_matrix_init` CFI function are:

*Table 41: Output parameters of `xp_sat_att_matrix_init`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_trans_id	xp_sat_trans_id*	-	Structure that contains the Satellite Transformation	-	-
ierr	long	-	Error vector	-	-

### 7.15.5 Example

TBD

### 7.15.6 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_sat_att_matrix_init` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_sat_att_matrix_init` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 42: Error messages of xp\_sat\_att\_matrix\_init function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Memory allocation error	No calculation performed	XP_CFI_SAT_ATT_MATRIX_INIT_MEMORY_ERR	0
ERR	Matrix not orthonormal	No calculation performed The CFI performs a check, with a tolerance of $10^{-6}$ , that the product of the input matrix and its transposed is the unitary matrix	XP_CFI_SAT_ATT_MATRIX_INIT_ORTHONORMAL_ERR	1

## 7.16 xp\_sat\_att\_init\_harmonic

### 7.16.1 Overview

The `xp_sat_att_init_harmonic` CFI function initialises the satellite nominal orbital to satellite attitude mispointing angles (i.e. roll, pitch, yaw) for a given satellite with a user-provided set of values. The initialised values will be stored in the `sat_trans_id` output structure.

The mispointing angle (attitudeangle in the formula) will be calculated by functions using such `sat_trans_id` (i.e. `xp_attitude_compute` or `xp_change_frame`) according to the following formula (the "angle" variable will be calculated as in `xl_position_on_orbit` (see [LIB\_SUM]), using as inputs:

- the input state vector in EF passed to such functions;
- the `angle_type` passed as input to `xp_sat_att_init_harmonic`.

### 7.16.2 Calling Interface

The calling interface of the `xp_sat_att_init_harmonic` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long angle_type, num_terms[3];
    long harmonic_type_pitch[XP_MAX_NUM_HARMONIC],
        harmonic_type_roll[XP_MAX_NUM_HARMONIC],
        harmonic_type_yaw[XP_MAX_NUM_HARMONIC];
    double harmonic_coef_pitch[XP_MAX_NUM_HARMONIC],
        harmonic_coef_roll[XP_MAX_NUM_HARMONIC],
        harmonic_coef_yaw[XP_MAX_NUM_HARMONIC];
    xp_sat_trans_id sat_trans_id = {NULL};
    long ierr[XP_NUM_ERR_SAT_ATT_INIT_HARMONIC], status;

    status = xp_sat_att_init_harmonic(&angle_type, num_terms,
                                     harmonic_type_pitch,
                                     harmonic_type_roll,
                                     harmonic_type_yaw,
                                     harmonic_coef_pitch,
                                     harmonic_coef_roll,
                                     harmonic_coef_yaw,
                                     &sat_trans_id, ierr);
}
```

The `XP_NUM_ERR_SAT_ATT_INIT_HARMONIC` and `XP_MAX_NUM_HARMONIC` constants are defined in the file *explorer\_pointing.h*.



### 7.16.3 Input Parameters

The `xp_sat_att_init_harmonic` CFI function has the following input parameters:

**Table 43: Input parameters of `xp_sat_att_init_harmonic` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>angle_type</code>	<code>long *</code>	-	Type of angle	-	XP_ANGLE_TYPE_TRUE_LAT_TOD XP_ANGLE_TYPE_MEAN_LAT_TOD XP_ANGLE_TYPE_TRUE_LAT_EF
<code>num_terms[3]</code>	<code>long</code>	[0]	Number of elements used in vectors <code>harmonic_type_pitch</code> and <code>harmonic_coef_pitch</code>	-	$\geq 0$
		[1]	Number of elements used in vectors <code>harmonic_type_roll</code> and <code>harmonic_coef_roll</code>	-	$\geq 0$
		[2]	Number of elements used in vectors <code>harmonic_type_yaw</code> and <code>harmonic_coef_yaw</code>	-	$\geq 0$
<code>harmonic_type_pitch</code>	<code>long[XP_MAX_NUM_HARMONIC]</code>	all	Type of coefficients: =0 for the bias parameter <0 for the sinus coefficients (-n means that corresponds to the sinus coefficient of order n) >0 for the cosinus coefficients (+n means that corresponds to the cosinus coefficient of order n)	-	
<code>harmonic_type_roll</code>	<code>long[XP_MAX_NUM_HARMONIC]</code>	all	Type of coefficients: =0 for the bias parameter <0 for the sinus coefficients (-n means that corresponds to the sinus coefficient of order n) >0 for the cosinus coefficients (+n means that corresponds to the cosinus coefficient of order n)	-	-
<code>harmonic_type_yaw</code>	<code>long[XP_MAX_NUM_HARMONIC]</code>	all	Type of coefficients: =0 for the bias parameter <0 for the sinus coefficients (-n means that corresponds to the	-	-

			sinus coefficient of order n) >0 for the cosinus coefficients (+n means that corresponds to the cosinus coefficient of order n)		
harmonic_coef _pitch	dou ble[XP_MA X_NUM_HA RMONIC]	all	Bias, sinus and cosinus coefi cients for the pitch angle	deg	
harmonic_coef _roll	dou ble[XP_MA X_NUM_HA RMONIC]	all	Bias, sinus and cosinus coefi cients for the roll angle	deg	
harmonic_coef _yaw	dou ble[XP_MA X_NUM_HA RMONIC]	all	Bias, sinus and cosinus coefi cients for the yaw angle	deg	

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Angle Type: See current document, Table 3.

### 7.16.4 Output Parameters

The output parameters of the `xp_sat_att_init_harmonic` CFI function are:

**Table 44: Output parameters of `xp_sat_att_init_harmonic`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_trans_id	xp_sat_trans_id*	-	Structure that contains the Satellite Transformation	-	-
ierr	long	-	Error vector	-	-

### 7.16.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_sat_att_init_harmonic` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_sat_att_init_harmonic` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

*Table 45: Error messages of xp\_sat\_att\_init\_harmonic function*

<b>Error type</b>	<b>Error message</b>	<b>Cause and impact</b>	<b>Error code</b>	<b>Error No</b>
ERR	Memory allocation error	No calculation performed	XP_CFI_SAT_ATT_INIT_HAR MONIC_MEMORY_ERR	0

## 7.17xp\_sat\_att\_init\_file

### 7.17.1 Overview

The `xp_sat_att_init_file` CFI function initialises the satellite attitude angles for a given satellite reading values from the attitude file(s). The validity time or orbital range for the attitude angles can be specified by the user. The initialised values will be stored in the `sat_trans_id` output structure. The quaternions that could be read from the file are checked to be normalized.

In order to read files, `xp_sat_att_init_file` function internally uses Data Handling functions. Please refer to [D\_H\_SUM], in particular sections 4.2 and 4.3, for further details.

### 7.17.2 Calling Interface

The calling interface of the `xp_sat_att_init_file` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    xl_time_id time_id = {NULL};
    long n_files, time_init_mode, time_ref;
    char **attitude_file *auxiliary_file;
    double time0, time1;
    double val_time0, val_time1;
    xp_sat_trans_id sat_trans_id = {NULL};
    long ierr[XP_NUM_ERR_SAT_ATT_INIT_FILE], status;

    status = xp_sat_att_init_file(&time_id, &n_files,
                                attitude_file, auxiliary_file,
                                time_init_mode, time_ref, time0, time1,
                                val_time0, val_time1, &sat_trans_id, ierr);
}
```

The `XP_NUM_ERR_SAT_ATT_INIT_FILE` constant is defined in the file *explorer\_pointing.h*.

### 7.17.3 Input Parameters

The `xp_sat_att_init_file` CFI function has the following input parameters:

**Table 46: Input parameters of `xp_sat_att_init_file` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>time_id</code>	<code>xl_time_id*</code>	-	Structure that contains the time correlations.	-	-
<code>n_files</code>	<code>long *</code>	-	Number of reference data files	-	> 0
<code>attitude_file</code>	<code>char **</code>	-	<p>Filenames of the reference data files. In case multiple files are used, the files should be time ordered.</p> <p>The supported Attitude File for mats are the Generic Attitude File (described in [D_H_SUM]Error: Reference source not found) and Star Tracker files.</p> <p>If multiple files are used, Generic Attitude Files and Star Tracker files cannot be given to the function as part of the same list.</p> <p>When using Star-Tracker files, the function assumes that all the input files belong to the same Star-Tracker. As a consequence of this assumption only the Star-Tracker identifier of the first file provided in the list is read. Note that the Star-Tracker identification number should be either 1, 2 or 3 (no internal check is performed)</p>	-	-
<code>auxiliary_file</code>	<code>char **</code>	-	Filename of an auxiliary file containing the Star-Tracker misalignment matrices	-	-
<code>time_init_mode</code>	<code>long *</code>	-	Flag for selecting the time range of the initialization.	-	Select either: · <code>XP_SEL_TIME</code> · <code>XP_SEL_FILE</code>
<code>time_ref</code>	<code>long *</code>	-	Time reference ID	-	Complete
<code>time0</code>	<code>double*</code>	-	If: <code>time_init_mode=XP_SEL_TIME</code> Start of the time range defined by [time0,time1]	Decimal days (Processing format)	[-18262.0,36524.0]
<code>time1</code>	<code>double*</code>	-	If: <code>time_init_mode=XP_SEL_TIME</code> End of the time range defined by	Decimal days	[-18262.0,36524.0] > time0

			[time0,time1]	(Processing format)	
--	--	--	---------------	---------------------	--

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Time Reference ID: time\_ref. See [GEN\_SUM].
- Time Init Mode ID: time\_init\_mode. See current document, Table 3.

### 7.17.4 Output Parameters

The output parameters of the `xp_sat_att_init_file` CFI function are:

**Table 47: Output parameters of `xp_sat_att_init_file`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
val_time0	double*	-	Validity start time of the initialization	Decimal days (Processing format)	[-18262.0,36524.0]
val_time1	double*	-	Validity end time of the initialization	Decimal days (Processing format)	[-18262.0,36524.0]
sat_trans_id	xp_sat_trans_id*	-	Structure that contains the Satellite Transformation	-	-
ierr	long	-	Error vector	-	-

### 7.17.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_sat_att_init_file` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_sat_att_init_file` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 48: Error messages of `xp_sat_att_init_file` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Memory allocation error	No calculation performed	XP_CFI_SAT_ATT_INIT_FILE_MEMORY_ERR	0
ERR	Error opening attitude file: %s	No calculation performed	XP_CFI_SAT_ATT_INIT_FILE_OPEN_FILES_ERR	1
ERR	Error reading input star	No calculation performed	XP_CFI_SAT_ATT_INIT_FILE_	2

	tracker files		READ_FILES_ERR	
ERR	Error reading generic attitude files	No calculation performed	XP_CFI_SAT_ATT_INIT_FILE_READ_ATT_FILES_ERR	3
ERR	No data has been read from the files	No calculation performed	XP_CFI_SAT_ATT_INIT_FILE_NO_READ_DATA_ERR	4
ERR	Error reading auxiliary file	No calculation performed	XP_CFI_SAT_ATT_INIT_FILE_READ_AUX_FILE_ERR	5
ERR	Wrong input time reference	No calculation performed	XP_CFI_SAT_ATT_INIT_FILE_WRONG_TIME_REF_ERR	6
ERR	Could not perform a time transformation	No calculation performed	XP_CFI_SAT_ATT_INIT_FILE_TIME_REF_ERR	7
ERR	Could not find word "SPH_DESCRIPTOR" in attitude file	No calculation performed	XP_CFI_SAT_ATT_INIT_FILE_READ_STR_ID_ERR	8
ERR	Quaternion is not normalized	No calculation performed	XP_CFI_SAT_ATT_INIT_FILE_QUAT_UNITARY_ERR	9

## 7.18 xp\_sat\_att\_quat\_plus\_matrix\_init

### 7.18.1 Overview

The `xp_sat_att_quat_plus_matrix_init` CFI function initialises the satellite attitude angles using the input quaternions, and stores the rotation matrix from the satellite-based reference frame defined by the quaternions to the satellite frame, that must be provided by the user. The initialised values will be stored in the `sat_trans_id` output structure. The input quaternions are checked to be normalized, and the input matrix is checked to be orthonormal.

#### Note on matrix notation:

If XYZ are the axes of the original reference frame, and X'Y'Z' are the axes of the rotated frame, the rows of the rotation matrix are respectively X, Y and Z axes expressed in X'Y'Z' system.

In the C representation, `M[0][[]]`, `M[1][[]]`, `M[2][[]]` are respectively 1st, and and 3rd row of a rotation matrix M.

The rotation matrix M satisfies the following equivalence:

$$\mathbf{V} = \mathbf{M} * \mathbf{V}'$$

where  $\mathbf{V}'$  is a vector expressed in the X'Y'Z' reference system and  $\mathbf{V}$  is expressed in the XYZ reference system.

### 7.18.2 Calling Interface

The calling interface of the `xp_sat_att_quat_plus_matrix_init` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long inertial_frame;
    long num_rec;
    xd_att_rec *quaternions;
    double **matrix;
    xp_sat_trans_id sat_trans_id = {NULL};
    long ierr[XP_NUM_ERR_SAT_ATT_QUAT_PLUS_MATRIX_INIT], status;

    status = xp_sat_att_quat_plus_matrix_init( &inertial_frame,
        &num_rec, quaternions, matrix, sat_trans_id, ierr);
}
```

The `XP_NUM_ERR_SAT_ATT_QUAT_PLUS_MATRIX_INIT` constant is defined in the file `explorer_pointing.h`.



### 7.18.3 Input Parameters

The `xp_sat_att_init_file` CFI function has the following input parameters:

*Table 49: Input parameters of `xp_sat_att_quat_plus_matrix_init` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>inertial_frame</code>	<code>long*</code>	-	Inertial reference frame.	-	Defined in <code>XD-Cs_enum</code>
<code>num_rec</code>	<code>long *</code>	-	Number of quaternions	-	> 0
<code>quaternions</code>	<code>xd_att_rec *</code>	-	Quaternions that give the rotation from the inertial reference frame to the frame based on the satellite.	-	-
<code>matrix</code>	<code>double**</code>	-	Rotation matrix from the frame based on the satellite to the satellite frame.	-	-

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Inertial frame. See `[D_H_SUM]`.

### 7.18.4 Output Parameters

The output parameters of the `xp_sat_att_init_file` CFI function are:

*Table 50: Output parameters of `xp_sat_att_quat_plus_matrix_init`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>sat_trans_id</code>	<code>xp_sat_trans_id*</code>	-	Structure that contains the Satellite Transformation	-	-
<code>ierr</code>	<code>long</code>	-	Error vector	-	-

### 7.18.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_sat_att_quat_plus_matrix_init` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the `EO_POINTING` software library `xp_get_msg` (see `[GEN_SUM]`).

This table also indicates the type of message returned, i.e. either a warning (`WARN`) or an error (`ERR`), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_sat_att_quat_plus_matrix_init` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 51: Error messages of `xp_sat_att_quat_plus_matrix_init` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Memory allocation error	No calculation performed	XP_CFI_SAT_ATT_QUAT_PLUS_MATRIX_INIT_MEMORY_ERR	0
ERR	Quaternion is not normalized	No calculation performed	XP_CFI_SAT_ATT_QUAT_PLUS_MATRIX_INIT_QUAT_UNITARY_ERR	1
ERR	Matrix is not orthonormal	No calculation performed. The CFI performs a check, with a tolerance of $10^{-6}$ , that the product of the input matrix and its transposed is the unitary matrix.	XP_CFI_SAT_ATT_QUAT_PLUS_MATRIX_INIT_MATRIX_ORTHONORMAL_ERR	2

## 7.19 xp\_sat\_att\_quat\_plus\_angle\_init

### 7.19.1 Overview

The `xp_sat_att_quat_plus_angle_init` CFI function initialises the satellite attitude angles using the input quaternions, and stores the rotation matrix from the satellite-based reference frame defined by the quaternions to the satellite frame, calculated with the input angles. The initialised values will be stored in the `sat_trans_id` output structure. The input quaternions are checked to be normalized.

### 7.19.2 Calling Interface

The calling interface of the `xp_sat_att_quat_plus_angle_init` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long inertial_frame;
    long num_rec;
    xd_att_rec *quaternions;
    double angles[3];
    xp_sat_trans_id sat_trans_id = {NULL};
    long ierr[XP_NUM_ERR_SAT_ATT_QUAT_PLUS_ANGLE_INIT], status;

    status = xp_sat_att_quat_plus_angle_init( &inertial_frame,
                                             &num_rec, quaternions, angles, sat_trans_id, ierr);
}
```

The `XP_NUM_ERR_SAT_ATT_QUAT_PLUS_ANGLE_INIT` constant is defined in the file `explorer_pointing.h`.

### 7.19.3 Input Parameters

The `xp_sat_att_quat_plus_angle_init` CFI function has the following input parameters:

*Table 52: Input parameters of `xp_sat_att_quat_plus_matrix_init` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>inertial_frame</code>	<code>long*</code>	-	Inertial reference frame.	-	Defined in <code>XD-Cs_enum</code>
<code>num_rec</code>	<code>long *</code>	-	Number of quaternions	-	> 0
<code>quaternions</code>	<code>xd_att_rec *</code>	-	Quaternions that give the rotation from the inertial reference frame to the frame based on the satellite.	-	-
<code>angles</code>	<code>double[3]</code>	-	Angles that define the rotation from the frame based on the satellite to the satellite frame.	-	-

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Inertial frame. See `[D_H_SUM]`.

### 7.19.4 Output Parameters

The output parameters of the `xp_sat_att_quat_plus_angle_init` CFI function are:

*Table 53: Output parameters of `xp_sat_att_quat_plus_angle_init`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>sat_trans_id</code>	<code>xp_sat_trans_id*</code>	-	Structure that contains the Satellite Transformation	-	-
<code>ierr</code>	<code>long</code>	-	Error vector	-	-

### 7.19.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_sat_att_quat_plus_angle_init` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the `EO_POINTING` software library `xp_get_msg` (see `[GEN_SUM]`).

This table also indicates the type of message returned, i.e. either a warning (`WARN`) or an error (`ERR`), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_sat_att_quat_plus_angle_init` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 54: Error messages of `xp_sat_att_quat_plus_angle_init` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Memory allocation error	No calculation performed	XP_CFI_SAT_ATT_QUAT_PLUS_ANGLE_INIT_MEMORY_ERROR	0
ERR	Error calculating rotation matrix for eurler angles	No calculation performed	XP_CFI_SAT_ATT_QUAT_PLUS_ANGLE_EULER_TO_MATRIX_ERR	1
ERR	Quaternions are not normalized	No calculation performed The CFI performs a check, with a tolerance of $10^{-6}$ , that the product of the input matrix and its transposed is the unitary matrix.	XP_SAT_ATT_QUAT_PLUS_ANGLE_INIT_QUAT_UNITARY_ERR	2

## 7.20 xp\_sat\_att\_close

### 7.20.1 Overview

The `xp_sat_att_close` CFI function cleans up any memory allocation performed by the satellite attitude initialization functions.

### 7.20.2 Calling Interface

The calling interface of the `xp_sat_att_close` CFI function is the following (input parameters are underlined>):

```
#include <explorer_pointing.h>
{
    xp_sat_trans_id sat_trans_id = {NULL};
    long ierr[XP_NUM_ERR_SAT_ATT_CLOSE], status;

    status = xp_sat_att_close(&sat_trans_id, ierr);
}
```

The `XP_NUM_ERR_SAT_ATT_CLOSE` constant is defined in the file *explorer\_pointing.h*.

### 7.20.3 Input Parameters

The `xp_sat_att_close` CFI function has the following input parameters:

*Table 55: Input parameters of `xp_sat_att_close` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_trans_id	xp_sat_trans_id*	-	Structure that contains the Sat. Trans.	-	-

### 7.20.4 Output Parameters

The output parameters of the `xp_sat_att_close` CFI function are:

*Table 56: Output parameters of `xp_sat_att_close`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
ierr	long	-	Error vector	-	-

### 7.20.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_sat_att_close` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_sat_att_close` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

*Table 57: Error messages of `xp_sat_att_close` function*

Error type	Error message	Cause and impact	Error code	Error No
ERR	Could not close the Id. as it is not initialized or it is being used	No calculation performed	XP_CFI_SAT_ATT_CLOSE_WRONG_ID_ERR	0





## 7.21 xp\_sat\_att\_get\_angles

### 7.21.1 Overview

The `xp_sat_att_get_angles` CFI function returns angle data used for the satellite attitude initialization.

### 7.21.2 Calling interface

The calling interface of the `xp_sat_att_get_angles` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    xp_sat_trans_id sat_trans_id;
    long status;
    xp_angle_model_str data;
    status = xp_sat_att_get_angles (&sat_trans_id,
                                   &data);
}
```

### 7.21.3 Input parameters

The `xp_sat_att_get_angles` CFI function has the following input parameters:

*Table 58: Input parameters of xp\_sat\_att\_get\_angles function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_trans_id	xp_sat_trans_id *	-	Satellite transformation ID.	-	-

### 7.21.4 Output parameters

The output parameters of the `xp_sat_att_get_angles` CFI function are:

*Table 59: Output parameters of xp\_sat\_att\_get\_angles function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xp_sat_att_get_angles	long	-	Status flag	-	-
data	xp_angle_model_str	-	Attitude initialization data	-	-

### **7.21.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The `sat_trans_id` was not initialised.
- The `sat_trans_id` initialization does not allow the use of this function.

## 7.22 xp\_sat\_att\_set\_angles

### 7.22.1 Overview

The `xp_sat_att_set_angles` CFI function changes the harmonic data used for the satellite attitude initialization.

### 7.22.2 Calling interface

The calling interface of the `xp_sat_att_set_angles` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    xp_sat_trans_id sat_trans_id;
    long status;
    xp_angle_model_str data;
    status = xp_sat_att_set_angles (&sat_trans_id,
                                   &data);
}
```

### 7.22.3 Input parameters

The `xp_sat_att_set_angles` CFI function has the following input parameters:

**Table 60: Input parameters of `xp_sat_att_set_angles` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_trans_id	xp_sat_trans_id*	-	Satellite transformation ID (input / output parameter)	-	-
data	xp_angle_model_str	-	Attitude initialization data	-	-

### 7.22.4 Output parameters

The output parameters of the `xp_sat_att_set_angles` CFI function are:

**Table 61: Output parameters of `xp_sat_att_set_angles` function**

C name	C type	Array	Description	Unit	Allowed Range
--------	--------	-------	-------------	------	---------------

		Element	(Reference)	(Format)	
xp_sat_att_set_angles	long	-	Status flag	-	-
sat_trans_id	xp_sat_trans_id *	-	Satellite transformation ID (input / output parameter)	-	-

### **7.22.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The sat\_trans\_id was not initialised.
- The sat\_trans\_id initialization does not allow the use of this function.

## 7.23 xp\_sat\_att\_get\_matrix

### 7.23.1 Overview

The `xp_sat_att_get_matrix` CFI function returns the matrix data used for the satellite attitude initialization.

#### Note on matrix notation:

If XYZ are the axes of the original reference frame, and X'Y'Z' are the axes of the rotated frame, the rows of the rotation matrix are respectively X, Y and Z axes expressed in X'Y'Z' system.

In the C representation, `M[0][[]]`, `M[1][[]]`, `M[2][[]]` are respectively 1st, and and 3rd row of a rotation matrix M.

The rotation matrix M satisfies the following equivalence:

$$\mathbf{V} = \mathbf{M} * \mathbf{V}'$$

where  $\mathbf{V}'$  is a vector expressed in the X'Y'Z' reference system and  $\mathbf{V}$  is expressed in the XYZ reference system.

### 7.23.2 Calling interface

The calling interface of the `xp_sat_att_get_matrix` CFI function is the following (input parameters are underlined>):

```
#include <explorer_lib.h>
{
    xp_sat_trans_id sat_trans_id;
    long status;
    xp_matrix_model_str data;
    status = xp_sat_att_get_matrix (&sat_trans_id,
                                   &data);
}
```

### 7.23.3 Input parameters

The `xp_sat_att_get_matrix` CFI function has the following input parameters:

*Table 62: Input parameters of xp\_sat\_att\_get\_matrix function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_trans_id	xp_sat_trans_id *	-	Satellite transformation ID.	-	-

### 7.23.4 Output parameters

The output parameters of the `xp_sat_att_get_matrix` CFI function are:

**Table 63: Output parameters of `xp_sat_att_get_matrix` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>xp_sat_att_get_matrix</code>	long	-	Status flag	-	-
data	<code>xp_matrix_mode_l_str</code>	-	Attitude initialization data	-	-

### **7.23.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The `sat_trans_id` was not initialised.
- The `sat_trans_id` initialization does not allow the use of this function.

## 7.24 xp\_sat\_att\_set\_matrix

### 7.24.1 Overview

The `xp_sat_att_set_matrix` CFI function changes matrix data used for the satellite attitude initialization. It is checked that the input matrix is orthonormal.

#### Note on matrix notation:

If XYZ are the axes of the original reference frame, and X'Y'Z' are the axes of the rotated frame, the rows of the rotation matrix are respectively X, Y and Z axes expressed in X'Y'Z' system.

In the C representation, `M[0][[]]`, `M[1][[]]`, `M[2][[]]` are respectively 1st, and and 3rd row of a rotation matrix M.

The rotation matrix M satisfies the following equivalence:

$$\mathbf{V} = \mathbf{M} * \mathbf{V}'$$

where  $\mathbf{V}'$  is a vector expressed in the X'Y'Z' reference system and  $\mathbf{V}$  is expressed in the XYZ reference system.

### 7.24.2 Calling interface

The calling interface of the `xp_sat_att_set_matrix` CFI function is the following (input parameters are underlined>):

```
#include <explorer_lib.h>
{
    xp_sat_trans_id sat_trans_id;
    long status;
    xp_matrix_model_str data;
    status = xp_sat_att_set_matrix (&sat_trans_id,
                                   &data);
}
```

### 7.24.3 Input parameters

The `xp_sat_att_set_matrix` CFI function has the following input parameters:

**Table 64: Input parameters of xp\_sat\_att\_set\_matrix function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_trans_id	xp_sat_trans_id *	-	Satellite transformation ID (input / output parameter)	-	-
data	xp_angle_model_str	-	Attitude initialization data	-	-

### 7.24.4 Output parameters

The output parameters of the `xp_sat_att_set_matrix` CFI function are:

*Table 65: Output parameters of xp\_sat\_att\_set\_matrix function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>xp_sat_att_set_matrix</code>	long	-	Status flag	-	-
<code>sat_trans_id</code>	<code>xp_sat_trans_id</code> *	-	Satellite transformation ID (input / output parameter)	-	-

### 7.24.5 Warnings and errors

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The `sat_trans_id` was not initialised.
- The `sat_trans_id` initialization does not allow the use of this function.



## 7.25 xp\_sat\_att\_get\_harmonic

### 7.25.1 Overview

The `xp_sat_att_get_harmonic` CFI function returns harmonic data used for the satellite attitude initialization.

### 7.25.2 Calling interface

The calling interface of the `xp_sat_att_get_harmonic` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    xp_sat_trans_id sat_trans_id;
    long status;
    xp_harmonic_model_str data;
    status = xp_sat_att_get_harmonic (&sat_trans_id,
                                     &data);
}
```

### 7.25.3 Input parameters

The `xp_sat_att_get_harmonic` CFI function has the following input parameters:

*Table 66: Input parameters of xp\_sat\_att\_get\_harmonic function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_trans_id	xp_sat_trans_id*	-	Satellite transformation ID.	-	-

### 7.25.4 Output parameters

The output parameters of the `xp_sat_att_get_harmonic` CFI function are:

*Table 67: Output parameters of xp\_sat\_att\_get\_harmonic function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xp_sat_att_get_harmonic	long	-	Status flag	-	-
data	xp_harmonic_m	-	Attitude initialization	-	-

---

	odel_str		data		
--	----------	--	------	--	--

### **7.25.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The sat\_trans\_id was not initialised.
- The sat\_trans\_id initialization does not allow the use of this function.

## 7.26 xp\_sat\_att\_set\_harmonic

### 7.26.1 Overview

The `xp_sat_att_set_harmonic` CFI function changes the harmonic data used for the satellite attitude initialization.

### 7.26.2 Calling interface

The calling interface of the `xp_sat_att_set_harmonic` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    xp_sat_trans_id sat_trans_id;
    long status;
    xp_harmonic_model_str data;
    status = xp_sat_att_set_harmonic (&sat_trans_id,
                                     &data);
}
```

### 7.26.3 Input parameters

The `xp_sat_att_set_harmonic` CFI function has the following input parameters:

*Table 68: Input parameters of xp\_sat\_att\_set\_harmonic function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_trans_id	xp_sat_trans_id*	-	Satellite transformation ID (input / output parameter)	-	-
data	xp_harmonic_model_str	-	Attitude initialization data	-	-

### 7.26.4 Output parameters

The output parameters of the `xp_sat_att_set_harmonic` CFI function are:

*Table 69: Output parameters of xp\_sat\_att\_set\_harmonic function*

C name	C type	Array	Description	Unit	Allowed Range
--------	--------	-------	-------------	------	---------------

		Element	(Reference)	(Format)	
xp_sat_att_set_harmonic	long	-	Status flag	-	-
sat_trans_id	xp_sat_trans_id *	-	Satellite transformation ID (input / output parameter)	-	-

### **7.26.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The sat\_trans\_id was not initialised.
- The sat\_trans\_id initialization does not allow the use of this function.

## 7.27 xp\_sat\_att\_get\_file

### 7.27.1 Overview

The `xp_sat_att_get_file` CFI function returns satellite attitude data from the satellite attitude Id. that was initialized with a file.

### 7.27.2 Calling interface

The calling interface of the `xp_sat_att_get_file` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    xp_sat_trans_id sat_trans_id;
    long status;
    xp_sat_att_file_model_str data;
    status = xp_sat_att_get_file (&sat_trans_id,
                                &data);
}
```

### 7.27.3 Input parameters

The `xp_sat_att_get_file` CFI function has the following input parameters:

*Table 70: Input parameters of xp\_sat\_att\_get\_file function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_trans_id	xp_sat_trans_id*	-	Satellite transformation ID.	-	-

### 7.27.4 Output parameters

The output parameters of the `xp_sat_att_get_file` CFI function are:

*Table 71: Output parameters of xp\_sat\_att\_get\_file function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xp_sat_att_get_file	long	-	Status flag	-	-
data	xp_sat_att_file_model_str	-	Attitude initialization data	-	-

### **7.27.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The `sat_trans_id` was not initialised.
- The `sat_trans_id` initialization does not allow the use of this function.

## 7.28 xp\_sat\_att\_set\_file

### 7.28.1 Overview

The `xp_sat_att_set_file` CFI function changes the initialization data in the satellite attitude Id. when it was initialised with a file. Quaternions are checked to be normalized.

### 7.28.2 Calling interface

The calling interface of the `xp_sat_att_set_file` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    xp_sat_trans_id sat_trans_id;
    long status;
    xp_sat_att_file_model_str data;
    status = xp_sat_att_set_file (&sat_trans_id,
                                &data);
}
```

### 7.28.3 Input parameters

The `xp_sat_att_set_file` CFI function has the following input parameters:

**Table 72: Input parameters of xp\_sat\_att\_set\_file function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_trans_id	xp_sat_trans_id *	-	Satellite transformation ID (input / output parameter)	-	-
data	xp_sat_att_file_model_str	-	Attitude initialization data	-	-

### 7.28.4 Output parameters

The output parameters of the `xp_sat_att_set_file` CFI function are:

**Table 73: Output parameters of xp\_sat\_att\_set\_file function**

C name	C type	Array	Description	Unit	Allowed Range
--------	--------	-------	-------------	------	---------------

		Element	(Reference)	(Format)	
xp_sat_att_set_file	long	-	Status flag	-	-
sat_trans_id	xp_sat_trans_id *	-	Satellite transformation ID (input / output parameter)	-	-

### **7.28.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The sat\_trans\_id was not initialised.
- The sat\_trans\_id initialization does not allow the use of this function.



## 7.29 xp\_sat\_att\_get\_quat\_plus\_angle

### 7.29.1 Overview

The `xp_sat_att_get_quat_plus_angle` CFI function returns satellite attitude data from the satellite attitude Id. that was initialized with quaternions and angles.

### 7.29.2 Calling interface

The calling interface of the `xp_sat_att_get_quat_plus_angle` CFI function is the following (input parameters are underlined>):

```
#include <explorer_lib.h>
{
    xp_sat_trans_id sat_trans_id;
    long status;
    xp_quat_plus_angle_model_str data;
    status = xp_sat_att_get_quat_plus_angle (&sat_trans_id,
                                             &data);
}
```

### 7.29.3 Input parameters

The `xp_sat_att_get_quat_plus_angle` CFI function has the following input parameters:

*Table 74: Input parameters of xp\_sat\_att\_get\_file function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_trans_id	xp_sat_trans_id*	-	Satellite transformation ID.	-	-

### 7.29.4 Output parameters

The output parameters of the `xp_sat_att_get_quat_plus_angle` CFI function are:

*Table 75: Output parameters of xp\_sat\_att\_get\_file function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xp_sat_att_get_quat_plus_angle	long	-	Status flag	-	-
data	xp_quat_plus_angle	-	Attitude initialization	-	-

---

	gle_model_str		data		
--	---------------	--	------	--	--

### **7.29.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The sat\_trans\_id was not initialised.
- The sat\_trans\_id initialization does not allow the use of this function.
- There was an error in the calculation of the angles from the rotation matrix.

## 7.30 xp\_sat\_att\_set\_quat\_plus\_angle

### 7.30.1 Overview

The `xp_sat_att_set_quat_plus_angle` CFI function changes the initialization data in the satellite attitude Id. when it was initialised with quaternions and angles. The input quaternions are checked to be normalized.

### 7.30.2 Calling interface

The calling interface of the `xp_sat_att_set_quat_plus_angle` CFI function is the following (input parameters are underlined>):

```
#include <explorer_lib.h>
{
    xp_sat_trans_id sat_trans_id;
    long status;
    xp_quat_plus_angle_model_str data;
    status = xp_sat_att_set_quat_plus_angle (&sat_trans_id,
                                             &data);
}
```

### 7.30.3 Input parameters

The `xp_sat_att_set_quat_plus_angle` CFI function has the following input parameters:

*Table 76: Input parameters of xp\_sat\_att\_set\_quat\_plus\_angle function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_trans_id	xp_sat_trans_id *	-	Satellite transformation ID (input / output parameter)	-	-
data	xp_quat_plus_angle_model_str	-	Attitude initialization data	-	-

### 7.30.4 Output parameters

The output parameters of the `xp_sat_att_set_quat_plus_angle` CFI function are:

**Table 77: Output parameters of xp\_sat\_att\_set\_quat\_plus\_angle function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xp_sat_att_set_quat_plus_angle	long	-	Status flag	-	-
sat_trans_id	xp_sat_trans_id *	-	Satellite transformation ID (input / output parameter)	-	-

### **7.30.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The sat\_trans\_id was not initialised.
- The sat\_trans\_id initialization does not allow the use of this function.
- There was an error in the calculation of the rotation matrix from angles.

## 7.31 xp\_sat\_att\_get\_quat\_plus\_matrix

### 7.31.1 Overview

The `xp_sat_att_get_quat_plus_matrix` CFI function returns satellite attitude data from the satellite attitude Id. that was initialized with quaternions and a rotation matrix.

#### Note on matrix notation:

If XYZ are the axes of the original reference frame, and X'Y'Z' are the axes of the rotated frame, the rows of the rotation matrix are respectively X, Y and Z axes expressed in X'Y'Z' system.

In the C representation, `M[0][[]]`, `M[1][[]]`, `M[2][[]]` are respectively 1st, and and 3rd row of a rotation matrix M.

The rotation matrix M satisfies the following equivalence:

$$\mathbf{V} = \mathbf{M} * \mathbf{V}'$$

where  $\mathbf{V}'$  is a vector expressed in the X'Y'Z' reference system and  $\mathbf{V}$  is expressed in the XYZ reference system.

### 7.31.2 Calling interface

The calling interface of the `xp_sat_att_get_quat_plus_matrix` CFI function is the following (input parameters are underlined>):

```
#include <explorer_lib.h>
{
    xp_sat_trans_id sat_trans_id;
    long status;
    xp_quat_plus_matrix_model_str data;
    status = xp_sat_att_get_quat_plus_matrix (&sat_trans_id,
                                             &data);
}
```

### 7.31.3 Input parameters

The `xp_sat_att_get_quat_plus_matrix` CFI function has the following input parameters:

**Table 78: Input parameters of xp\_sat\_att\_get\_quat\_plus\_matrix function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_trans_id	xp_sat_trans_id *	-	Satellite transformation ID.	-	-

### 7.31.4 Output parameters

The output parameters of the `xp_sat_att_get_quat_plus_matrix` CFI function are:

*Table 79: Output parameters of `xp_sat_att_get_quat_plus_matrix` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>xp_sat_att_get_quat_plus_matrix</code>	long	-	Status flag	-	-
data	<code>xp_quat_plus_matrix_model_str</code>	-	Attitude initialization data	-	-

### 7.31.5 Warnings and errors

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The `sat_trans_id` was not initialised.
- The `sat_trans_id` initialization does not allow the use of this function.

## 7.32 xp\_sat\_att\_set\_quat\_plus\_matrix

### 7.32.1 Overview

The `xp_sat_att_set_quat_plus_matrix` CFI function changes the initialization data in the satellite attitude Id. when it was initialised with quaternions and a rotation matrix. The input quaternions are checked to be normalized, and the input matrix is checked to be orthonormal.

#### Note on matrix notation:

If XYZ are the axes of the original reference frame, and X'Y'Z' are the axes of the rotated frame, the rows of the rotation matrix are respectively X, Y and Z axes expressed in X'Y'Z' system.

In the C representation, `M[0][[]]`, `M[1][[]]`, `M[2][[]]` are respectively 1st, and and 3rd row of a rotation matrix M.

The rotation matrix M satisfies the following equivalence:

$$\mathbf{V} = \mathbf{M} * \mathbf{V}'$$

where  $\mathbf{V}'$  is a vector expressed in the X'Y'Z' reference system and  $\mathbf{V}$  is expressed in the XYZ reference system.

### 7.32.2 Calling interface

The calling interface of the `xp_sat_att_set_quat_plus_matrix` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    xp_sat_trans_id sat_trans_id;
    long status;
    xp_quat_plus_matrix_model_str data;
    status = xp_sat_att_set_quat_plus_matrix (&sat_trans_id,
                                             &data);
}
```

### 7.32.3 Input parameters

The `xp_sat_att_set_quat_plus_matrix` CFI function has the following input parameters:

*Table 80: Input parameters of xp\_sat\_att\_set\_quat\_plus\_matrix function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_trans_id	xp_sat_trans_id *	-	Satellite transformation ID (input / output parameter)	-	-
data	xp_quat_plus_	-	Attitude initialization	-	-

	matrix_model_str		data		
--	------------------	--	------	--	--

### 7.32.4 Output parameters

The output parameters of the `xp_sat_att_set_quat_plus_matrix` CFI function are:

*Table 81: Output parameters of xp\_sat\_att\_get\_quat\_plus\_matrix function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>xp_sat_att_set_quat_plus_matrix</code>	long	-	Status flag	-	-
<code>sat_trans_id</code>	<code>xp_sat_trans_id</code> *	-	Satellite transformation ID (input / output parameter)	-	-

### 7.32.5 Warnings and errors

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The `sat_trans_id` was not initialised.
- The `sat_trans_id` initialization does not allow the use of this function.



## 7.33 xp\_instr\_att\_angle\_init

### 7.33.1 Overview

The `xp_instr_att_angle_init` CFI function initialises the instrument attitude mispointing angles for a given satellite and instrument with a user-provided set of values. The initialised values will be stored in the `instr_trans_id` output structure.

### 7.33.2 Calling Interface

The calling interface of the `xp_instr_att_angle_init` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    double ang[3], offset[3];
    xp_instr_trans_id instr_trans_id = {NULL};
    long ierr[XP_NUM_ERR_INSTR_ATT_ANGLE_INIT], status;

    status = xp_instr_att_angle_init(ang, offset,
                                     &instr_trans_id, ierr);
}
```

The `XP_NUM_ERR_INSTR_ATT_ANGLE_INIT` constant is defined in the file `explorer_pointing.h`.

### 7.33.3 Input Parameters

The `xp_instr_att_angle_init` CFI function has the following input parameters:

*Table 82: Input parameters of `xp_instr_att_angle_init` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
ang	double[3]	[0]	Pitch mispointing angle (Satellite Attitude Frame)	deg	If no better value, assume 0.0
		[1]	Roll mispointing angle (Satellite Attitude Frame)	deg	If no better value, assume 0.0
		[2]	Yaw mispointing angle (Satellite Attitude Frame)	deg	If no better value, assume 0.0
offset	double[3]	all	Instrument Frame Origin position vector (Satellite Attitude Frame)	m	-

### 7.33.4 Output Parameters

The output parameters of the `xp_instr_att_angle_init` CFI function are:

*Table 83: Output parameters of `xp_instr_att_angle_init`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
instr_trans_id	xp_instr_trans_id*	-	Structure that contains the Instrument Transformation	-	-
ierr	long	-	Error vector	-	-

### 7.33.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_instr_att_angle_init` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_instr_att_angle_init` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

*Table 84: Error messages of xp\_instr\_att\_angle\_init function*

Error type	Error message	Cause and impact	Error code	Error No
ERR	Memory allocation error	No calculation performed	XP_CFI_INSTR_ATT_ANGLE_INIT_MEMORY_ERR	0

## 7.34 xp\_instr\_att\_matrix\_init

### 7.34.1 Overview

The `xp_instr_att_matrix_init` CFI function initialises the instrument attitude mispointing angles for a given satellite and instrument with a user-provided matrix. The initialised values will be stored in the `instr_trans_id` output structure. Input matrix is checked to be orthonormal.

#### Note on matrix notation:

If XYZ are the axes of the original reference frame, and X'Y'Z' are the axes of the rotated frame, the rows of the rotation matrix are respectively X, Y and Z axes expressed in X'Y'Z' system.

In the C representation, `M[0][[]]`, `M[1][[]]`, `M[2][[]]` are respectively 1st, and and 3rd row of a rotation matrix M.

The rotation matrix M satisfies the following equivalence:

$$\mathbf{V} = \mathbf{M} * \mathbf{V}'$$

where  $\mathbf{V}'$  is a vector expressed in the X'Y'Z' reference system and  $\mathbf{V}$  is expressed in the XYZ reference system.

### 7.34.2 Calling Interface

The calling interface of the `xp_instr_att_matrix_init` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    double att_matrix[3][3], offset[3];
    xp_instr_trans_id instr_trans_id = {NULL};
    long ierr[XP_NUM_ERR_INSTR_ATT_MATRIX_INIT], status;

    status = xp_instr_att_matrix_init(att_matrix, offset,
                                     &instr_trans_id, ierr);
}
```

The `XP_NUM_ERR_INSTR_ATT_MATRIX_INIT` constant is defined in the file `explorer_pointing.h`.

### 7.34.3 Input Parameters

The `xp_instr_att_matrix_init` CFI function has the following input parameters:

*Table 85: Input parameters of `xp_instr_att_matrix_init` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>att_matrix</code>	<code>double[3][3]</code>	all	Mispointing Matrix	-	-
<code>offset</code>	<code>double[3]</code>	all	Instrument Frame Origin position vector (Satellite Attitude Frame)	m	-

### 7.34.4 Output Parameters

The output parameters of the `xp_instr_att_matrix_init` CFI function are:

*Table 86: Output parameters of `xp_instr_att_matrix_init`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>instr_trans_id</code>	<code>xp_instr_trans_id*</code>	-	Structure that contains the Instrument Transformation	-	-
<code>ierr</code>	<code>long</code>	-	Error vector	-	-

### 7.34.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_instr_att_matrix_init` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_instr_att_matrix_init` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

*Table 87: Error messages of `xp_instr_att_matrix_init` function*

Error type	Error message	Cause and impact	Error code	Error No
ERR	Memory allocation error	No calculation performed	XP_CFI_INSTR_ATT_MATRIX_INIT_MEMORY_ERR	0

ERR	Matrix is not orthonormal	No calculation performed. The CFI performs a check, with a tolerance of $10^{-6}$ , that the product of the input matrix and its transposed is the unitary matrix.	XP_CFI_INSTR_ATT_MATRIX_INIT_MATRIX_ORTHONORMAL_ERR	1
-----	---------------------------	--	---	---

## 7.35 xp\_instr\_att\_init\_harmonic

### 7.35.1 Overview

The `xp_instr_att_init_harmonic` CFI function initialises the instrument attitude mispointing angles (i.e. roll, pitch, yaw) for a given satellite and instrument with a user-provided set of values. The initialised values will be stored in the `instr_trans_id` output structure.

The mispointing angle (`attitudeangle` in the formula) will be calculated by functions using such `instr_trans_id` (i.e. `xp_attitude_compute` or `xp_change_frame`) according to the following formula (the "angle" variable will be calculated as in `xl_position_on_orbit` (see [LIB\_SUM]), using as inputs:

- the input state vector in EF passed to such functions;
- the `angle_type` passed as input to `xp_instr_att_init_harmonic`.

### 7.35.2 Calling Interface

The calling interface of the `xp_instr_att_init_harmonic` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long angle_type, num_terms[3];
    long harmonic_type_pitch[XP_MAX_NUM_HARMONIC],
        harmonic_type_roll[XP_MAX_NUM_HARMONIC],
        harmonic_type_yaw[XP_MAX_NUM_HARMONIC];
    double harmonic_coef_pitch[XP_MAX_NUM_HARMONIC],
        harmonic_coef_roll[XP_MAX_NUM_HARMONIC],
        harmonic_coef_yaw[XP_MAX_NUM_HARMONIC];
    double offset[3];
    xp_instr_trans_id instr_trans_id = {NULL};
    long ierr[XP_NUM_ERR_INSTR_ATT_INIT_HARMONIC], status;

    status = xp_instr_att_init_harmonic(&angle_type, num_terms,
                                        harmonic_type_pitch,
                                        harmonic_type_roll,
                                        harmonic_type_yaw,
                                        harmonic_coef_pitch,
                                        harmonic_coef_roll,
                                        harmonic_coef_yaw,
                                        offset,
```

```
        &instr_trans_id, ierr);  
    }
```

The `XP_NUM_ERR_INSTR_ATT_INIT_HARMONIC` and `XP_MAX_NUM_HARMONIC` constants are defined in the file *explorer\_pointing.h*.



### 7.35.3 Input Parameters

The `xp_instr_att_init_harmonic` CFI function has the following input parameters:

**Table 88: Input parameters of `xp_instr_att_init_harmonic` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>angle_type</code>	<code>long *</code>	-	Type of angle	-	XP_ANGLE_TYPE_TRUE_LAT_TOD XP_ANGLE_TYPE_MEAN_LAT_TOD XP_ANGLE_TYPE_TRUE_LAT_EF
<code>num_terms[3]</code>	<code>long</code>	[0]	Number of elements used in vectors <code>harmonic_type_pitch</code> and <code>harmonic_coef_pitch</code>	-	$\geq 0$
		[1]	Number of elements used in vectors <code>harmonic_type_roll</code> and <code>harmonic_coef_roll</code>	-	$\geq 0$
		[2]	Number of elements used in vectors <code>harmonic_type_yaw</code> and <code>harmonic_coef_yaw</code>	-	$\geq 0$
<code>harmonic_type_pitch</code>	<code>long[XP_MAX_NUM_HARMONIC]</code>	all	Type of coefficients: =0 for the bias parameter <0 for the sinus coefficients (-n means that corresponds to the sinus coefficient of order n) >0 for the cosinus coefficients (+n means that corresponds to the cosinus coefficient of order n)	-	
<code>harmonic_type_roll</code>	<code>long[XP_MAX_NUM_HARMONIC]</code>	all	Type of coefficients: =0 for the bias parameter <0 for the sinus coefficients (-n means that corresponds to the sinus coefficient of order n) >0 for the cosinus coefficients (+n means that corresponds to the cosinus coefficient of order n)	-	-
<code>harmonic_type_yaw</code>	<code>long[XP_MAX_NUM_HARMONIC]</code>	all	Type of coefficients: =0 for the bias parameter <0 for the sinus coefficients (-n means that corresponds to the	-	-

			sinus coefficient of order n) >0 for the cosinus coefficients (+n means that corresponds to the cosinus coefficient of order n)		
harmonic_coef _pitch	double[XP_MAX_NUM_HARMONIC]	all	Bias, sinus and cosinus coefficients for the pitch angle	deg	
harmonic_coef _roll	double[XP_MAX_NUM_HARMONIC]	all	Bias, sinus and cosinus coefficients for the roll angle	deg	
harmonic_coef _yaw	double[XP_MAX_NUM_HARMONIC]	all	Bias, sinus and cosinus coefficients for the yaw angle	deg	
offset	double[3]	all	Instrument Frame Origin position vector (Satellite Attitude Frame)	m	-

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Angle Type: See current document, Table 3.

### 7.35.40 Output Parameters

The output parameters of the `xp_instr_att_init_harmonic` CFI function are:

*Table 89: Output parameters of xp\_instr\_att\_init\_harmonic*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
instr_trans_id	xp_instr_trans_id*	-	Structure that contains the Instrument Transformation	-	-
ierr	long	-	Error vector	-	-

### 7.35.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_instr_att_init_harmonic` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_instr_att_init_harmonic` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 90: Error messages of `xp_instr_att_init_harmonic` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Memory allocation error	No calculation performed	XP_CFI_INSTR_ATT_INIT_HARMONIC_MEMORY_ERR	0

## 7.36 xp\_instr\_att\_init\_file

### 7.36.1 Overview

The `xp_instr_att_init_file` CFI function initialises the instrument attitude mispointing angles for a given satellite reading values from the attitude file(s). The validity time or orbital range for the attitude angles can be specified by the user. The initialised values will be kept in memory and used by other CFI functions.

In order to read files, `xp_instr_att_init_file` function internally uses Data Handling functions. Please refer to [D\_H\_SUM], in particular sections 4.2 and 4.3, for further details.

### 7.36.2 Calling Interface

The calling interface of the `xp_instr_att_init_file` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    xl_time_id time_id = {NULL};
    long n_files, time_init_mode, time_ref;
    char **instrument_file;
    double time0, time1;
    double val_time0, val_time1;
    xp_instr_trans_id instr_trans_id = {NULL};
    long ierr[XP_NUM_ERR_INSTR_ATT_INIT_FILE], status;

    status = xp_instr_att_init_file(&time_id,
        &n_files, instrument_file,
        &time_init_mode, &time_ref, &time0, &time1,
        &val_time0, &val_time1, &instr_trans_id, ierr);
}
```

The `XP_NUM_ERR_INSTR_ATT_INIT_FILE` constant is defined in the file *explorer\_pointing.h*.

### 7.36.3 Input Parameters

The `xp_instr_att_init_file` CFI function has the following input parameters:

**Table 91: Input parameters of `xp_instr_att_init_file` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>time_id</code>	<code>xl_time_id*</code>	-	Structure that contains the time correlations.	-	-
<code>n_files</code>	<code>long *</code>	-	Number of reference data files	-	> 0
<code>instrument_file</code>	<code>char **</code>	-	Filenames of the reference data files. In case multiple files are used, the files should be time ordered.  The supported Attitude File format is the Generic Attitude File as described in [D_H_SUM]	-	-
<code>time_init_mode</code>	<code>long *</code>	-	Flag for selecting the time range of the initialization.	-	Select either: · <code>XP_SEL_TIME</code> · <code>XP_SEL_FILE</code>
<code>time_ref</code>	<code>long *</code>	-	Time reference ID	-	Complete
<code>time0</code>	<code>double*</code>	-	If: <code>time_init_mode=XP_SEL_TIME</code> Start of the time range defined by [time0,time1]	Decimal days (Processing format)	[-18262.0,36524.0]
<code>time1</code>	<code>double*</code>	-	If: <code>time_init_mode=XP_SEL_TIME</code> End of the time range defined by [time0,time1]	Decimal days (Processing format)	[-18262.0,36524.0] > time0

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Time Reference ID: `time_ref`. See [GEN\_SUM].
- Time Init Mode ID: `time_init_mode`. See current document, Table 3.

### 7.36.4 Output Parameters

The output parameters of the `xp_instr_att_init_file` CFI function are:

**Table 92: Output parameters of `xp_instr_att_init_file`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
--------	--------	---------------	-------------------------	---------------	---------------

val_time0	double*	-	Validity start time of the initialization	Decimal days (Processing format)	[-18262.0,36524.0]
val_time1	double*	-	Validity end time of the initialization	Decimal days (Processing format)	[-18262.0,36524.0]
instr_trans_id	xp_instr_trans_id*	-	Structure that contains the Instrument Transformation	-	-
ierr	long	-	Error vector	-	-

### 7.36.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the **xp\_instr\_att\_init\_file** CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library **xp\_get\_msg** (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the **xp\_instr\_att\_init\_file** function by calling the function of the EO\_POINTING software library **xp\_get\_code** (see [GEN\_SUM]).

**Table 93: Error messages of xp\_instr\_att\_init\_file function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Memory allocation error	No calculation performed	XP_CFI_INSTR_ATT_INIT_FILE_MEMORY_ERR	0
ERR	Wrong input time reference	No calculation performed	XP_CFI_INSTR_ATT_INIT_FILE_WRONG_TIME_REF_ERR	1
ERR	Error opening attitude file: %s	No calculation performed	XP_CFI_INSTR_ATT_INIT_FILE_OPEN_FILES_ERR	2
ERR	Error reading generic attitude files	No calculation performed	XP_CFI_INSTR_ATT_INIT_FILE_READ_ATT_FILES_ERR	3
ERR	Could not perform a time transformation	No calculation performed	XP_CFI_INSTR_ATT_INIT_FILE_TIME_CONV_ERR	4

## 7.37 xp\_instr\_att\_close

### 7.37.1 Overview

The `xp_instr_att_close` CFI function cleans up any memory allocation performed by the instrument attitude initialization functions.

### 7.37.2 Calling Interface

The calling interface of the `xp_instr_att_close` CFI function is the following (input parameters are underlined>):

```
#include <explorer_pointing.h>
{
    xp_instr_trans_id instr_trans_id = {NULL};
    long ierr[XP_NUM_ERR_INSTR_ATT_CLOSE], status;

    status = xp_instr_att_close(&instr_trans_id, ierr);
}
```

The `XP_NUM_ERR_INSTR_ATT_CLOSE` constant is defined in the file `explorer_pointing.h`.

### 7.37.3 Input Parameters

The `xp_instr_att_close` CFI function has the following input parameters:

*Table 94: Input parameters of xp\_instr\_att\_close function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
instr_trans_id	xp_instr_trans_id*	-	Structure that contains the Instr. Trans.	-	-

### 7.37.4 Output Parameters

The output parameters of the `xp_instr_att_close` CFI function are:

*Table 95: Output parameters of xp\_instr\_att\_close*

C name	C type	Array	Description	Unit	Allowed Range
--------	--------	-------	-------------	------	---------------

		Element	(Reference)	(Format)	
ierr	long	-	Error vector	-	-

### 7.37.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_instr_att_close` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_instr_att_close` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 96: Error messages of `xp_instr_att_close` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Could not close the Id. as it is not initialized or it is being used	No calculation performed	XP_CFI_INSTR_ATT_CLOS E_WRONG_ID_ERR	0



## 7.38 xp\_instr\_att\_get\_angles

### 7.38.1 Overview

The `xp_instr_att_get_angles` CFI function returns the angle data used for the instrument attitude initialization.

### 7.38.2 Calling interface

The calling interface of the `xp_instr_att_get_angles` CFI function is the following (input parameters are underlined>):

```
#include <explorer_lib.h>
{
    xp_instr_trans_id instr_trans_id;
    long status;
    xp_angle_model_str data;
    status = xp_instr_att_get_angles (&instr_trans_id,
                                     &data);
}
```

### 7.38.3 Input parameters

The `xp_instr_att_get_angles` CFI function has the following input parameters:

*Table 97: Input parameters of xp\_instr\_att\_get\_angles function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
instr_trans_id	xp_instr_trans_id *	-	Instrument transformation ID.	-	-

### 7.38.4 Output parameters

The output parameters of the `xp_instr_att_get_angles` CFI function are:

*Table 98: Output parameters of xp\_instr\_att\_get\_angles function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xp_instr_att_get_angles	long	-	Status flag	-	-
data	xp_angle_model	-	Attitude initialization	-	-

---

	_str		data		
--	------	--	------	--	--

### **7.38.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The `instr_trans_id` was not initialised.
- The `instr_trans_id` initialization does not allow the use of this function.

## 7.39 xp\_instr\_att\_set\_angles

### 7.39.1 Overview

The `xp_instr_att_set_angles` CFI function changes the harmonic data used for the satellite attitude initialization.

### 7.39.2 Calling interface

The calling interface of the `xp_instr_att_set_angles` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    xp_instr_trans_id instr_trans_id;
    long status;
    xp_angle_model_str data;
    status = xp_instr_att_set_angles (&instr_trans_id,
                                     &data);
}
```

### 7.39.3 Input parameters

The `xp_instr_att_set_angles` CFI function has the following input parameters:

**Table 99: Input parameters of xp\_instr\_att\_set\_angles function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
instr_trans_id	xp_instr_trans_id *	-	Instrument transformation ID (input / output parameter)	-	-
data	xp_angle_model_str	-	Attitude initialization data	-	-

### 7.39.4 Output parameters

The output parameters of the `xp_instr_att_set_angles` CFI function are:

**Table 100: Output parameters of xp\_instr\_att\_set\_angles function**

C name	C type	Array	Description	Unit	Allowed Range
--------	--------	-------	-------------	------	---------------

		Element	(Reference)	(Format)	
xp_instr_att_set_angles	long	-	Status flag	-	-
instr_trans_id	xp_instr_trans_id *	-	Instrument transformation ID (input / output parameter)	-	-

### **7.39.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The instr\_trans\_id was not initialised.
- The instr\_trans\_id initialization does not allow the use of this function.

## 7.40 xp\_instr\_att\_get\_matrix

### 7.40.1 Overview

The `xp_instr_att_get_matrix` CFI function returns the matrix data used for the satellite attitude initialization.

#### Note on matrix notation:

If XYZ are the axes of the original reference frame, and X'Y'Z' are the axes of the rotated frame, the rows of the rotation matrix are respectively X, Y and Z axes expressed in X'Y'Z' system.

In the C representation, `M[0][[]]`, `M[1][[]]`, `M[2][[]]` are respectively 1st, and and 3rd row of a rotation matrix M.

The rotation matrix M satisfies the following equivalence:

$$\mathbf{V} = \mathbf{M} * \mathbf{V}'$$

where  $\mathbf{V}'$  is a vector expressed in the X'Y'Z' reference system and  $\mathbf{V}$  is expressed in the XYZ reference system.

### 7.40.2 Calling interface

The calling interface of the `xp_instr_att_get_matrix` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    xp_instr_trans_id instr_trans_id;
    long status;
    xp_matrix_model_str data;
    status = xp_instr_att_get_matrix (&instr_trans_id,
                                     &data);
}
```

### 7.40.3 Input parameters

The `xp_instr_att_get_matrix` CFI function has the following input parameters:

**Table 101: Input parameters of `xp_instr_att_get_matrix` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>instr_trans_id</code>	<code>xp_instr_trans_id *</code>	-	Instrument transformation ID.	-	-

### 7.40.4 Output parameters

The output parameters of the `xp_instr_att_get_matrix` CFI function are:

*Table 102: Output parameters of `xp_instr_att_get_matrix` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>xp_instr_att_get_matrix</code>	long	-	Status flag	-	-
data	<code>xp_matrix_mode_l_str</code>	-	Attitude initialization data	-	-

### 7.40.5 Warnings and errors

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The `instr_trans_id` was not initialised.
- The `instr_trans_id` initialization does not allow the use of this function.

## 7.41 xp\_instr\_att\_set\_matrix

### 7.41.1 Overview

The `xp_instr_att_set_matrix` CFI function changes matrix data used for the satellite attitude initialization. The matrix is checked to be orthonormal.

#### Note on matrix notation:

If XYZ are the axes of the original reference frame, and X'Y'Z' are the axes of the rotated frame, the rows of the rotation matrix are respectively X, Y and Z axes expressed in X'Y'Z' system.

In the C representation, `M[0][[]]`, `M[1][[]]`, `M[2][[]]` are respectively 1st, and and 3rd row of a rotation matrix M.

The rotation matrix M satisfies the following equivalence:

$$\mathbf{V} = \mathbf{M} * \mathbf{V}'$$

where  $\mathbf{V}'$  is a vector expressed in the X'Y'Z' reference system and  $\mathbf{V}$  is expressed in the XYZ reference system.

### 7.41.2 Calling interface

The calling interface of the `xp_instr_att_set_matrix` CFI function is the following (input parameters are underlined>):

```
#include <explorer_lib.h>
{
    xp_instr_trans_id instr_trans_id;
    long status;
    xp_matrix_model_str data;
    status = xp_instr_att_set_matrix (&instr_trans_id,
                                     &data);
}
```

### 7.41.3 Input parameters

The `xp_instr_att_set_matrix` CFI function has the following input parameters:

**Table 103: Input parameters of xp\_instr\_att\_set\_matrix function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
instr_trans_id	xp_instr_trans_id *	-	Instrument transformation ID (input / output parameter)	-	-
data	xp_angle_model_str	-	Attitude initialization data	-	-

### 7.41.4 Output parameters

The output parameters of the `xp_instr_att_set_matrix` CFI function are:

*Table 104: Output parameters of `xp_instr_att_set_matrix` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>xp_instr_att_set_matrix</code>	long	-	Status flag	-	-
<code>instr_trans_id</code>	<code>xp_instr_trans_id *</code>	-	Instrument transformation ID (input / output parameter)	-	-

### 7.41.5 Warnings and errors

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The `instr_trans_id` was not initialised.
- The `instr_trans_id` initialization does not allow the use of this function.



## 7.42 xp\_instr\_att\_get\_harmonic

### 7.42.1 Overview

The `xp_instr_att_get_harmonic` CFI function returns harmonic data used for the satellite attitude initialization.

### 7.42.2 Calling interface

The calling interface of the `xp_instr_att_get_harmonic` CFI function is the following (input parameters are underlined>):

```
#include <explorer_lib.h>
{
    xp_instr_trans_id instr_trans_id;
    long status;
    xp_harmonic_model_str data;
    status = xp_instr_att_get_harmonic (&instr_trans_id,
                                        &data);
}
```

### 7.42.3 Input parameters

The `xp_instr_att_get_harmonic` CFI function has the following input parameters:

*Table 105: Input parameters of xp\_instr\_att\_get\_harmonic function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
instr_trans_id	xp_instr_trans_id *	-	Instrument transformation ID.	-	-

### 7.42.4 Output parameters

The output parameters of the `xp_instr_att_get_harmonic` CFI function are:

*Table 106: Output parameters of xp\_instr\_att\_get\_harmonic function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xp_instr_att_get_harmonic	long	-	Status flag	-	-
data	xp_harmonic_m	-	Attitude initialization	-	-

---

	odel_str		data		
--	----------	--	------	--	--

### **7.42.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The `instr_trans_id` was not initialised.
- The `instr_trans_id` initialization does not allow the use of this function.

## 7.43 xp\_instr\_att\_set\_harmonic

### 7.43.1 Overview

The `xp_instr_att_set_harmonic` CFI function changes the harmonic data used for the satellite attitude initialization.

### 7.43.2 Calling interface

The calling interface of the `xp_instr_att_set_harmonic` CFI function is the following (input parameters are underlined>):

```
#include <explorer_lib.h>
{
    xp_instr_trans_id instr_trans_id;
    long status;
    xp_harmonic_model_str data;
    status = xp_instr_att_set_harmonic (&instr_trans_id,
                                        &data);
}
```

### 7.43.3 Input parameters

The `xp_instr_att_set_harmonic` CFI function has the following input parameters:

*Table 107: Input parameters of xp\_instr\_att\_set\_harmonic function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
instr_trans_id	xp_instr_trans_id *	-	Instrument transformation ID (input / output parameter)	-	-
data	xp_harmonic_model_str	-	Attitude initialization data	-	-

### 7.43.4 Output parameters

The output parameters of the `xp_instr_att_set_harmonic` CFI function are:

*Table 108: Output parameters of xp\_instr\_att\_set\_harmonic function*

C name	C type	Array	Description	Unit	Allowed Range
--------	--------	-------	-------------	------	---------------

		Element	(Reference)	(Format)	
xp_instr_att_set_harmonic	long	-	Status flag	-	-
instr_trans_id	xp_instr_trans_id *	-	Instrument transformation ID (input / output parameter)	-	-

### **7.43.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The instr\_trans\_id was not initialised.
- The instr\_trans\_id initialization does not allow the use of this function.

## 7.44 xp\_instr\_att\_get\_file

### 7.44.1 Overview

The `xp_instr_att_get_file` CFI function returns satellite attitude data from the satellite attitude Id. that was initialized with a file.

### 7.44.2 Calling interface

The calling interface of the `xp_instr_att_get_file` CFI function is the following (input parameters are underlined>):

```
#include <explorer_lib.h>
{
    xp_instr_trans_id instr_trans_id;
    long status;
    xp_instr_att_file_model_str data;
    status = xp_instr_att_get_file (&instr_trans_id,
                                   &data);
}
```

### 7.44.3 Input parameters

The `xp_instr_att_get_file` CFI function has the following input parameters:

*Table 109: Input parameters of xp\_instr\_att\_get\_file function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
instr_trans_id	xp_instr_trans_id *	-	Instrument transformation ID.	-	-

### 7.44.4 Output parameters

The output parameters of the `xp_instr_att_get_file` CFI function are:

*Table 110: Output parameters of xp\_instr\_att\_get\_file function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xp_instr_att_get_file	long	-	Status flag	-	-
data	xp_instr_att_file_model_str	-	Attitude initialization data	-	-

### **7.44.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The `instr_trans_id` was not initialised.
- The `instr_trans_id` initialization does not allow the use of this function.

## 7.45 xp\_instr\_att\_set\_file

### 7.45.1 Overview

The `xp_instr_att_set_file` CFI function changes the initialization data in the satellite attitude Id. when it was initialised with a file. Quaternions are checked to be normalized.

### 7.45.2 Calling interface

The calling interface of the `xp_instr_att_set_file` CFI function is the following (input parameters are underlined>):

```
#include <explorer_lib.h>
{
    xp_instr_trans_id instr_trans_id;
    long status;
    xp_instr_att_file_model_str data;
    status = xp_instr_att_set_file (&instr_trans_id,
                                   &data);
}
```

### 7.45.3 Input parameters

The `xp_instr_att_set_file` CFI function has the following input parameters:

*Table 111: Input parameters of xp\_instr\_att\_set\_file function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
instr_trans_id	xp_instr_trans_id *	-	Instrument transformation ID (input / output parameter)	-	-
data	xp_instr_att_file_model_str	-	Attitude initialization data	-	-

### 7.45.4 Output parameters

The output parameters of the `xp_instr_att_set_file` CFI function are:

*Table 112: Output parameters of xp\_instr\_att\_set\_file function*

C name	C type	Array	Description	Unit	Allowed Range
--------	--------	-------	-------------	------	---------------

		Element	(Reference)	(Format)	
xp_instr_att_set_file	long	-	Status flag	-	-
instr_trans_id	xp_instr_trans_id *	-	Instrument transformation ID (input / output parameter)	-	-

### 7.45.5 Warnings and errors

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The `instr_trans_id` was not initialised.
- The `instr_trans_id` initialization does not allow the use of this function.

## 7.46 xp\_set\_az\_el\_definition

### 7.46.1 Overview

The `xp_set_az_el_definition` function sets an user-defined azimuth/elevation in a satellite nominal attitude id, satellite attitude id or instrument attitude id.

### 7.46.2 Calling interface

The calling interface of the `xp_set_az_el_definition` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    void *att_frame_id;
    xl_az_el_definition azel_def;
    long ierr[XP_NUM_ERR_SET_AZ_EL_DEFINITION];
    status = xp_set_az_el_definition (att_frame_id,
                                     &azel_def,
                                     ierr);
}
```

### 7.46.3 Input parameters

The `xp_set_az_el_definition` CFI function has the following input parameters:



**Table 113: Input parameters of xp\_instr\_att\_set\_file function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
att_frame_id	void*	-	Attitude where the definition will be inserted.	-	It must be a Satellite Nominal id (xp_sat_nom_trans_id*), satellite attitude id (xp_sat_trans_id*) or instrument attitude id (xp_instr_trans_id*).
azel_def	xl_az_el_definition	-	Azimuth/elevation definition	-	-

#### 7.46.4 Output parameters

The output parameters of the xp\_set\_az\_el\_definition CFI function are:

**Table 114: Output parameters of xp\_instr\_att\_set\_file function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
ierr	long	-	Error vector	-	-

#### 7.46.5 Warnings and errors

This function returns error if the input id is not initialized, it is not of the correct type, or there is a problem with the azimuth/elevation definition introduced by the user. In Table 115 are summarized the possible errors.

**Table 115: Error messages of xp\_set\_az\_el\_definition function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Argument ID is not initialized.	No calculation performed	XP_CFI_SET_AZ_EL_DEFINITION_NOT_INITIALIZE_ERR	0
ERR	Argument ID is not a satellite nominal, satellite or instrument attitude ID.	No calculation performed	XP_CFI_SET_AZ_EL_DEFINITION_NOT_ATTITUDE_ID_ERR	1
ERR	Azimuth axis are nor	No calculation performed	XP_CFI_SET_AZ_EL_DEFINITION_ERR	2

	perpendicular.		F_NOT_PERPENDICULAR_AZIMUTH_AXIS_ERROR	
ERR	Elevation axis not perpendicular to azimuth plane.	No calculation performed	XP_CFI_SET_AZ_EL_DEF_NOT_PERPENDICULAR_ELEVATION_AXIS_ERR	3

## 7.47 xp\_attitude\_define

### 7.47.1 Overview

The `xp_attitude_define` CFI function initializes the satellite nominal attitude, satellite attitude and instrument attitude according to the input data.

The input data is stored in a structure of type `xd_attitude_definition_data` (see section 6.3 of [D\_H\_SUM]). The user can fill this structure within his application program or by reading an attitude definition file using function `xd_read_att_def` (see [D\_H\_SUM]).

### 7.47.2 Calling Interface

The calling interface of the `xp_attitude_define` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    xd_attitude_definition_data data;
    xp_sat_nom_trans_id sat_nom_trans_id;
    xp_sat_trans_id sat_trans_id;
    xp_instr_trans_id instr_trans_id;
    long ierr[XP_NUM_ERR_ATTITUDE_DEFINE], status;

    status = xp_attitude_define(&data,
                               &sat_nom_trans_id,
                               &sat_trans_id,
                               &instr_trans_id, ierr);
}
```

The `XP_NUM_ERR_ATTITUDE_DEFINE` constant is defined in the file *explorer\_pointing.h*.

### 7.47.3 Input Parameters

The `xp_attitude_define` CFI function has the following input parameters:

*Table 116: Input parameters of `xp_attitude_define` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
Data	<code>xd_attitude_definition_data</code>	-	Attitude file definition data	-	-

### 7.47.4 Output Parameters

The output parameters of the `xp_attitude_define` CFI function are:

*Table 117: Output parameters of `xp_attitude_define`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>sat_nom_trans_id</code>	<code>xp_sat_nom_trans_id*</code>	-	Structure that contains the Satellite nominal Transformation	-	-
<code>sat_trans_id</code>	<code>xp_sat_trans_id*</code>	-	Structure that contains the Satellite Transformation	-	-
<code>instr_trans_id</code>	<code>xp_instr_trans_id*</code>	-	Structure that contains the Instrument Transformation	-	-
<code>ierr</code>	<code>long</code>	-	Error vector	-	-

### 7.47.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_attitude_define` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_attitude_define` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 118: Error messages of xp\_attitude\_define function**

<b>Error type</b>	<b>Error message</b>	<b>Cause and impact</b>	<b>Error code</b>	<b>Error No</b>
ERR	Error initializing satellite nominal attitude	No computation performed	XP_ATTITUDE_DEFINE_SAT_NOM_TRANS_INIT	0
ERR	Error initializing satellite attitude	No computation performed	XP_ATTITUDE_DEFINE_SAT_TRANS_INIT	1
ERR	Error initializing instrument attitude	No computation performed	XP_ATTITUDE_DEFINE_INSTR_TRANS_INIT	2

## 7.48 xp\_run\_init

### 7.48.1 Overview

The `xp_run_init` CFI function adds to the `run_id` the `sat_nom_trans_id`, `sat_trans_id`, `instr_trans_id`, `atmos_id` and `dem_id`.

### 7.48.2 Calling interface

The calling interface of the `xp_run_init` CFI function is the following:

```
#include <explorer_pointing.h>
{
    long run_id;
    xp_sat_nom_trans_id sat_nom_trans_id = {NULL};
    xp_sat_trans_id      sat_trans_id = {NULL};
    xp_instr_trans_id    instr_trans_id = {NULL};
    xp_atmos_id          atmos_id = {NULL};
    xp_dem_id            dem_id = {NULL};
    long ierr[XP_NUM_ERR_RUN_INIT], status;
    status = xp_run_init (&run_id, &sat_nom_trans_id,
                        &sat_trans_id, &instr_trans_id,
                        &atmos_id, &dem_id,
                        ierr);
}
```

### 7.48.3 Input parameters

The `xp_run_init` CFI function has the following input parameters:

*Table 119: Input parameters of `xp_run_init` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>run_id</code>	<code>long *</code>	-	Run ID	-	$\geq 0$
<code>sat_nom_trans_id</code>	<code>xp_sat_nom_trans_id*</code>	-	Structure that contains the Sat. Nom. Trans.	-	-
<code>sat_trans_id</code>	<code>xp_sat_trans_id*</code>	-	Structure that contains the Sat. Trans.	-	-
<code>instr_trans_id</code>	<code>xp_instr_trans_id*</code>	-	Structure that contains the Instr. Trans.	-	-
<code>atmos_id</code>	<code>xp_atmos_id*</code>	-	Structure that contains the atmosphere initialization.	-	-
<code>dem_id</code>	<code>xp_dem_id*</code>	-	Structure that contains the DEM initialization.	-	-

### 7.48.4 Output parameters

The output parameters of the `xp_run_init` CFI function are:

*Table 120: Output parameters of `xp_run_init` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>xp_run_init</code>	<code>long</code>	-	Status flag	-	-
<code>run_id</code>	<code>long *</code>	-	Run ID	-	$\geq 0$
<code>ierr</code>	<code>long</code>	-	Error vector	-	-

### 7.48.5 Warnings and errors

Next table lists the possible error messages that can be returned by the `xp_run_init` CFI function after translating the returned extended status flag into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained translating the extended status flag returned by the `xp_run_init` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 121: Error messages of `xl_run_init` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Wrong input <code>run_id</code> . It is not correctly initialized	No calculation performed	XP_CFI_RUN_INIT_STATUS_ERR	0
ERR	Memory allocation error	No calculation performed	XP_CFI_RUN_INIT_MEMORY_ERR	1
ERR	Incompatible input <code>lds</code>	No calculation performed	XP_CFI_RUN_INIT_INCONSISTENCY_ERR	2



## 7.49 xp\_run\_get\_ids

### 7.49.1 Overview

The `xp_run_get_ids` CFI function returns the *ids* being used..

### 7.49.2 Calling interface

The calling interface of the `xp_run__get_ids` CFI function is the following:

```
#include <explorer_pointing.h>
{
    long run_id;
    xp_sat_nom_trans_id sat_nom_trans_id = {NULL};
    xp_sat_trans_id      sat_trans_id = {NULL};
    xp_instr_trans_id   instr_trans_id = {NULL};
    xp_atmos_id         atmos_id = {NULL};
    xp_dem_id           dem_id = {NULL};
    xp_run_get_ids (&run_id,
                  &sat_nom_trans_id,
                  &sat_trans_id,
                  &instr_trans_id,
                  &atmos_id,
                  &dem_id);
}
```

### 7.49.3 Input parameters

The `xp_run_get_ids` CFI function has the following input parameters:

*Table 122: Input parameters of `xp_run_get_ids` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
run_id	long *	-	Run ID	-	>=0

### 7.49.4 Output parameters

The output parameters of the `xp_run_get_ids` CFI function are:

*Table 123: Output parameters of `xp_run_get_ids` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xl_run_get_ids	void	-	-	-	-
sat_nom_trans_id	xp_sat_nom_trans_id*	-	Structure that contains the Sat. Nom. Trans.	-	-
sat_trans_id	xp_sat_trans_id*	-	Structure that contains the Sat. Trans.	-	-
instr_trans_id	xp_instr_trans_id*	-	Structure that contains the Instr. Trans.	-	-
atmos_id	xp_atmos_id*	-	Structure that contains the atmosphere initialization.	-	-
dem_id	xp_dem_id*	-	Structure that contains the DEM initialization.	-	-

### 7.49.5 Warnings and errors

TBW

## 7.50 xp\_run\_close

### 7.50.1 Overview

The `xp_run_close` CFI function cleans up any memory allocation performed by the initialization functions.

### 7.50.2 Calling interface

The calling interface of the `xp_run_close` CFI function is the following:

```
#include <explorer_pointing.h>
{
    long run_id;
    xp_run_close (&run_id);
}
```

### 7.50.3 Input parameters

The `xp_run_close` CFI function has the following input parameters:

*Table 124: Input parameters of xp\_run\_close function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
run_id	long *	-	Run ID	-	>=0

### 7.50.4 Output parameters

The output parameters of the `xp_run_close` CFI function are:

*Table 125: Output parameters of xp\_run\_close function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xp_run_close	void	-	-	-	-

### 7.50.5 Warnings and errors

This function does not return errors nor warnings.

## 7.51 xp\_attitude\_init

### 7.51.1 Overview

The `xp_attitude_init` CFI function creates an empty *attitude Id*.

### 7.51.2 Calling Interface

The calling interface of the `xp_attitude_init` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    xp_attitude_id attitude_id = {NULL};
    long ierr[XP_NUM_ERR_ATTITUDE_INIT], status;

    status = xp_attitude_init(&attitude_id, ierr);
}
```

The `XP_NUM_ERR_ATTITUDE_INIT` constant is defined in the file *explorer\_pointing.h*.

### 7.51.3 Input Parameters

The `xp_attitude_init` CFI function has no input parameters.

### 7.51.4 Output Parameters

The output parameters of the `xp_attitude_init` CFI function are:

*Table 126: Output parameters of `xp_attitude_init`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>attitude_id</code>	<code>xp_attitude_id*</code>	-	Structure that contains the Attitude.	-	-
<code>ierr</code>	<code>long</code>	-	Error vector	-	-

### 7.51.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_attitude_init` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_attitude_init` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

*Table 127: Error messages of `xp_attitude_init` function*

Error type	Error message	Cause and impact	Error code	Error No
ERR	Memory allocation error	No calculation performed	XP_CFI_ATTITUDE_INIT_MEMORY_ERR	0

## 7.52 xp\_attitude\_compute

### 7.52.1 Overview

The `xp_attitude_compute` CFI function calculates the Attitude Frame for a given S/C state vector.

Note: a correction can be applied in order to compensate the travel time of Sun light travel time. This correction is not applied with default model. To activate this correction, the Sun model in `xl_model_id` must be initialized with the enum `XL_MODEL_SUN_TRAVEL_TIME` using the function `xl_model_init` (see [LIB\_SUM]).

### 7.52.2 Calling interface

The calling interface of the `xp_attitude_compute` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    xl_model_id          model_id = {NULL};
    xl_time_id           time_id  = {NULL};
    xp_sat_nom_trans_id sat_nom_trans_id = {NULL};
    xp_sat_trans_id      sat_trans_id = {NULL};
    xp_instr_trans_id    instr_trans_id = {NULL};
    xp_attitude_id       attitude_id = {NULL};
    long time_ref, target_frame;
    double time, pos[3], vel[3], acc[3];
    long ierr[XP_NUM_ERR_ATTITUDE_COMPUTE];

    status =xp_attitude_compute(&model_id, &time_id,
                                &sat_nom_trans_id,
                                &sat_trans_id,
                                &instr_trans_id,
                                &attitude_id,
                                /* input/output */
                                &time_ref, &time, pos, vel, acc,
                                &target_frame,
                                ierr);

    /* Or, using the run_id */
    long run_id;
```

```

status = xp_attitude_compute_run(&run_id,
                                &attitude_id,
                                /* input/output */
                                &time_ref, &time, pos, vel, acc,
                                &target_frame,
                                ierr);
}

```

The `XP_NUM_ERR_ATTITUDE_COMPUTE` constant is defined in the file *explorer\_pointing.h*.

### 7.52.3 Input parameters

The `xp_attitude_compute` CFI function has the following input parameters:

**Table 128: Input parameters of `xp_attitude_compute` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
model_id	xl_model_id*	-	Model ID.	-	-
time_id	xl_time_id*	-	Structure that contains the time correlations.	-	-
sat_nom_trans_id	xp_sat_nom_trans_id*	-	Structure that contains the Sat. Nom. Trans.	-	-
sat_trans_id	xp_sat_trans_id*	-	Structure that contains the Sat. Trans.	-	-
instr_trans_id	xp_instr_trans_id*	-	Structure that contains the Instr. Trans.	-	-
attitude_id	xp_attitude_id*	-	Structure that contains the Attitude (input/output)	-	-
time_ref	long *	-	Time reference ID	-	Complete
time	double	-	Time in Processing Format	Decimal days, MJD2000	[-18262.0,36524.0]
pos[3]	double	all	Satellite position vector (Earth Fixed CS)	m	-
vel[3]	double	all	Satellite velocity vector (Earth Fixed CS)	m/s	-
acc[3]	double	all	Satellite acceleration vector (Earth Fixed CS)	m/s <sup>2</sup>	-
target_frame	long *	-	Attitude FrameID	-	Complete

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Time Reference ID: `time_ref`. See [GEN\_SUM].
- Attitude Frame ID: `attitude_frame_id`. See current document, Table 3.

## 7.52.4 Output parameters

The output parameters of the `xp_attitude_compute` CFI function are:

**Table 129: Output parameters of `xp_attitude_compute` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>attitude_id</code>	<code>xp_attitude_id*</code>	-	Structure that contains the Attitude. (input/output)	-	-
<code>ierr</code>	<code>long</code>	-	Error vector	-	-

## 7.52.5 Warnings and errors

Next table lists the possible error messages that can be returned by the `xp_attitude_compute` CFI function after translating the returned extended status flag into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xl_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained translating the extended status flag returned by the `xp_attitude_compute` function by calling the function of the EO\_POINTING software library `xl_get_code` (see [GEN\_SUM])

**Table 130: Error messages of `xp_attitude_compute` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Time Id. not initialized	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_TIME_STATUS_ERR	0
ERR	Instrument Trans. Id. not initialized	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_INSTR_TRANS_STATUS_ERR	1
ERR	Satellite Att. Trans. not initialized	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_SAT_TRANS_STATUS_ERR	2
ERR	Satellite Nom. Trans not initialized	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_SAT_NOM_TRANS_STATUS_ERR	3
ERR	Attitude Id. not initialized	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_ATTITUDE_STATUS_ERR	4
ERR	Wrong input time reference	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_WRONG_TIME	5



			_REF_ERR	
ERR	Attitude Id is being used by another Id.	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_BEING_USED_ERR	6
ERR	Could not compute orbit reference frame	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_ORB_REF_ERR	7
ERR	Could not calculate AOCS parametes	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_AOCS_CALC_ERR	8
ERR	Could not compute Sat. Nom. Trans frame	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_SAT_NOM_TRANS_ERR	9
ERR	"Could not calculate the true latitude"	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_TRUE_LAT_ERR	10
ERR	Could not calculate harmonic angles	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_HARMONIC_CALC_ERR	11
ERR	Could not compute Sat.Trans. frame	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_SAT_TRANS_ERR	12
ERR	Error computing direction cosine matrix from Sat. Att. to BJ2000	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_ATT_TO_J2000_ERR	13
ERR	Could not compute Instrument Trans. frame	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_INSTR_TRANS_ERR	14
ERR	Memory allocation error	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_MEMORY_ERR	15
ERR	Both input targets are the same	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_SAME_TARGETS_ERR	16
ERR	Error occured during call to XP_Vec_Find	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_VEC_FIND_ERR	17
ERR	Error occured during call to XP_Create_Base	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_CREATE_BASE_ERR	18
ERR	Error occured trying to get the interpolated value for the quaternions/angles	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_ATT_FILE_INTER_ERR	19
ERR	Error in a change of coordinate frame	No calculation performed	XP_CFI_ATTITUDE_COMPUTE_CHANGE_CS_ERR	20
WARN	Warning raised by XP_Vec_Find	Calculation performed	XP_CFI_ATTITUDE_COMPUTE_VEC_FIND_WARN	21

ERR	Error computing Sun position	No calculation performed	XP_ATTITUDE_COMPUT E_SUN_ERR	22
ERR	Error in a change of time system	No calculation performed	XP_ATTITUDE_COMPUT E_CHANGE_TIME_ERR	23

## 7.53 xp\_attitude\_user\_set

### 7.53.1 Overview

The `xp_attitude_user_set` CFI function assigns a user defined Attitude Frame to the *attitude Id*. Input matrix is checked to be orthonormal.

#### Note on matrix notation:

If XYZ are the axes of the original reference frame, and X'Y'Z' are the axes of the rotated frame, the rows of the rotation matrix are respectively X, Y and Z axes expressed in X'Y'Z' system.

In the C representation, `M[0][i]`, `M[1][i]`, `M[2][i]` are respectively 1st, and and 3rd row of a rotation matrix M.

The rotation matrix M satisfies the following equivalence:

$$\mathbf{V} = \mathbf{M} * \mathbf{V}'$$

where  $\mathbf{V}'$  is a vector expressed in the X'Y'Z' reference system and  $\mathbf{V}$  is expressed in the XYZ reference system.

### 7.53.2 Calling interface

The calling interface of the `xp_attitude_user_set` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    xl_model_id          model_id = {NULL};
    xl_time_id           time_id  = {NULL};
    xp_attitude_id      attitude_id = {NULL};
    long time_ref, target_frame;
    double time, pos[3], vel[3], acc[3];
    double matrix[3][3];
    double matrix_rate[3][3];
    double matrix_rate_rate[3][3];
    double offset[3],;
    long ierr[XP_NUM_ERR_ATTITUDE_USER_SET];

    long xp_attitude_user_set(&model_id, &time_id,
                             &attitude_id,
                             /* input / output */
                             &time_ref, &time, pos, vel, acc,
                             &target_frame,
                             matrix, matrix_rate, matrix_rate_rate,
                             offset,
                             ierr);
}
```

```

/* Or, using the run_id */
long run_id;

long xp_attitude_user_set_run(&run_id,
                              &attitude_id,
                              /* input / output */
                              &time_ref, &time, pos, vel, acc,
                              &target_frame,
                              matrix, matrix_rate, matrix_rate_rate,
                              offset, ierr);
}

```

The `XP_NUM_ERR_ATTITUDE_USER_SET` constant is defined in the file *explorer\_pointing.h*.

### 7.53.3 Input parameters

The `xp_attitude_user_set` CFI function has the following input parameters:

**Table 131: Input parameters of `xp_attitude_user_set` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
model_id	xl_model_id*	-	Model ID	-	-
time_id	xl_time_id*	-	Structure that contains the time correlations.	-	-
attitude_id	xp_attitude_id*	-	Structure that contains the Attitude (input/output)	-	-
time_ref	long *	-	Time reference ID	-	Complete
time	double	-	Time in Processing Format	Decimal days, MJD2000	[-18262.0,36524.0]
pos[3]	double	all	Satellite position vector (Earth Fixed CS)	m	-
vel[3]	double	all	Satellite velocity vector (Earth Fixed CS)	m/s	-
acc[3]	double	all	Satellite acceleration vector (Earth Fixed CS)	m/s <sup>2</sup>	-
target_frame	long *	-	Attitude FrameID	-	Complete
matrix[3][3]	double	all	Matrix representing the transformation from ToD to target_frame	-	-

matrix_rate [3][3]	double	all	Matrix representing the transformation rate from ToD to target_frame	-	-
matrix_rate_rate [3][3]	double	all	Matrix representing the transformation rate rate from ToD to target_frame	-	-
offset[3]	double	all	Offset in the instrument frame origin	m	-

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Time Reference ID: time\_ref. See [GEN\_SUM].
- Attitude Frame ID: attitude\_frame\_id. See current document, Table 3.

### 7.53.4 Output parameters

The output parameters of the `xp_attitude_user_set` CFI function are:

**Table 132: Output parameters of `xp_attitude_user_set` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
attitude_id	xp_attitude_id*	-	Structure that contains the Attitude. (input/output)	-	-
ierr	long	-	Error vector	-	-

### 7.53.5 Warnings and errors

Next table lists the possible error messages that can be returned by the `xp_attitude_user_set` CFI function after translating the returned extended status flag into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xl_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained translating the extended status flag returned by the `xp_attitude_user_set` function by calling the function of the EO\_POINTING software library `xl_get_code` (see [GEN\_SUM]).

**Table 133: Error messages of `xp_attitude_user_set` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Time Id. not initialized	No calculation performed	XP_CFI_ATTITUDE_USER_SET_TIME_STATUS_ERR	0
ERR	Wrong input target frame	No calculation performed	XP_CFI_ATTITUDE_US	1

			ER_SET_WRONG_TARGET_FRAME_ERR	
ERR	Attitude Id. not initialized	No calculation performed	XP_CFI_ATTITUDE_USER_SET_ATTITUDE_STATUS_ERR	2
ERR	Attitude Id is being used by another Id	No calculation performed	XP_CFI_ATTITUDE_USER_SET_BEING_USED_ERR	3
ERR	Could not compute orbit reference frame	No calculation performed	XP_CFI_ATTITUDE_USER_SET_ORB_REF_ERR	4
ERR	Memory allocation error	No calculation performed	XP_CFI_ATTITUDE_USER_SET_MEMORY_ERR	5
ERR	Matrix is not orthonormal	No calculation performed. The CFI performs a check, with a tolerance of $10^{-6}$ , that the product of the input matrix and its transposed is the unitary matrix.	XP_CFI_ATTITUDE_USER_SET_MATRIX_ORTHONORMAL_ERR,	6

## 7.54 xp\_get\_attitude\_data

### 7.54.1 Overview

The `xp_get_attitude_data` CFI function computes the quaternions or attitude angles (roll, pitch, yaw) that define the rotation between two reference frames:

- A source reference frame (given as input).
- The attitude reference frame given by the input `attitude_id`. Note that the `attitude_id` has to be previously computed using the functions `xp_attitude_compute` or `xp_attitude_user_set`.

### 7.54.2 Calling interface

The calling interface of the `xp_get_attitude_data` CFI function is the following (input parameters are underlined>):

```
#include <explorer_pointing.h>
{
    xp_attitude_id      attitude_id = {NULL};
    long data_type;
    long source_ref_type;
    long source_ref;
    xd_att_rec att_rec;
    long ierr[XP_NUM_ERR_GET_ATTITUDE_DATA];
    long xp_get_attitude_data(&attitude_id,
                             &data_type,
                             &source_ref_type,
                             &source_ref,
                             /* output */
                             &att_rec,
                             ierr);
}
```

The `XP_NUM_ERR_GET_ATTITUDE_DATA` constant is defined in the file *explorer\_pointing.h*.

### 7.54.3 Input parameters

The `xp_get_attitude_data` CFI function has the following input parameters:

**Table 134: Input parameters of `xp_get_attitude_data` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>attitude_id</code>	<code>xp_attitude_id*</code>	-	Structure that contains the Attitude	-	-

data_type	long	-	Requested data type: angles or quaternions.	-	XD_ATT_QUATERNIONS XD_ATT_ANGLES
source_ref_type	long	-	Source reference type: External or Satellite.	-	XP_FRAME_FLAG_EXT XP_FRAME_FLAG_SAT
source_ref	long	-	Source reference CS	-	XL_BM2000, XL_HM2000, XL_GM2000, XL_MOD, XL_TOD, XL_PEF, XL_EF XL_LIF, XL_GALACTIC, XL_SAT_ORBITAL_REF, XL_SAT_NOMINAL_ATT, XL_SAT_ATT, XL_INSTR_ATT

It is possible to use enumeration values rather than integer values for some of the input arguments:

- data\_type: See XD\_Attitude\_data\_type\_enum [D\_H\_SUM].
- source\_ref\_type: See enumeration XP\_Frame\_flag\_enum in current document (Table 3).
- source\_ref: See enumeration XL\_CS\_rl\_enum and XL\_Attitude\_fr\_enum in [LIB\_SUM].

### 7.54.4 Output parameters

The output parameters of the `xp_get_attitude_data` CFI function are:

*Table 135: Output parameters of xp\_get\_attitude\_data function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
att_rec	xd_att_rec	-	Structure containing the attitude angles/quaternions	-	-
ierr	long	-	Error vector	-	-

### 7.54.5 Warnings and errors

Next table lists the possible error messages that can be returned by the `xp_get_attitude_data` CFI function after translating the returned extended status flag into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.



The table is completed by the error code and value. These error codes can be obtained translating the extended status flag returned by the `xp_get_attitude_data` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 136: Error messages of `xp_get_attitude_data` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Wrong input satellite source frame	No calculation performed	XP_CFI_GET_ATT_DATA_WRONG_SAT_CS_ERR	0
ERR	Wrong input external source frame	No calculation performed	XP_CFI_GET_ATT_DATA_WRONG_EXT_CS_ERR	1
ERR	Wrong input source frame type. Should be external or satellite	No calculation performed	XP_CFI_GET_ATT_DATA_WRONG_FRAME_ERR	2
ERR	Error getting attitude data from input attitude Id.	No calculation performed	XP_CFI_GET_ATT_DATA_GET_ATT_DATA_ERR	3
ERR	Error computing rotation matrix	No calculation performed	XP_CFI_GET_ATT_DATA_GET_ROTATION_MATRIX_ERR, ERR	4
ERR	Error in attitude initialization	No calculation performed	XP_CFI_GET_ATT_DATA_GET_ATT_INIT_ERR	5
ERR	Error in attitude compute	No calculation performed	XP_CFI_GET_ATT_DATA_GET_ATT_COMPUTE_ERR	6
ERR	Error in matrix inversion	No calculation performed	XP_CFI_GET_ATT_DATA_MATRIX_INV_ERR	7
ERR	Could not close the attitude id.	No calculation performed	XP_CFI_GET_ATT_DATA_CLOSE_ATT_ERR	8
ERR	Could not compute the Euler angles	No calculation performed	XP_CFI_GET_ATT_DATA_ANGLE_COMP_ERR	9
ERR	Could not compute the quaternions	No calculation performed	(XP_CFI_GET_ATT_DATA_QUAT_COMP_ERR	10

## 7.55 xp\_gen\_attitude\_data

### 7.55.1 Overview

The `xp_gen_attitude_data` function computes a list of quaternions or attitude angles (roll, pitch, yaw) at an interval given by the user (with a regular time separation) that define the rotation between two reference frames:

- A source reference frame (given as input).
- The attitude frame given by the input attitude definition file.

### 7.55.2 Calling interface

The calling interface of the `xp_gen_attitude_data` function is the following (input parameters are underlined>):

```
#include <explorer_pointing.h>
{
    xo_orbit_id      orbit_id = {NULL};
    xp_attitude_def  att_def;
    xo_time_interval time_interval;
    double           time_step;
    long             data_type;
    long             source_ref_type;
    long             source_ref;
    xd_att_file      *att_file;
    long ierr[XP_NUM_ERR_GEN_ATTITUDE_DATA];

    long xp_gen_attitude_data(&orbit_id,
                             &att_def,
                             &time_interval,
                             &time_step,
                             &data_type,
                             &source_ref_type,
                             &source_ref,
                             /* output */
                             &att_file,
                             ierr);

    /* Or, using the run_id */
    long run_id;
    long xp_gen_attitude_data_run(&run_id,
                                  &time_interval,
```

```

    &time_step,
    &data_type,
    &source_ref_type,
    &source_ref,
    /* output */
    &att_file,
    ierr);
  }

```

The `XP_NUM_ERR_GEN_ATTITUDE_DATA` constant is defined in the file `explorer_pointing.h`.

### 7.55.3 Input parameters

The `xp_gen_attitude_data` CFI function has the following input parameters:

**Table 137: Input parameters of `xp_gen_attitude_data` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
orbit_id	xp_orbit_id*	-	Structure that contains the satellite orbit data	-	-
att_def	xp_attitude_def*	-	Structure defining the attitude frames. It also defines the destination frame.	-	-
time_interval	xo_time_interval*	-	start-stop time interval for the data generation	-	-
time_step	double*	-	Time step between records in the output file data.	seconds	-
data_type	long	-	Requested data type: angles or quaternions.	-	XD_ATT_QUATERNIONS XD_ATT_ANGLES
source_ref_type	long	-	Source reference type: External or Satellite.	-	XP_FRAME_FLAG_EXT XP_FRAME_FLAG_SAT
source_ref	long	-	Source reference CS	-	XL_BM2000, XL_HM2000, XL_GM2000, XL_MOD, XL_TOD, XL_PEF, XL_EF XL_LIF, XL_GALACTIC,

					XL_SAT_ORBITAL_REF, XL_SAT_NOMINAL_ATT, XL_SAT_ATT, XL_INSTR_ATT
--	--	--	--	--	---

It is possible to use enumeration values rather than integer values for some of the input arguments:

- data\_type: See XD\_Attitude\_data\_type\_enum [D\_H\_SUM].
- source\_ref\_type: See enumeration XP\_Frame\_flag\_enum in current document (Table 139).
- source\_ref: See enumeration XL\_CS\_rl\_enum and XL\_Attitude\_fr\_enum in [LIB\_SUM].

### 7.55.4 Output parameters

The output parameters of the `xp_gen_attitude_data` CFI function are:

**Table 138: Output parameters of `xp_gen_attitude_data` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
att_file	xd_att_file	-	Structure containing the list of attitude angles/quaternions	-	-
ierr	long	-	Error vector	-	-

### 7.55.5 Warnings and errors

Next table lists the possible error messages that can be returned by the `xp_gen_attitude_data` CFI function after translating the returned extended status flag into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained translating the extended status flag returned by the `xp_gen_attitude_data` function by calling the function of the EO\_POINTING software library `xp_gen_code` (see [GEN\_SUM]).

**Table 139: Error messages of `xp_gen_attitude_data` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Wrong input orbit Id. It is not initialized	No calculation performed	XP_CFI_GEN_ATT_DATA_ORBIT_INIT_ERR	0
ERR	Error in attitude initialization	No calculation performed	XP_CFI_GEN_ATT_DATA_ATT_INIT_ERR	1
ERR	Wrong input attitude	No calculation performed	XP_CFI_GEN_ATT_DATA	2

	definition structure: Attitude type has a wrong value		_ATT_TARGET_TYPE_ERR	
ERR	Wrong input attitude definition structure: Instrument attitude is not initialized	No calculation performed	XP_CFI_GEN_ATT_DATA_INSTR_ATT_ERR	3
ERR	Wrong input attitude definition structure: Satellite attitude is not initialized	No calculation performed	XP_CFI_GEN_ATT_DATA_SAT_ATT_ERR	4
ERR	Wrong input attitude definition structure: Satellite nominal attitude is not initialized	No calculation performed	XP_CFI_GEN_ATT_DATA_SAT_NOM_ATT_ERR	5
ERR	Could not compute the start interval UTC time	No calculation performed	XP_CFI_GEN_ATT_DATA_START_INTERVAL_ERR	6
ERR	Could not compute the stop interval UTC time	No calculation performed	XP_CFI_GEN_ATT_DATA_STOP_INTERVAL_ERR	7
ERR	Wrong input time step. It cannot be negative	No calculation performed	XP_CFI_GEN_ATT_DATA_TIME_STEP_ERR	8
ERR	Wrong input data type. It should be quaternions or angles	No calculation performed	XP_CFI_GEN_ATT_DATA_DATA_TYPE_ERR	9
ERR	Wrong input satellite source frame	No calculation performed	XP_CFI_GEN_ATT_DATA_SAT_CS_ERR	10
ERR	Wrong input external source frame	No calculation performed	XP_CFI_GEN_ATT_DATA_EXTERNAL_CS_ERR	11
ERR	Wrong input source frame type. Should be external or satellite	No calculation performed	XP_CFI_GEN_ATT_DATA_CS_TYPE_ERR	12
ERR	Memory allocation error	No calculation performed	XP_CFI_GEN_ATT_DATA_MEM_ALLOC_ERR	13
ERR	Error computing the satellite state vector	No calculation performed	XP_CFI_GEN_ATT_DATA_OSV_COMP_ERR	14
ERR	Error in attitude compute	No calculation performed	XP_CFI_GEN_ATT_DATA_ATT_COMP_ERR	15
ERR	Could not compute the attitude data	No calculation performed	XP_CFI_GEN_ATT_DATA_GET_ATT_DATA_ERR	16

## 7.56 xp\_gen\_attitude\_file

### 7.56.1 Overview

The `xp_gen_attitude_file` function creates an attitude file with the list of quaternions or attitude angles (roll, pitch, yaw) at an interval given by the user (with a regular time separation) that define the rotation between two reference frames:

- A source reference frame (given as input).
- The attitude frame given by the input attitude definition file.

### 7.56.2 Calling interface

The calling interface of the `xp_gen_attitude_file` function is the following (input parameters are underlined>):

```
#include <explorer_pointing.h>
{
    xo_orbit_id      orbit_id = {NULL};
    xp_attitude_def att_def;
    xo_time_interval time_interval;
    double           time_step;
    long             data_type;
    long             source_ref_type;
    long             source_ref;
    char             *output_dir,
    char             *file_class,
    long             *version_number,
    char             *fh_system,
    char             filename[XD_MAX_STR],
    long ierr[XP_NUM_ERR_GEN_ATTITUDE_FILE];

    long xp_gen_attitude_file(&orbit_id,
                             &att_def,
                             &time_interval,
                             &time_step,
                             &data_type,
                             &source_ref_type,
                             &source_ref,
                             output_dir,
                             file_class,
                             &version_number,
                             fh_system,
```

```

        /* input/output */
        filename,
        ierr);

/* Or, using the run_id */
long run_id;
long xp_gen_attitude_data_run(&run_id,
                              &time_interval,
                              &time_step,
                              &data_type,
                              &source_ref_type,
                              &source_ref,
                              output_dir,
                              file_class,
                              &version_number,
                              fh_system,
                              /* input/output */
                              filename,
                              ierr);
}

```

The `XP_NUM_ERR_GEN_ATTITUDE_FILE` constant is defined in the file *explorer\_pointing.h*.

### 7.56.3 Input parameters

The `xp_gen_attitude_file` CFI function has the following input parameters:

**Table 140: Input parameters of `xp_gen_attitude_file` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
orbit_id	xp_orbit_id*	-	Structure that contains the satellite orbit data	-	-
att_def	xp_attitude_def*	-	Structure defining the attitude frames. It also defines the destination frame.	-	-
time_interval	xo_time_interval*	-	start-stop time interval for the data generation	-	-
time_step	double*	-	Time step between records in the output file data.	seconds	-
data_type	long	-	Requested data type:	-	XD_ATT_QUATERNIONS

			angles or quaternions.		XD_ATT_ANGLES
source_ref_type	long	-	Source reference type: External or Satellite.	-	XP_FRAME_FLAG_EXT XP_FRAME_FLAG_SAT
source_ref	long	-	Source reference CS	-	XL_BM2000, XL_HM2000, XL_GM2000, XL_MOD, XL_TOD, XL_PEF, XL_EF XL_LIF, XL_GALACTIC, XL_SAT_ORBITAL_REF, XL_SAT_NOMINAL_ATT, XL_SAT_ATT, XL_INSTR_ATT
output_dir	char	-	Directory for the output file. If empty, the current directory is chosen.	-	-
file_class	char	-	File class	-	-
version_number	long	-	File version	-	-
fh_system	char	-	system	-	-
filename	char	-	Output file name. If empty, the file is generated automatically and returned to this variable.	-	-

It is possible to use enumeration values rather than integer values for some of the input arguments:

- data\_type: See XD\_Attitude\_data\_type\_enum [D\_H\_SUM].
- source\_ref\_type: See enumeration XP\_Frame\_flag\_enum in current document (Table 142).
- source\_ref: See enumeration XL\_CS\_rl\_enum and XL\_Attitude\_fr\_enum in [LIB\_SUM].

### 7.56.4 Output parameters

The output parameters of the `xp_gen_attitude_file` CFI function are:

**Table 141: Output parameters of `xp_gen_attitude_file` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
ierr	long	-	Error vector	-	-



### 7.56.5 Warnings and errors

Next table lists the possible error messages that can be returned by the `xp_gen_attitude_file` CFI function after translating the returned extended status flag into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained translating the extended status flag returned by the `xp_gen_attitude_file` function by calling the function of the EO\_POINTING software library `xp_gen_code` (see [GEN\_SUM]).

**Table 142: Error messages of `xp_gen_attitude_file` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Error generating attitude data	No calculation performed	XP_CFI_GEN_ATT_FILE_GENDATA_ERR	0
ERR	Could not get the Fixed header data	No calculation performed	XP_CFI_GEN_ATT_FILE_GENFHR_ERR	1
ERR	No data generated for the requested interval	No calculation performed	XP_CFI_GEN_ATT_FILE_NO_DATA_ERR	2
ERR	Memory allocation error	No calculation performed	XP_CFI_GEN_ATT_FILE_MEM_ERR	3
ERR	Error writing attitude file to disk	No calculation performed	XP_CFI_GEN_ATT_FILE_WRITE_ERR	4

### 7.56.6 Executable Program

The `gen_attitude` executable program can be called from a shell as:

```
gen_attitude
    -sat satellite_name
    -tref time_ref
    {
        -tstart start_time -tstop stop_time (decimal days) |
        -tastart start_time -tastop stop_time (CCSDSA format) |
        -ostart start_orbit -ostop stop_orbit (orbits)
    }
    -orbtyp "orbit file type"
    -orbf "orbit file name"
    -atdef "attitude definition file name"
```

```

-attyp "attitude data type, angles or quaternions"
-tstep "Time step between generated attitude records (seconds)"
-cs "source reference frame"
[-dir output_dir] (default: current directory)
[-atf output_filename] (default: name generated automatically)
[-flcl file_class] (empty string by default)
[-vers version] (version=1 by default)
[-fhsys fh_system] (empty string by default)
[-v ]
[-xd_v ]
[-xl_v ]
[-xo_v ]
[-xp_v ]
[-help ]
[-show ]
[-with_xslt ] (add xslt reference with default style sheet)
[
    (-tai TAI_time -gps GPS_time -utc UTC_time -ut1 UT1_time) |
    (-tmod time_model -tfile time_file -trid time_reference
    {(-tm0 time0 -tm1 time1) | (-orb0 orbit0 -orb1 orbit1) } )
]

```

Note that:

- Order of parameters does not matter.
- Bracketed parameters are not mandatory.
- Options between curly brackets and separated by a vertical bar are mutually exclusive.
- [ -xd\_v ] option for EXPLORER\_DATA\_HANDLING Verbose mode.
- [ -xl\_v ] option for EXPLORER\_LIB Verbose mode.
- [ -xo\_v ] option for EXPLORER\_ORBIT Verbose mode.
- [ -xp\_v ] option for EXPLORER\_POINTING Verbose mode.
- [ -v ] option for Verbose mode for all libraries (default is Silent).
- [ -show ] displays the inputs of the function and the results.
- Possible values for satellite\_name: ERS1, ERS2, ENVISAT, METOP1, METOP2, METOP3,  
 CRYOSAT, ADM, GOCE, SMOS, TERRASAR, EARTHCARE,  
 SWARM\_A, SWARM\_B, SWARM\_C,

SENTINEL\_1A, SENTINEL\_1B, SENTINEL\_1C,  
SENTINEL\_2A, SENTINEL\_2B, SENTINEL\_2C,  
SENTINEL\_3A, SENTINEL\_3B, SENTINEL\_3C,  
JASON\_CSA, JASON\_CSB,  
METOP\_SG\_A1, METOP\_SG\_A2, METOP\_SG\_A3,  
METOP\_SG\_B1, METOP\_SG\_B2, METOP\_SG\_B3,  
SENTINEL\_5P,  
BIOMASS, SENTINEL\_5, SAOCOM\_CS,  
SEOSAT, GENERIC.

- Possible values for time\_model: USER, NONE, IERS\_B\_PREDICTED,  
IERS\_B\_RESTITUTED, FOS\_PREDICTED,  
FOS\_RESTITUTED, DORIS\_PRELIMINARY, DORIS\_PRECISE,  
DORIS\_NAVIGATOR, OSF.

- Possible values for time\_ref and time\_reference: UNDEF, TAI, UTC, UT1.

- Possible values for "orbit file type": OSF, POF, DORISNAV, ROF, DORISPREM, DORISPREC.

- Possible values for "Attitude data type": ANGLES, QUATERNIONS.

- Possible values for "source reference frame": GALACTIC (= Galactic CS)

BM2000 (= Barycentric Mean of 2000.0 CS)  
HM2000 (= Heliocentric Mean of 2000.0 CS)  
GM2000 (= Geocentric Mean of 2000.0 CS)  
MOD (= Mean of Date CS)  
TOD (= True of Date CS)  
PEF (= Pseudo Earth Fixed CS)  
EF (= Earth Fixed CS)  
LIF (= Launch Inertial CS)  
ORBITAL (= Satellite orbital frame CS)  
NOM\_ATT (= Satellite nominal attitude CS)  
ATT (= Satellite attitude CS)  
INSTR (= Satellite instrument CS)

- Time references need to be initialized.

The inputs needed for this issue are provided in the last three lines of parameters. Note that only one set of parameters should be introduced:

1. TAI, GPS, UTC and UT1 input times (as in x1\_time\_ref\_init)\n");

2. A file with time reference data, the time mode, the time reference name and a time range (as in xl\_time\_ref\_init\_file)

## 7.57 **xp\_attitude\_close**

### 7.57.1 Overview

The `xp_attitude_close` CFI function cleans up any memory allocation performed by the Attitude functions.

### 7.57.2 Calling Interface

The calling interface of the `xp_attitude_close` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    xp_attitude_id attitude_id = {NULL};
    long ierr[XP_NUM_ERR_ATTITUDE_CLOSE], status;

    status = xp_attitude_close(&attitude_id, ierr);
}
```

The `XP_NUM_ERR_ATTITUDE_CLOSE` constant is defined in the file *explorer\_pointing.h*.

### 7.57.3 Input Parameters

The `xp_attitude_close` CFI function has the following input parameters:

*Table 143: Input parameters of xp\_attitude\_close function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
attitude_id	xp_attitude_id *	-	Structure that contains the Attitude.	-	-

### 7.57.4 Output Parameters

The output parameters of the `xp_attitude_close` CFI function are:

*Table 144: Output parameters of xp\_attitude\_close*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
ierr	long	-	Error vector	-	-

### 7.57.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_attitude_close` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_attitude_close` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

*Table 145: Error messages of xp\_attitude\_close function*

Error type	Error message	Cause and impact	Error code	Error No
ERR	Could not close Attitude Id. The Attitude Id. is not initialized or it is being used	No calculation performed	XP_CFI_ATTITUDE_CLOSE_WRONG_ID_ERR	0

## 7.58 xp\_attitude\_get\_id\_data

### 7.58.1 Overview

The `xp_attitude_get_id_data` CFI function returns attitude initialization data.

### 7.58.2 Calling interface

The calling interface of the `xp_attitude_get_id_data` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    xp_attitude_id attitude_id;
    long status;
    xp_attitude_id_data data;
    status = xp_attitude_get_id_data (&attitude_id,
                                     &data);
}
```

### 7.58.3 Input parameters

The `xp_attitude_get_id_data` CFI function has the following input parameters:

*Table 146: Input parameters of xp\_attitude\_get\_id\_data function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
attitude_id	xp_attitude_id *	-	Structure that contains the Attitude.	-	-

### 7.58.4 Output parameters

The output parameters of the `xp_attitude_get_id_data` CFI function are:

*Table 147: Output parameters of xp\_attitude\_get\_id\_data function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xp_attitude_get_id_data	long	-	Status flag	-	-
data	xp_attitude_id_data	-	Attitude initialization data	-	-

### **7.58.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The attitude\_id was not initialised.
- The attitude\_id initialization does not allow the use of this function.



## 7.59 xp\_attitude\_set\_id\_data

### 7.59.1 Overview

The `xp_attitude_set_id_data` CFI function changes the harmonic data used for the satellite attitude initialization. Input matrix is checked to be orthonormal.

### 7.59.2 Calling interface

The calling interface of the `xp_attitude_set_id_data` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    xp_attitude_id attitude_id;
    long status;
    xp_attitude_id_data data;
    status = xp_attitude_set_id_data (&attitude_id,
                                     &data);
}
```

### 7.59.3 Input parameters

The `xp_attitude_set_id_data` CFI function has the following input parameters:

**Table 148: Input parameters of xp\_attitude\_set\_id\_data function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
attitude_id	xp_attitude_id *	-	Structure that contains the Attitude (input / output parameter)	-	-
data	xp_attitude_id_data	-	Attitude initialization data	-	-

### 7.59.4 Output parameters

The output parameters of the `xp_attitude_set_id_data` CFI function are:

**Table 149: Output parameters of xp\_attitude\_set\_id\_data function**

C name	C type	Array	Description	Unit	Allowed Range
--------	--------	-------	-------------	------	---------------

		Element	(Reference)	(Format)	
xp_attitude_set_id_data	long	-	Status flag	-	-
attitude_id	xp_attitude_id *	-	Structure that contains the Attitude. (input / output parameter)	-	-

### **7.59.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The attitude\_id was not initialised.
- The attitude\_id initialization does not allow the use of this function.

## 7.60 xp\_attitude\_get\_model\_id

### 7.60.1 Overview

The `xp_attitude_get_model_id` CFI function retrieves the model ID from the input attitude ID.

### 7.60.2 Calling interface

The calling interface of the `xp_attitude_get_model_id` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    xp_attitude_id attitude_id = {NULL};
    xl_model_id model_id;
    model_id = xp_attitude_get_model_id (&attitude_id);
}
```

### 7.60.3 Input parameters

The `xp_attitude_get_model_id` CFI function has the following input parameters:

*Table 150: Input parameters of xp\_attitude\_get\_model\_id function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
attitude_id	xp_attitude_id *	-	Structure that contains the attitude	-	-

### 7.60.4 Output parameters

The output parameters of the `xp_attitude_get_model_id` CFI function are:

*Table 151: Output parameters of xp\_attitude\_get\_model\_id function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xp_attitude_get_model_id	long	-	Status flag	-	-

### 7.60.5 Warnings and errors

This function does not return any error/warning code. If there is an error, then the returned model ID will be set to NULL (no initialised)

The possible causes of error are:

- The `attitude_id` was not initialised.



## 7.61 xp\_change\_frame

### 7.61.1 Overview

The `xp_change_frame` CFI function changes the coordinate or attitude frame of a location or direction by keeping the location or direction in inertial space identical. Both all coordinate frames and all attitude frames are supported.

When changing the frame for a location (`mode_flag = XP_MODE_FLAG_LOCATION`), the difference between the frame origins is taken into account.

When changing the frame for a direction (`mode_flag = XP_MODE_FLAG_DIRECTION`), the output of the function is a direction, that does not depend on the origin of reference frame of the input vector. Therefore, in this specific case, the instrument offsets are not taken into account.

### 7.61.2 Calling interface

The calling interface of the `xp_change_frame` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    xl_model_id model_id = {NULL};
    long sat_id, mode_flag, frame_flag_in, frame_id_in,
        frame_flag_out, frame_id_out, time_ref;
    xl_time_id time_id = {NULL};
    xp_sat_nom_trans_id sat_nom_trans_id = {NULL};
    xp_sat_trans_id sat_trans_id = {NULL};
    xp_instr_trans_id instr_trans_id = {NULL};
    double time;
    double pos[3], vel[3], acc[3];
    long deriv;
    double vec_in[3], vec_rate_in[3], vec_rate_rate_in[3];
    double vec_out[3], vec_rate_out[3], vec_rate_rate_out[3];
    long ierr[XP_NUM_ERR_CHANGE_FRAME], status;
    status = xp_change_frame (&sat_id, &model_id,
        &time_id,
        &sat_nom_trans_id,
        &sat_trans_id,
        &instr_trans_id,
        &mode_flag,
```

```
&frame_flag_in, &frame_id_in,  
&frame_flag_out, &frame_id_out,  
&time_ref, &time,  
pos, vel, acc, &deriv,  
vec_in, vec_rate_in, vec_rate_rate_in,  
vec_out, vec_rate_out, vec_rate_rate_out,  
ierr);  
  
/* Or, using the run_id */  
long run_id;  
  
status = xp_change_frame_run (&run_id,  
                               &mode_flag,  
                               &frame_flag_in, &frame_id_in,  
                               &frame_flag_out, &frame_id_out,  
                               &time_ref, &time,  
                               pos, vel, acc, &deriv,  
                               vec_in, vec_rate_in, vec_rate_rate_in,  
                               vec_out, vec_rate_out, vec_rate_rate_out,  
                               ierr);  
  
}
```

The `XP_NUM_ERR_CHANGE_FRAME` constant is defined in the file *explorer\_pointing.h*.

### 7.61.3 Input parameters

The `xp_change_frame` CFI function has the following input parameters:

**Table 152: Input parameters of `xp_change_frame` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>sat_id</code>	<code>long *</code>	-	Satellite ID	-	Complete
<code>model_id</code>	<code>xl_model_id*</code>	-	Model ID	-	-
<code>time_id</code>	<code>xl_time_id*</code>	-	Structure that contains the time correlations.	-	-
<code>sat_nom_trans_id</code>	<code>xp_sat_nom_trans_id*</code>	-	Structure that contains the Sat. Nom. Trans.	-	-
<code>sat_trans_id</code>	<code>xp_sat_trans_id*</code>	-	Structure that contains the Sat. Trans.	-	-
<code>instr_trans_id</code>	<code>xp_instr_trans_id*</code>	-	Structure that contains the Instr. Trans.	-	-
<code>mode_flag</code>	<code>long *</code>	-	Selection of location or direction calculus		Complete
<code>frame_flag_in</code>	<code>long *</code>	-	Selection of Coordinate or Attitude Frame on input		Complete
<code>frame_id_in</code>	<code>long *</code>		Coordinate Frame id or Attitude Frame id on input		Complete
<code>frame_flag_out</code>	<code>long *</code>	-	Selection of Coordinate or Attitude Frame on output		Complete
<code>frame_id_out</code>	<code>long *</code>		Coordinate Frame id or Attitude Frame id on output		Complete
<code>time_ref</code>	<code>long *</code>	-	Time reference ID	-	Complete
<code>time</code>	<code>double</code>	-	Time in Processing Format	Decimal days, MJD2000	[-18262.0,36524.0]
<code>pos[3]</code>	<code>double</code>	all	Satellite position vector (Earth Fixed CS)	m	-
<code>vel[3]</code>	<code>double</code>	all	Satellite velocity vector (Earth Fixed CS)	m/s	-
<code>acc[3]</code>	<code>double</code>	all	Satellite acceleration vector (Earth Fixed CS)	m/s <sup>2</sup>	-
<code>deriv</code>	<code>long *</code>	-	Derivative ID	-	Allowed values: (0) XP_NO_DER (1) XP_DER_1ST (2) XP_DER_2ND
<code>vec_in[3]</code>	<code>double</code>	all	Position (direction) vector	m or -	-

			(Frame in)		
vec_rate_in[3]	double	all	Velocity (direction) vector (Frame in)	m/s or 1/s	-
vec_rate_rate_in[3]	double	all	Acceleration (direction) vector (Frame in)	m/s <sup>2</sup> or 1/s <sup>2</sup>	-

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Time Reference ID: time\_ref. See [GEN\_SUM].
- Selection of location or direction calculus: mode\_flag. See current document, Table 3.
- Selection of Coordinate or Attitude Frame: frame\_flag. See current document, Table 3.

### 7.61.4 Output parameters

The output parameters of the `xp_change_frame` CFI function are

**Table 153: Output parameters of `xp_change_frame` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
vec_out[3]	double	all	Position (direction) vector (Frame out)	m or -	-
vec_rate_out[3]	double	all	Velocity (direction) vector (Frame out)	m/s or 1/s	-
vec_rate_rate_out[3]	double	all	Acceleration (direction) vector (Frame out)	m/s <sup>2</sup> or 1/s <sup>2</sup>	-
ierr	long	-	Error vector	-	-

### 7.61.5 Warnings and errors

Next table lists the possible error messages that can be returned by the `xp_change_frame` CFI function after translating the returned extended status flag into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained translating the extended status flag returned by the `xp_change_frame` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 154: Error messages of `xp_change_frame` function**

Error type	Error message	Cause and impact	Error code	Error No
------------	---------------	------------------	------------	----------



ERR	Could not initialize the attitude	No calculation performed	XP_CHANGE_FRAME_ATTITUDE_INIT_ERR	0
ERR	Frame input flag is not correct	No calculation performed	XP_CHANGE_FRAME_INPUT_FRAME_ERR	1
ERR	Frame output flag is not correct	No calculation performed	XP_CHANGE_FRAME_OUTPUT_FRAME_ERR	2
ERR	Error calling xl_change_cart_cs	No calculation performed	XP_CHANGE_FRAME_CHANGE_CART_CS_ERR	3
ERR	Could not compute the attitude	No calculation performed	XP_CHANGE_FRAME_ATTITUDE_COMP_ERR	4
ERR	The Attitude Id could not be closed	No calculation performed	XP_CHANGE_FRAME_ATTITUDE_CLOSE_ERR	5

## 7.62 xp\_atmos\_init

### 7.62.1 Overview

The `xp_atmos_init` CFI function initialises the atmospheric model for a given satellite. The initialised values will be stored in the `atmos_id` output structure.

### 7.62.2 Calling Interface

The calling interface of the `xp_atmos_init` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long atmos_mode, atmos_model;
    char atmos_file[XL_MAX_STR];
    xp_atmos_id atmos_id = {NULL};
    long ierr[XP_NUM_ERR_ATMOS_INIT], status;

    status = xp_atmos_init(&atmos_mode, &atmos_model, atmos_file,
                          &atmos_id, ierr);
}
```

The `XP_NUM_ERR_ATMOS_INIT` constant is defined in the file `explorer_pointing.h`.

### 7.62.3 Input Parameters

The `xp_atmos_init` CFI function has the following input parameters:

*Table 155: Input parameters of `xp_atmos_init` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>atmos_mode</code>	<code>long *</code>	-	Atmosphere initialization mode	-	Complete
<code>atmos_model</code>	<code>long *</code>	-	Not Used in the current implementation.	-	-
<code>atmos_file</code>	<code>char[]</code>	-	File used for atmosphere initialization. It is required when the input <code>atmos_mode</code> is: - User initialization mode (n-z table, see section 10) - User LUT mode	-	Complete

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Atmosphere Initialization Mode: `atmos_mode`. See current document, Table 3 .

### 7.62.4 Output Parameters

The output parameters of the `xp_atmos_init` CFI function are:

*Table 156: Output parameters of `xp_atmos_init`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>atmos_id</code>	<code>xp_atmos_id*</code>	-	Structure that contains the atmosphere initialization.	-	-
<code>ierr</code>	<code>long</code>	-	Error vector	-	-

### 7.62.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_atmos_init` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_atmos_init` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 157: Error messages of `xp_atmos_init` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Atmosphere Mode ID is not correct	No calculation performed	XP_CFI_ATMOS_INIT_MODE_ID_ERR	0
ERR	Atmosphere Model ID is not correct	No calculation performed	XP_CFI_ATMOS_INIT_MODEL_ID_ERR	1
ERR	Atmosphere initialization file could not be opened	No calculation performed	XP_CFI_ATMOS_INIT_FILE_NOT_OPEN_ERR	2
ERR	Unable to store atmosphere initialization file (not enough memory)	No calculation performed	XP_CFI_ATMOS_INIT_MEMORY_ERR	3
ERR	Error while reading atmosphere initialization file	No calculation performed	XP_CFI_ATMOS_INIT_FILE_READING_ERR	4

## 7.63 xp\_atmos\_close

### 7.63.1 Overview

The `xp_atmos_close` CFI function cleans up any memory allocation performed by the `xp_atmos_init` functions.

### 7.63.2 Calling Interface

The calling interface of the `xp_atmos_close` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    xp_atmos_id atmos_id = {NULL};
    long ierr[XP_NUM_ERR_ATMOS_CLOSE], status;

    status = xp_atmos_close(&atmos_id, ierr);
}
```

The `XP_NUM_ERR_ATMOS_CLOSE` constant is defined in the file *explorer\_pointing.h*.

### 7.63.3 Input Parameters

The `xp_atmos_close` CFI function has the following input parameters:

*Table 158: Input parameters of `xp_atmos_close` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>atmos_id</code>	<code>xp_atmos_id*</code>	-	Structure that contains the atmosphere initialization.	-	-

### 7.63.4 Output Parameters

The output parameters of the `xp_atmos_close` CFI function are:

*Table 159: Output parameters of `xp_atmos_close`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>ierr</code>	<code>long</code>	-	Error vector	-	-

### 7.63.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_atmos_close` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_atmos_close` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

*Table 160: Error messages of `xp_atmos_close` function*

Error type	Error message	Cause and impact	Error code	Error No
ERR	Could not close the Atmos. Id. as it is not initialized or it is being used	No calculation performed	XP_CFI_ATMOS_CLOSE_WRONG_ID_ERR	0



## 7.64 xp\_atmos\_get\_id\_data

### 7.64.1 Overview

The `xp_atmos_get_id_data` CFI function returns atmospheric initialization data.

### 7.64.2 Calling interface

The calling interface of the `xp_atmos_get_id_data` CFI function is the following (input parameters are underlined):

```
#include <explorer_lib.h>
{
    xp_atmos_id atmos_id;
    long status;
    xp_atmos_id_data data;
    status = xp_atmos_get_id_data (&atmos_id, &data);
}
```

### 7.64.3 Input parameters

The `xp_atmos_get_id_data` CFI function has the following input parameters:

*Table 161: Input parameters of xp\_atmos\_get\_id\_data function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
atmos_id	xp_atmos_id *	-	Atmospheric Id.	-	-

### 7.64.4 Output parameters

The output parameters of the `xp_atmos_get_id_data` CFI function are:

*Table 162: Output parameters of xp\_atmos\_get\_id\_data function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xp_atmos_get_id_data	long	-	Status flag	-	-
data	xp_atmos_id_data	-	Atmospheric initialization data	-	-



### **7.64.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The `atmos_id` was not initialised.

## 7.65 xp\_dem\_init

### 7.65.1 Overview

The `xp_dem_init` CFI function initializes the digital elevation model (DEM). The DEM is initialized using the DEM configuration file (see [D\_H\_SUM]) which contains some characteristics that can be configured. Note however that the DEM version (1 or 2) is automatically detected (See [MCD] for further details about the DEM models).

Finally the initialisation values will be stored in the `dem_id` output structure.

### 7.65.2 Location of DEM dataset

The DEM files are looked for in the directory specified in the field `Directory` in the DEM configuration file (see [D\_H\_SUM]). If this field is empty, the DEM files are looked for in the directory where the DEM configuration file is placed.

### 7.65.3 Access to DEM dataset

Depending on the `Cache_Type` field in the DEM configuration file (see [D\_H\_SUM]), one of the following methods is used to access the DEM dataset:

- `FIFO_CACHE` (default): memory is reserved for holding DEM data. As soon as an altitude value is requested and is not yet available in memory, the corresponding data file is loaded in memory. When the maximum size of reserved memory (configurable with the field `Cache_Max_Size`) is exceeded, memory is made available with a First In – First Out policy, that is memory correspondent to the file loaded earliest is made available for the file to be loaded.
- `PRELOAD_CACHE`: memory is reserved for holding DEM data. The user shall load in memory the needed files in advance via the function `xp_dem_id_configure` (see section 7.70). Request of a value not available in memory would result in an error.
- `NO_CACHE`: no memory is reserved for holding DEM data. The dataset is accessed via a single direct I/O access to the file storing the requested value.

In the case of GDEM, due to the special structure of the tiles, loading them to memory can take much time, so it is not recommended the use of cache methods.

Choice of the method that best fits user's needs depends on many aspects including HW/SW setup and the type of user application:

- 1) The `FIFO_CACHE` is recommended for user applications able to request to the operating system a large amount of physical memory and that require making a large numbers of DEM computations per DEM area i.e. when several DEM computations are done reading the same file or small set of files covering the same region.
- 2) The `PRELOAD_CACHE` is recommended for multithreading applications. Note that memory holding DEM data can be shared amongst several threads. In the `FIFO_CACHE`, as memory content can change at runtime, mutual exclusion mechanisms are implemented in order to avoid threads to access inconsistent data. Such mechanisms are not needed in the `PRELOAD_CACHE` methods and therefore multithreading applications may run more efficiently. However the user is requested to estimate the area (in terms of the longitude/latitude boundaries) that will be requested during computations.

- 3) The above methods using memory to hold DEM data do not improve performance (or make even performance worse) of applications running with low amount of physical memory available or when DEM request is sporadic per DEM area. In all these cases, the user is recommended to set Cache\_Type to NO\_CACHE. For example, applications making sporadic accesses and in different DEM areas will not benefit of the caching methods, as the advantage of having a fast access to data is lost by the disadvantage of continuously load new files correspondent to different areas.

The default configuration is (i.e. when fields are not provided in the file):

- Cache\_Type = FIFO\_CACHE
- Cache\_Max\_Size = 2 GigaBytes

Values of Cache\_Type and Cache\_Max\_Size can be changed at runtime under certain conditions using the function `xp_dem_id_configure`.

Memory is allocated using the `malloc()` C library function. Therefore performance of DEM access using caching strictly depends on the implementation of such library and on memory management from the Operating System. Performance of access to memory depends on many factors that can be tuned by the user. For the sake of example, if, as it normally happens in Linux systems, the memory request is larger than a given threshold size, the memory will be allocated in the virtual memory space and this may result in several page faults at runtime, leading to inefficiencies in the execution. The user can improve this by tuning the threshold size (i.e. using the `mallopt()` C library, if available). In order to get the best advantages from the caching methods, the user is therefore recommended to evaluate and tackle platform specific issues to memory allocation and management.

#### **7.65.4 DEM maximum altitude algorithm**

If the mini tile configuration is provided (MiniTile\_Configuration tag) in the DEM configuration file (see [D\_H\_SUM]), the maximum altitude algorithm is used to compute DEM intersection. This algorithm consists in the following:

- The tiles are divided in sub-sections (mini-tiles), according to the configuration provided in DEM configuration file: Lon\_Size and Lat\_Size tags. For example, if the tile is 15 degrees long in longitude and 15 degrees long in latitude, and Lon\_Size and Lat\_Size are 5 degrees and 5 degrees respectively, the tile would have 9 mini-tiles equal in size between them.
- In the DEM configuration of mini-tiles, also the tag Filename is provided, which corresponds to the name (or path) of the binary file which contains the maximum altitude corresponding to each mini-tile. This file can be generated with function `xp_gen_dem_max_altitude_file`. If no path is provided, the binary file is looked for in current directory and the DEM directory.
- Internally, the algorithm checks if the altitude of the rays when crossing above each mini-tile is higher or lower than maximum altitude contained in the mini-tile. If the altitude is lower, the mini-tile is computed to look for an intersection; if not, the mini-tile is skipped and the following mini-tile is checked.

Note: the algorithm is not executed if the difference in latitude/longitude of start and end points in ray search is less than mini-tile size.

#### **7.65.5 DEM Geoid computation**

The DEM ACE2 and GDEM V2 files provide the altitude with respect to its reference geoid. In the internal DEM computations, the altitude is transformed to altitude over the reference ellipsoid. To perform this

operation, a number of harmonics must be used, which can be configured with the following DEM configuration user tags (see [D\_H\_SUM]):

- Geoid\_Computation tag: this field can take the values:
  - “Enabled”: geoid computation is performed.
  - “Disabled”: geoid computation is not performed.
- Geoid\_Nof\_Harmonics tag: the number of harmonics to be used in geoid computation.

If this fields are not provided, the default values are:

- Geoid\_Computation: Enabled
- Geoid\_Nof\_Harmonics: 30

The computation precision increases with the number of harmonics (maximum is 360 harmonics) but the runtime performance gets worse. The computation of the geoid at runtime can be avoided by generating offline a DEM dataset storing altitudes w.r.t ellipsoid using `xp_gen_dem_altitudes_from_ellipsoid` function. In this case, when the DEM is used, the geoid computation shall be disabled in the DEM configuration file.

### 7.65.6 Calling Interface

The calling interface of the `xp_dem_init` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long mode, model;
    char dem_file[XL_MAX_STR];
    xp_dem_id dem_id = {NULL};
    long ierr[XP_NUM_ERR_DEM_INIT], status;

    status = xp_dem_init(&mode, &model, dem_file, &dem_id, ierr);
}
```

The `XP_NUM_ERR_DEM_INIT` constant is defined in the file `explorer_pointing.h`.

### 7.65.7 Input Parameters

The `xp_dem_init` CFI function has the following input parameters:

*Table 163: Input parameters of `xp_dem_init` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
mode	long *	-	Digital Elevation Model initialization mode. This parameter has no effect in current implementation (the DEM type is taken from configuration file), but a warning will be raised if the value does not coincide with the one in configuration file.	-	Complete
model	long *	-	Digital Elevation Model initialization model (dummy in current implementation)	-	Complete
dem_file	char[]	-	File used for DEM initialization (See DEM Configuration file in [D_H_SUM])	-	Complete

It is possible to use enumeration values rather than integer values for some of the input arguments:

- DEM Initialization Mode: initialization mode (according to `XD_Dem_model_enum` in [D\_H\_SUM])

### 7.65.8 Output Parameters

The output parameters of the `xp_dem_init` CFI function are:

*Table 164: Output parameters of `xp_dem_init`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
dem_id	xp_dem_id*	-	Structure that contains the DEM initialization.	-	-
ierr	long	-	Error vector	-	-

### 7.65.9 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_dem_init` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the `EO_POINTING` software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_dem_init` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM])

**Table 165: Error messages of `xp_dem_init` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	DEM Mode ID is not correct	No calculation performed	XP_CFI_DEM_INIT_MODE_ID_ERR	0
ERR	DEM Model ID is not correct	No calculation performed	XP_CFI_DEM_INIT_MODEL_ID_ERR	1
ERR	DEM initialization file could not be opened	No calculation performed	XP_CFI_DEM_INIT_FILE_NOT_OPEN_ERR	2
ERR	Unable to store DEM initialization file (not enough memory)	No calculation performed	XP_CFI_DEM_INIT_MEMORY_ERR	3
ERR	Error while reading DEM initialization file	No calculation performed	XP_CFI_DEM_INIT_FILE_READING_ERR	4
WARN	Default DEM values at Poles will be taken	Calculation performed. If required, default altitude values at the poles will be used.	XP_CFI_DEM_INIT_FILE_READING_WARN	5
WARN	DEM file mode and input mode are not the same	No calculation performed	XP_CFI_DEM_INIT_WRONG_MODEL_WARN	6
WARN	Input DEM configuration file version is deprecated	Calculation performed	XP_CFI_DEM_INIT_DEPRECATED_WARN	7
WARN	DEM Cache Type not supplied, assuming FIFO_CACHE with maximum size of 2 GB	Calculation performed	XP_CFI_DEM_INIT_CACHE_WARN	8
ERR	Error initializing TILE Database	No calculation performed	XP_CFI_DEM_INIT_TILE_DATABASE_ERR	9

## 7.66 xp\_dem\_close

### 7.66.1 Overview

The `xp_dem_close` CFI function cleans up any memory allocation performed by the `xp_dem_init` functions.

### 7.66.2 Calling Interface

The calling interface of the `xp_dem_close` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    xp_dem_id dem_id = {NULL};
    long ierr[XP_NUM_ERR_DEM_CLOSE], status;

    status = xp_dem_close(&dem_id, ierr);
}
```

The `XP_NUM_ERR_DEM_CLOSE` constant is defined in the file `explorer_pointing.h`.

### 7.66.3 Input Parameters

The `xp_dem_close` CFI function has the following input parameters:

**Table 166: Input parameters of `xp_dem_close` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
dem_id	xp_dem_id*	-	Structure that contains the DEM initialization.	-	-

### 7.66.4 Output Parameters

The output parameters of the `xp_dem_close` CFI function are:

**Table 167: Output parameters of `xp_dem_close`**

C name	C type	Array	Description	Unit	Allowed Range
--------	--------	-------	-------------	------	---------------

		Element	(Reference)	(Format)	
ierr	long	-	Error vector	-	-

### 7.66.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the **xp\_dem\_close** CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library **xp\_get\_msg** (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the **xp\_dem\_close** function by calling the function of the EO\_POINTING software library **xp\_get\_code** (see [GEN\_SUM]).

**Table 168: Error messages of xp\_dem\_close function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Could not close the Dem. Id. as it is not initialized or it is being used	No calculation performed	XP_CFI_DEM_CLOSE_WRONG_ID_ERR	0



## 7.67 xp\_dem\_compute

### 7.67.1 Overview

The `xp_dem_compute` CFI function compute the altitude over the see level for a point in the Earth. The altitude is calculated from the altitudes read from a digital elevation model (DEM).

### 7.67.2 Calling Interface

The calling interface of the `xp_dem_compute` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    xl_model_id model_id = {NULL};
    xp_dem_id   dem_id   = {NULL};
    long ierr[XP_NUM_ERR_DEM_COMPUTE], status;
    double lon, lat, alt;
    status = xp_dem_compute(&model_id, &dem_id,
                          &lon, &lat,
                          &alt, ierr);
}
```

The `XP_NUM_ERR_DEM_COMPUTE` constant is defined in the file *explorer\_pointing.h*.

### 7.67.3 Input Parameters

The `xp_dem_compute` CFI function has the following input parameters:

*Table 169: Input parameters of `xp_dem_compute` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>model_id</code>	<code>xl_model_id*</code>	-	Model ID	-	-
<code>dem_id</code>	<code>xp_dem_id*</code>	-	Structure that contains the DEM initialization.	-	-
<code>lon</code>	<code>double</code>	-	Input longitude	degrees	[0, 360)
<code>lat</code>	<code>double</code>	-	Input latitude	degrees	[-90, 90]

### 7.67.4 Output Parameters

The output parameters of the `xp_dem_compute` CFI function are:

*Table 170: Output parameters of `xp_dem_compute`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>alt</code>	<code>double</code>	-	Altitude	meters	-
<code>ierr</code>	<code>long</code>	-	Error vector	-	-

### 7.67.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_dem_compute` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_dem_compute` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

*Table 171: Error messages of `xp_dem_compute` function*

Error type	Error message	Cause and impact	Error code	Error No
------------	---------------	------------------	------------	----------

ERR	Error getting cell altitude	No calculation performed	XP_CFI_DEM_COMPUTE_GET_CELL_ERR	0
ERR	Error allocating memory	No calculation performed	XP_CFI_DEM_COMPUTE_MEMORY_ERR	1

## 7.68xp\_dem\_get\_info

### 7.68.1 Overview

The `xp_dem_get_info` CFI function reads DEM information for a given geodetic point.

### 7.68.2 Calling Interface

The calling interface of the `xp_dem_get_info` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    xl_model_id model_id = {NULL};
    xp_dem_id   dem_id   = {NULL};
    long ierr[XP_NUM_ERR_DEM_GET_INFO], status;
    double lon, lat;
    xp_dem_info dem_info
    status = xp_dem_get_info(&model_id, &dem_id,
                           &lon, &lat,
                           &dem_info,
                           ierr);
}
```

The `XP_NUM_ERR_DEM_GET_INFO` constant is defined in the file *explorer\_pointing.h*.

### 7.68.3 Input Parameters

The `xp_dem_get_info` CFI function has the following input parameters:

*Table 172: Input parameters of `xp_dem_get_info` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>model_id</code>	<code>xl_model_id*</code>	-	Model ID	-	-
<code>dem_id</code>	<code>xp_dem_id*</code>	-	Structure that contains the DEM initialization.	-	-
<code>lon</code>	<code>double</code>	-	Input longitude	degrees	[0, 360)
<code>lat</code>	<code>double</code>	-	Input latitude	degrees	[-90, 90]

### 7.68.4 Output Parameters

The output parameters of the `xp_dem_get_info` CFI function are:

*Table 173: Output parameters of `xp_dem_get_info`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>dem_info</code>	<code>xp_dem_info</code>	-	Structure containing DEM information	-	-
<code>ierr</code>	<code>long</code>	-	Error vector	-	-

### 7.68.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_dem_get_info` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_dem_get_info` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

*Table 174: Error messages of `xp_dem_get_info` function*

Error	Error message	Cause and impact	Error code	Error
-------	---------------	------------------	------------	-------

type				No
ERR	DEM Id. is not initialized	No calculation performed	XP_CFI_DEM_GET_INFO_STATUS_ERR	0
ERR	Input longitude is out of allowed range [0, 360]	No calculation performed	XP_CFI_DEM_GET_INFO_WRONG_LONGITUDE_ERR	1
ERR	Input latitude is out of allowed range [90, -90]	No calculation performed	XP_CFI_DEM_GET_INFO_WRONG_LATITUDE_ERR	2
ERR	Could not open DEM file: %s	No calculation performed	XP_CFI_DEM_GET_INFO_OPEN_FILE_ERR	3
ERR	Could not read DEM file: %s	No calculation performed	XP_CFI_DEM_GET_INFO_READ_FILE_ERR	4

## 7.69 xp\_dem\_get\_id\_data

### 7.69.1 Overview

The `xp_dem_get_id_data` CFI function returns DEM initialization data.

### 7.69.2 Calling interface

The calling interface of the `xp_dem_get_id_data` CFI function is the following (input parameters are underlined>):

```
#include <explorer_lib.h>
{
    xp_dem_id dem_id;
    long status;
    xp_dem_id_data data;
    status = xp_dem_get_id_data (&u>dem_id, &data);
}
```

### 7.69.3 Input parameters

The `xp_dem_get_id_data` CFI function has the following input parameters:

*Table 175: Input parameters of xp\_dem\_get\_id\_data function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
dem_id	xp_dem_id *	-	Structure that contains the DEM initialization.	-	-

### 7.69.4 Output parameters

The output parameters of the `xp_dem_get_id_data` CFI function are:

*Table 176: Output parameters of xp\_dem\_get\_id\_data function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
xp_dem_get_id_data	long	-	Status flag	-	-
data	xp_dem_id_data	-	DEM initialization data	-	-

## 7.69.5 Warnings and errors

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The `dem_id` was not initialised.

## 7.70 `xp_dem_id_configure`

### 7.70.1 Overview

The `xp_dem_id_configure` CFI function performs configuration operations on DEM cache. The following operations can be performed:

- CLEAR CACHE: all the tiles in the cache are unloaded but cache memory is not freed.
- FREE CACHE: all the tiles in the cache are unloaded and cache memory is freed.
- SET MAXIMUM CACHE SIZE: a new maximum size for cache is set. If there are more tiles loaded in cache than new maximum size, the tiles are unloaded in a FIFO (First in- First out) order till new maximum size is reached.
- LOAD TILE SET: this operation can only be performed for PRELOAD cache. A set of tiles corresponding to an input rectangular longitude-latitude area is loaded in cache.

### 7.70.2 Calling Interface

The calling interface of the `xp_dem_id_configure` CFI function is the following (input parameters are underlined>):

```
#include <explorer_pointing.h>
{
    xp_dem_id    dem_id    = {NULL};
    long ierr[XP_NUM_ERR_DEM_ID_CONFIGURE], status;
    xp_dem_id_config config;

    status = xp_dem_id_configure(&dem_id, &config,
                                ierr);
}
```

The `XP_NUM_ERR_DEM_ID_CONFIGURE` constant is defined in the file `explorer_pointing.h`.

### 7.70.3 Input Parameters

The `xp_dem_id_configure` CFI function has the following input parameters:

*Table 177: Input parameters of `xp_dem_id_configure` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>dem_id</code>	<code>xp_dem_id*</code>	-	Structure that contains the DEM initialization.	-	-
<code>config</code>	<code>xp_dem_id_configure</code>	-	Input operation on cache	-	- Possible values for command field: XP_LOAD_TILE_SET XP_CLEAR_CACHE XP_FREE_CACHE XP_SET_MAX_SIZE - For rectangular area: 0. ≤ longitude ≤ 360. -90. ≤ latitude ≤ 90.

### 7.70.4 Output Parameters

The output parameters of the `xp_dem_id_configure` CFI function are:

*Table 178: Output parameters of `xp_dem_id_configure`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>xp_dem_id_configure</code>	<code>long</code>	-	Status flag	-	-
<code>ierr</code>	<code>long</code>	-	Error vector	-	-

### 7.70.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_dem_id_configure` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.



The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the **xp\_dem\_id\_configure** function by calling the function of the EO\_POINTING software library **xp\_get\_code** (see [GEN\_SUM]).

**Table 179: Error messages of xp\_dem\_get\_info function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	DEM id configured without cache	No calculation performed	XD_CFI_DEM_ID_CONFIGUR E_NO_CACHE_ERR	0
ERR	Wrong configuration command provided	No calculation performed	XD_CFI_DEM_ID_CONFIGUR E_WRONG_COMMAND_ERR	1
ERR	Error allocating memory	No calculation performed	XD_CFI_DEM_ID_CONFIGUR E_MEMORY_ERR	2
ERR	Error in input longitudes	No calculation performed	XD_CFI_DEM_ID_CONFIGUR E_LON_ERR	3
ERR	Error in input latitudes	No calculation performed	XD_CFI_DEM_ID_CONFIGUR E_LAT_ERR	4
ERR	Requested area needs more memory than maximum cache size	No calculation performed	XD_CFI_DEM_ID_CONFIGUR E_MAX_CACHE_ERR	5
ERR	Error loading tile	No calculation performed	XD_CFI_DEM_ID_CONFIGUR E_LOAD_TILE_ERR	6
ERR	Error locking thread	No calculation performed	XD_CFI_DEM_ID_CONFIGUR E_LOCK_THREAD_ERR	7

## 7.71 xp\_target\_inter

### 7.71.1 Overview

The `xp_target_inter` CFI function computes the first or the second intersection point of the line of sight from the satellite (defined by an elevation and an azimuth angle expressed in the selected Attitude Frame) with a surface located at a certain geodetic altitude over the Earth.

The light travel time (from the satellite to the target or vice versa) can be taken into account by the computations. For details about light propagation mode see the section Error: Reference source not found.

### 7.71.2 Calling Interface

The calling interface of the `xp_target_inter` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long          sat_id;
    xp_attitude_id attitude_id = {NULL};
    xp_atmos_id   atmos_id = {NULL};
    xp_dem_id     dem_id = {NULL};
    xp_target_id  target_id = {NULL};
    long deriv, inter_flag, iray;
    double los_az, los_el, geod_alt, los_az_rate, los_el_rate, freq;
    long ierr[XP_NUM_ERR_TARGET_INTER], status, num_user_target,
        num_los_target;

    status = xp_target_inter(&sat_id,
        &attitude_id,
        &atmos_id,
        &dem_id,
        &deriv, &inter_flag, &los_az, &los_el, &geod_alt,
        &los_az_rate, &los_el_rate, &iray, &freq,
        &num_user_target, &num_los_target,
        &target_id, ierr);

    /* Or, using the run_id */
    long run_id;

    status = xp_target_inter_run(&run_id,
```

```
&attitude_id,  
&deriv, &inter_flag, &los_az, &los_el, &geod_alt,  
&los_az_rate, &los_el_rate, &iray, &freq,  
&num_user_target, &num_los_target,  
&target_id, ierr);
```

```
}
```

The `XP_NUM_ERR_TARGET_INTER` constant is defined in the file *explorer\_pointing.h*.

### 7.71.3 Input Parameters

The `xp_target_inter` CFI function has the following input parameters:

*Table 180: Input parameters of `xp_target_inter` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>sat_id</code>	<code>long *</code>	-	Satellite ID	-	Complete
<code>attitude_id</code>	<code>xp_attitude_id*</code>	-	Structure that contains the Attitude. (input/output)	-	-
<code>atmos_id</code>	<code>xp_atmos_id*</code>	-	Structure that contains the atmosphere initialization.	-	The <code>atmos_id</code> has to be initialized with any of these modes: - <code>XP_NO_REF_INIT</code> - <code>XP_STD_INIT</code> - <code>XP_USER_INIT</code>
<code>dem_id</code>	<code>xp_dem_id*</code>	-	Structure that contains the DEM initialization.	-	-
<code>deriv</code>	<code>long *</code>	-	Derivative ID	-	Allowed values: (0) <code>XP_NO_DER</code> (1) <code>XP_DER_1ST</code> (2) <code>XP_DER_2ND</code>
<code>inter_flag</code>	<code>long *</code>	-	Flag for first or second inter section point selection	-	Allowed values: (1) <code>XP_INTER_1ST</code> (2) <code>XP_INTER_2ND</code>
<code>los_az</code>	<code>double *</code>	-	Azimuth of the LOS (Attitude Frame)	deg	$\geq 0$ $< 360$
<code>los_el</code>	<code>double *</code>	-	Elevation of the LOS (Attitude Frame)	deg	$\geq -90$ $\leq 90$
<code>geod_alt</code>	<code>double *</code>	-	Geodetic altitude over the Earth	m	$\geq -bWGS$
<code>los_az_rate</code>	<code>double *</code>	-	Azimuth-rate of the LOS (Attitude Frame)	deg/s	-
<code>los_el_rate</code>	<code>double *</code>	-	Elevation-rate of the LOS (Attitude Frame)	deg/s	-
<code>iray</code>	<code>long *</code>	-	Not used. The atmosphere refraction model can be defined via <code>atmos_id</code> initialization. If <code>iray</code> is different of <code>XP_NO_REF_INIT</code> , a warning is raised.	-	-

freq	double *	-	Frequency of the signal	Hz	>= 0
------	----------	---	-------------------------	----	------

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Derivative switch: deriv. See current document, Table 3.
- Intersection flag: inter\_flag. See current document, Table 3 .
- 

### 7.71.4 Output Parameters

The output parameters of the `xp_target_inter` CFI function are:

**Table 181: Output parameters of `xp_target_inter`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
num_user_target	long*	-	Number of user defined targets calculated	-	>= 0 (Set to 1 for non multi-target routines)
num_los_target	long*	-	Number of LOS targets calculated	-	>= 0
target_id	xp_target_id*	-	Structure that contains the Target results	-	-
ierr	long	-	Error vector	-	-

### 7.71.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_inter` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_inter` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 182: Error messages of `xp_target_inter` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Attitude Id. is not initialized	No calculation performed	XP_CFI_TARGET_INTER_ATTITUDE_STATUS_ERR	0
ERR	Intersection flag is not correct	No calculation performed	XP_CFI_TARGET_INTER_INTER_FLAG_ERR	1
ERR	Invalid Frequency	No calculation performed	XP_CFI_TARGET_INTER_	2

			FREQ_ERR	
ERR	Time reference ID is not correct	No calculation performed	XP_CFI_TARGET_INTER_TIME_REF_ERR	3
ERR	Deriv flag is not correct	No calculation performed	XP_CFI_TARGET_INTER_DERIV_FLAG_ERR	4
ERR	Ray Tracing Model ID is not correct	No calculation performed	XP_CFI_TARGET_INTER_I_RAY_ID_ERR	5
ERR	Input state vector does not satisfy loose tolerance requirement	No calculation performed	XP_CFI_TARGET_INTER_I_NVALID_SV_ERR	6
ERR	Invalid LOS Azimuth	No calculation performed	XP_CFI_TARGET_INTER_LOS_AZIMUTH_ERR	7
ERR	Invalid LOS Elevation	No calculation performed	XP_CFI_TARGET_INTER_LOS_ELEVATION_ERR	8
ERR	Invalid Geodetic Altitude	No calculation performed	XP_CFI_TARGET_INTER_GEODETTIC_ALT_ERR	9
ERR	Memory allocation error	No calculation performed	XP_CFI_TARGET_INTER_MEMORY_ERR	10
ERR	Internal computation error # 3	No calculation performed	XP_CFI_TARGET_INTER_I_NITIAL_LOOK_DIR_OR_PLANE_ERR	11
ERR	Time Reference not initialised	No calculation performed	XP_CFI_TARGET_INTER_TIME_REF_INIT_ERR	12
ERR	No target was found	No calculation performed	XP_CFI_TARGET_INTER_TARGET_NOT_FOUND_ERR	13
ERR	Internal computation error # 4	No calculation performed	XP_CFI_TARGET_INTER_RANGE_OR_POINTING_CALC_ERR	14
WARN	Input state vector does not satisfy tight tolerance requirement	Calculation performed. A message informs the user.	XP_CFI_TARGET_INTER_I_NVALID_SV_WARN	15
WARN	Path from satellite to target occulted by the Earth	Calculation performed. A message informs the user.	XP_CFI_TARGET_INTER_NEGATIVE_ALTITUDE_WARN	16
WARN	The ray tracing flag (iray) is ignored	Calculation performed. A message informs the user that this parameter is not used. If the variable iray is equal to XP_NO_REF_INIT (=0), the warning is avoided.	XP_CFI_TARGET_INTER_IRAY_ID_WARN	17

## 7.72 xp\_target\_ground\_range

### 7.72.1 Overview

The `xp_target_ground_range` CFI function computes the location of a point that is placed on a surface at a certain geodetic altitude over the Earth, that lays on the plane defined by the satellite position, the nadir and a reference point, and that is at a certain distance or ground range measured along that surface from that reference point.

This reference point is calculated being the intersection of the previous surface with the line of sight defined by an elevation and azimuth angle in the selected Attitude Frame.

The light travel time (from the satellite to the target or vice versa) can be taken into account by the computations. For details about light propagation mode see the section Error: Reference source not found.

### 7.72.2 Calling Interface

The calling interface of the `xp_target_ground_range` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long          sat_id;
    xp_attitude_id attitude_id = {NULL};
    xp_dem_id     dem_id = {NULL};
    xp_target_id  target_id = {NULL};
    long deriv;
    double los_az, los_el, geod_alt, distance;
    double los_az_rate, los_el_rate;
    long ierr[XP_NUM_ERR_TARGET_GROUND_RANGE], status,
        num_user_target, num_los_target;

    status = xp_target_ground_range(&sat_id,
                                   &attitude_id,
                                   &dem_id,
                                   &deriv, &los_az,
                                   &los_el, &geod_alt, &distance, &los_az_rate,
                                   &los_el_rate, &num_user_target, &num_los_target,
                                   &target_id, ierr);

    /* Or, using the run_id */
    long run_id;
```

```
status = xp_target_ground_range_run(&run_id,  
                                     &attitude_id,  
                                     &deriv, &los_az,  
                                     &los_el, &geod_alt, &distance, &los_az_rate,  
                                     &los_el_rate, &num_user_target, &num_los_target,  
                                     &target_id, ierr);  
}
```

The `XP_NUM_ERR_TARGET_GROUND_RANGE` constant is defined in the file *explorer\_pointing.h*.



### 7.72.3 Input Parameters

The `xp_target_ground_range` CFI function has the following input parameters:

*Table 183: Input parameters of `xp_target_ground_range` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>sat_id</code>	<code>long *</code>	-	Satellite ID	-	Complete
<code>attitude_id</code>	<code>xp_attitude_id*</code>	-	Structure that contains the Attitude. (input/output)	-	-
<code>dem_id</code>	<code>xp_dem_id*</code>	-	Structure that contains the DEM initialization.	-	-
<code>deriv</code>	<code>long *</code>	-	Derivative ID	-	Allowed values: (0) <code>XP_NO_DER</code> (1) <code>XP_DER_1ST</code> (2) <code>XP_DER_2ND</code>
<code>los_az</code>	<code>double *</code>	-	Azimuth of the LOS (Attitude Frame)	deg	$\geq 0$ $< 360$
<code>los_el</code>	<code>double *</code>	-	Elevation of the LOS (Attitude Frame)	deg	$\geq -90$ $\leq 90$
<code>geod_alt</code>	<code>double *</code>	-	Geodetic altitude over the Earth (Earth fixed CS)	m	$\geq -bWGS$
<code>distance</code>	<code>double *</code>	-	Distance or ground range to the reference point, positive from nadir in the azimuth direction (Earth Fixed CS)	m	-
<code>los_az_rate</code>	<code>double *</code>	-	Azimuth-rate of the LOS (Attitude Frame)	deg/s	-
<code>los_el_rate</code>	<code>double *</code>	-	Elevation-rate of the LOS (Attitude Frame)	deg/s	-

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Derivative switch: `deriv`. See current document, Table 3.

### 7.72.4 Output Parameters

The output parameters of the `xp_target_ground_range` CFI function are:

**Table 184: Output parameters of `xp_target_ground_range`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
num_user_target	long*	-	Number of user defined targets calculated	-	$\geq 0$ (Set to 1 for non multi-target routines)
num_los_target	long*	-	Number of LOS targets calculated	-	$\geq 0$
target_id	xp_target_id*	-	Structure that contains the Target results	-	-
ierr	long	-	Error vector	-	-

### 7.72.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_ground_range` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_ground_range` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 185: Error messages of `xp_target_ground_range` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Attitude Id. is not initialized	No calculation performed	XP_CFI_TARGET_GR_RANGE_ATTITUDE_STATUS_ERR	0
ERR	Time reference ID is not correct	No calculation performed	XP_CFI_TARGET_GR_RANGE_TIME_REF_ERR	1
ERR	Deriv flag is not correct	No calculation performed	XP_CFI_TARGET_GR_RANGE_DERIV_FLAG_ERR	2
ERR	Invalid LOS Azimuth	No calculation performed	XP_CFI_TARGET_GR_RANGE_LOS_AZIMUTH_ERR	3
ERR	Invalid LOS Elevation	No calculation performed	XP_CFI_TARGET_GR_RANGE_LOS_ELEVATION_ERR	4

ERR	Invalid Geodetic Altitude	No calculation performed	XP_CFI_TARGET_GR_RANG GEODETIC_ALT_ERR	5
ERR	Input state vector does not satisfy loose tolerance requirement	No calculation performed	XP_CFI_TARGET_GR_RANG INVALID_SV_ERR	6
ERR	Memory allocation error	No calculation performed	XP_CFI_TARGET_GR_RANG MEMORY_ERR	7
ERR	Internal computation error # 3	No calculation performed	XP_CFI_TARGET_GR_RANG INITIAL_LOOK_DIR OR_PLANE_ERR	8
ERR	Time reference is not initialized	No calculation performed	XP_CFI_TARGET_GR_RANG TIME_REF_INIT_ERR	9
ERR	No target was found	No calculation performed	XP_CFI_TARGET_GR_RANG TARGET_NOT_FOUND_ERR	10
ERR	Internal computation error #4	No calculation performed	XP_CFI_TARGET_GR_RANG RANGE_OR_POINTING CALC_ERR	11
WARN	Input state vector does not satisfy tight tolerance requirement	Calculation performed. A message informs the user.	XP_CFI_TARGET_GR_RANG INVALID_SV_WARN	18

## 7.73 xp\_target\_incidence\_angle

### 7.73.1 Overview

The `xp_target_incidence_angle` CFI function computes the location of a point that is placed on a surface at a certain geodetic altitude over the Earth and that is seen from the satellite on a line of sight that forms a certain azimuth angle in the selected Attitude Frame and that intersects that surface with a certain incidence angle.

The light travel time (from the satellite to the target or vice versa) can be taken into account by the computations. For details about light propagation mode see the section Error: Reference source not found.

### 7.73.2 Calling Interface

The calling interface of the `xp_target_incidence_angle` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long          sat_id, deriv;
    xp_attitude_id attitude_id = {NULL};
    xp_dem_id     dem_id = {NULL};
    xp_target_id  target_id = {NULL};
    double los_az, inc_angle, geod_alt, los_az_rate;
    long ierr[XP_NUM_ERR_TARGET_INCIDENCE_ANGLE], status,
        num_user_target, num_los_target;

    status = xp_target_incidence_angle(&sat_id,
        &attitude_id, &dem_id,
        &deriv, &los_az,
        &inc_angle, &geod_alt, &los_az_rate,
        &num_user_target, &num_los_target,
        &target_id, ierr);

    /* Or, using the run_id */
    long run_id;

    status = xp_target_incidence_angle_run(&run_id, &attitude_id,
        &deriv, &los_az,
        &inc_angle, &geod_alt, &los_az_rate,
        &num_user_target, &num_los_target,
```

```
        &target_id, ierr);  
    }
```

The `XP_NUM_ERR_TARGET_INCIDENCE_ANGLE` constant is defined in the file *explorer\_pointing.h*.

### 7.73.3 Input Parameters

The `xp_target_incidence_angle` CFI function has the following input parameters:

*Table 186: Input parameters of `xp_target_incidence_angle` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_id	long *	-	Satellite ID	-	Complete
attitude_id	xp_attitude_id*	-	Structure that contains the Attitude. (input/output)	-	-
dem_id	xp_dem_id *	-	Structure that contains the DEM initialization.	-	-
deriv	long *	-	Derivative ID	-	Allowed values: (0) XP_NO_DER (1) XP_DER_1ST (2) XP_DER_2ND
los_az	double *	-	Azimuth of the LOS (Attitude Frame)	deg	$\geq 0$ $< 360$
inc_angle	double *	-	Incidence angle of the LOS (Earth fixed CS)	deg	$\geq 0$ $\leq 90$
geod_alt	double *	-	Geodetic altitude over the Earth (Earth fixed CS)	m	$\geq -bWGS$
los_az_rate	double *	-	Azimuth-rate of the LOS (Attitude Frame)	deg/s	-

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Derivative switch: `deriv`. See current document, Table 3 .

### 7.73.4 Output Parameters

The output parameters of the `xp_target_incidence_angle` CFI function are:

**Table 187: Output parameters of `xp_target_incidence_angle`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
num_user_target	long*	-	Number of user defined targets calculated	-	$\geq 0$ (Set to 1 for non multi-target routines)
num_los_target	long*	-	Number of LOS targets calculated	-	$\geq 0$
target_id	xp_target_id*	-	Structure that contains the Target results	-	-
ierr	long	-	Error vector	-	-

### 7.73.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_incidence_angle` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_incidence_angle` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 188: Error messages of `xp_target_incidence_angle` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Attitude Id. is not initialized	No calculation performed	XP_CFI_TARGET_INC_ANGLE_ATTITUDE_STATUS_ERR	0
ERR	Deriv flag is not correct	No calculation performed	XP_CFI_TARGET_INC_ANGLE_DERIV_FLAG_ERR	1
ERR	Invalid LOS Azimuth	No calculation performed	XP_CFI_TARGET_INC_ANGLE_LOS_AZIMUTH_ERR	2
ERR	Invalid Incidence Angle	No calculation performed	XP_CFI_TARGET_INC_ANGLE_INC_ANGLE_ERR	3
ERR	Invalid Geodetic Altitude	No calculation performed	XP_CFI_TARGET_INC_ANGLE_GEODETTIC_ALT_ERR	4

ERR	Input state vector does not satisfy loose tolerance requirement	No calculation performed	XP_CFI_TARGET_INC_ANGLE_INVALID_SV_ERR	5
ERR	Memory allocation error	No calculation performed	XP_CFI_TARGET_INC_ANGLE_MEMORY_ERR	6
ERR	Internal computation error #3	No calculation performed	XP_CFI_TARGET_INC_ANGLE_INITIAL_LOOK_DIRECTION_PLANE_ERR	7
ERR	Time Reference not initialised	No calculation performed	XP_CFI_TARGET_INC_ANGLE_TIME_REF_INIT_ERR	8
ERR	No target was found	No calculation performed	XP_CFI_TARGET_INC_ANGLE_TARGET_NOT_FOUND_ERR	9
WARN	Input state vector does not satisfy tight tolerance requirement	Calculation performed. A message informs the user.	XP_CFI_TARGET_INC_ANGLE_INVALID_SV_WARN	11



## 7.74 xp\_target\_range

### 7.74.1 Overview

The **xp\_target\_range** CFI function computes the location of a point that is placed on a surface at a certain geodetic altitude over the Earth, that is seen from the satellite on a line of sight that forms a certain azimuth angle in the selected Attitude Frame, and that is at a certain range or slant-range from the satellite.

The light travel time (from the satellite to the target or vice versa) can be taken into account by the computations. For details about light propagation mode see the section Error: Reference source not found.

### 7.74.2 Calling Interface

The calling interface of the **xp\_target\_range** CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long          sat_id;
    xp_attitude_id attitude_id = {NULL};
    xp_dem_id     dem_id = {NULL};
    xp_target_id  target_id = {NULL};
    long deriv;
    double los_az, range, geod_alt, los_az_rate, range_rate;
    long ierr[XP_NUM_ERR_TARGET_RANGE], status, num_user_target,
        num_los_target;

    status = xp_target_range(&sat_id, &attitude_id, &dem_id,
        &deriv, &los_az, &range,
        &geod_alt, &los_az_rate, &range_rate,
        &num_user_target, &num_los_target,
        &target_id, ierr);

    /* Or, using the run_id */
    long run_id;

    status = xp_target_range_run(&run_id, &attitude_id,
        &deriv, &los_az, &range,
        &geod_alt, &los_az_rate, &range_rate,
        &num_user_target,          &num_los_target,
        &target_id, ierr);
```

}

The `XP_NUM_ERR_TARGET_RANGE` constant is defined in the file *explorer\_pointing.h*.

### 7.74.3 Input Parameters

The `xp_target_range` CFI function has the following input parameters:

*Table 189: Input parameters of `xp_target_range` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>sat_id</code>	long *	-	Satellite ID	-	Complete
<code>attitude_id</code>	<code>xp_attitude_id*</code>	-	Structure that contains the Attitude. (input/output)	-	-
<code>dem_id</code>	<code>xp_dem_id*</code>	-	Structure that contains the DEM initialization.	-	-
<code>deriv</code>	long *	-	Derivative ID	-	Allowed values: (0) XP_NO_DER (1) XP_DER_1ST (2) XP_DER_2ND
<code>los_az</code>	double *	-	Azimuth of the LOS (Attitude Frame)	deg	$\geq 0$ $< 360$
<code>range</code>	double *	-	Range to the satellite (Earth fixed CS)	m	$> 0$
<code>geod_alt</code>	double *	-	Geodetic altitude over the Earth	m	$\geq -bWGS$
<code>los_az_rate</code>	double *	-	Azimuth-rate of the LOS (Attitude Frame)	deg/s	-
<code>range_rate</code>	double *	-	Range-rate to the satellite (Earth fixed CS)	m/s	-

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Derivative switch: `deriv`. See current document, Table 3 .

### 7.74.4 Output Parameters

The output parameters of the `xp_target_range` CFI function are:

**Table 190: Output parameters of `xp_target_range`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
num_user_target	long*	-	Number of user defined targets calculated	-	$\geq 0$ (Set to 1 for non multi-target routines)
num_los_target	long*	-	Number of LOS targets calculated	-	$\geq 0$
target_id	xp_target_id*	-	Structure that contains the Target results	-	-
ierr	long	-	Error vector	-	-

### 7.74.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_range` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_range` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 191: Error messages of `xp_target_range` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Attitude Id. is not initialized	No calculation performed	XP_CFI_TARGET_RANGE_ATTITUDE_STATUS_ERR	0
ERR	Deriv flag is not correct	No calculation performed	XP_CFI_TARGET_RANGE_DERIV_FLAG_ERR	1
ERR	Invalid LOS Azimuth	No calculation performed	XP_CFI_TARGET_RANGE_LOS_AZIMUTH_ERR	2
ERR	Invalid Range	No calculation performed	XP_CFI_TARGET_RANGE_RANGE_ERR	3
ERR	Invalid Geodetic Altitude	No calculation performed	XP_CFI_TARGET_RANGE_GEODETTIC_ALT_ERR	4
ERR	Input state vector does not	No calculation performed	XP_CFI_TARGET_RANGE	5

	satisfy loose tolerance requirement		E_INVALID_SV_ERR	
ERR	Memory allocation error	No calculation performed	XP_CFI_TARGET_RANGE_MEMORY_ERR	6
ERR	Internal computation error #3	No calculation performed	XP_CFI_TARGET_RANGE_INITIAL_LOOK_DIRECTION_PLANE_ERR	7
ERR	Could not perform a time transformation	No calculation performed	XP_CFI_TARGET_RANGE_TIME_TRANSFORMATION_ERR	8
ERR	No target was found	No calculation performed	XP_CFI_TARGET_RANGE_TARGET_NOT_FOUND_ERR	9
WARN	Input state vector does not satisfy tight tolerance requirement	Calculation performed. A message informs the user.	XP_CFI_TARGET_RANGE_INVALID_SV_WARN	11

## 7.75 xp\_target\_range\_rate

### 7.75.1 Overview

The `xp_target_range_rate` CFI function computes the location of a point that is placed on a surface at a certain geodetic altitude over the Earth, that is at a certain range from the satellite, and this range has a certain change rate (`range_rate`). Associated Earth-fixed target is supposed to have zero range-rate value.

The light travel time (from the satellite to the target or vice versa) can be taken into account by the computations. For details about light propagation mode see the section Error: Reference source not found.

### 7.75.2 Calling Interface

The calling interface of the `xp_target_range_rate` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long          sat_id;
    xp_attitude_id attitude_id = {NULL};
    xp_dem_id     dem_id = {NULL};
    xp_target_id  target_id = {NULL};
    long deriv;
    double ef_range_rate, range, geod_alt;
    double ef_range_rate_rate, range_rate;
    long ierr[XP_NUM_ERR_TARGET_RANGE_RATE], status, num_user_target,
        num_los_target;

    status = xp_target_range_rate(&sat_id,
        &attitude_id,
        &dem_id,
        &deriv, &ef_range_rate, &range,
        &geod_alt, &ef_range_rate_rate, &range_rate,
        &num_user_target, &num_los_target, &target_id, ierr);

    /* Or, using the run_id */
    long run_id;

    status = xp_target_range_rate_run(&run_id,
        &attitude_id,
        &deriv, &ef_range_rate, &range,
```

```
&geod_alt, &ef_range_rate_rate, &range_rate,  
&num_user_target, &num_los_target, &target_id, ierr);  
}
```

The `XP_NUM_ERR_TARGET_RANGE_RATE` constant is defined in the file *explorer\_pointing.h*.

### 7.75.3 Input Parameters

The `xp_target_range_rate` CFI function has the following input parameters:

*Table 192: Input parameters of `xp_target_range_rate` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>sat_id</code>	<code>long *</code>	-	Satellite ID	-	Complete
<code>attitude_id</code>	<code>xp_attitude_id*</code>	-	Structure that contains the Attitude. (input/output)	-	-
<code>dem_id</code>	<code>xp_dem_id*</code>	-	Structure that contains the DEM initialization.	-	-
<code>attitude_frame_id</code>	<code>long *</code>	-	Attitude Frame ID	-	Complete
<code>deriv</code>	<code>long *</code>	-	Derivative ID	-	Allowed values: (0) XP_NO_DER (1) XP_DER_1ST (2) XP_DER_2ND
<code>ef_range_rate</code>	<code>double *</code>	-	Range-rate of the related Earth-fixed target (Earth fixed CS)	m/s	-
<code>range</code>	<code>double *</code>	-	Range or slant-range from target to satellite (Earth fixed CS)	m	> 0
<code>geod_alt</code>	<code>double *</code>	-	Geodetic altitude over the Earth	m	>= -bWGS
<code>ef_range_rate_rate</code>	<code>double *</code>	-	Range-rate-rate of the related Earth-fixed target (Earth fixed CS) Dummy parameter.	m/s <sup>2</sup>	-
<code>range_rate</code>	<code>double *</code>	-	Range-rate from target to satellite (Earth fixed CS) Dummy parameter.	m/s	-

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Derivative switch: `deriv`. See current document, Table 3 .



### 7.75.4 Output Parameters

The output parameters of the `xp_target_range_rate` CFI function are:

**Table 193: Output parameters of `xp_target_range_rate`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
num_user_target	long*	-	Number of user defined targets calculated	-	$\geq 0$ (Set to 1 for non multi-target routines)
num_los_target	long*	-	Number of LOS targets calculated	-	$\geq 0$
target_id	xp_target_id*	-	Structure that contains the Target results	-	-
ierr	long	-	Error vector	-	-

### 7.75.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_range_rate` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_range_rate` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 194: Error messages of `xp_target_range_rate` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Attitude Id. is not initialized	No calculation performed	XP_CFI_TARGET_RANGE_RATE_ATTITUDE_STATUS_ERR	0
ERR	Deriv flag is not correct	No calculation performed	XP_CFI_TARGET_RANGE_RATE_DERIV_FLAG_ERR	1
ERR	Invalid Range	No calculation performed	XP_CFI_TARGET_RANGE_RATE_RANGE_ERR	2
ERR	Invalid Geodetic Altitude	No calculation performed	XP_CFI_TARGET_RANGE_RATE_GEODETTIC_ALT_ERR	3
ERR	Input state vector does not satisfy loose tolerance	No calculation performed	XP_CFI_TARGET_RANGE	4

	requirement		E_RATE_INVALID_SV_ERR	
ERR	Memory allocation error	No calculation performed	XP_CFI_TARGET_RANGE_RATE_MEMORY_ERR	5
ERR	Time Reference not initialised	No calculation performed	XP_CFI_TARGET_RANGE_RATE_TIME_REF_INIT_ERR	6
ERR	Internal computation error #3	No calculation performed	XP_CFI_TARGET_RANGE_RATE_INITIAL_LOOK_DIR_OR_PLANE_ERR	7
ERR	No target was found	No calculation performed	XP_CFI_TARGET_RANGE_RATE_TARGET_NOT_FOUND_ERR	8
WARN	Input state vector does not satisfy tight tolerance requirement	Calculation performed. A message informs the user.	XP_CFI_TARGET_RANGE_RATE_INVALID_SV_WARN	9
WARN	Range rate algo only returns results without derivatives	Calculation performed. A message informs the user.	XP_CFI_TARGET_RANGE_RATE_DERIV_FLAG_WARN	10

## 7.76 xp\_target\_tangent

### 7.76.1 Overview

The `xp_target_tangent` CFI function computes the location of the tangent point over the Earth that is located on the line of sight defined by an elevation and azimuth angles expressed in the selected Attitude Frame.

The light travel time (from the satellite to the target or vice versa) can be taken into account by the computations. For details about light propagation mode see the section Error: Reference source not found.

### 7.76.2 Calling Interface

The calling interface of the `xp_target_tangent` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long          sat_id;
    xp_attitude_id attitude_id = {NULL};
    xp_atmos_id   atmos_id = {NULL};
    xp_dem_id     dem_id = {NULL};
    xp_target_id  target_id = {NULL};
    long deriv,   iray;
    double los_az, los_el, los_az_rate, los_el_rate, freq;
    long ierr[XP_NUM_ERR_TARGET_TANGENT], status, num_user_target,
        num_los_target;

    status = xp_target_tangent(&sat_id, &attitude_id,
                               &atmos_id, &dem_id,
                               &deriv, &los_az, &los_el,
                               &los_az_rate, &los_el_rate, &iray, &freq,
                               &num_user_target, &num_los_target,
                               &target_id, ierr);

    /* Or, using the run_id */
    long run_id;

    status = xp_target_tangent_run(&run_id, &attitude_id,
                                    &deriv, &los_az, &los_el,
                                    &los_az_rate, &los_el_rate, &iray, &freq,
```

```
&num_user_target, &num_los_target,  
&target_id, ierr);
```

```
}
```

The `XP_NUM_ERR_TARGET_TANGENT` constant is defined in the file *explorer\_pointing.h*.

### 7.76.3 Input Parameters

The `xp_target_tangent` CFI function has the following input parameters:

*Table 195: Input parameters of `xp_target_tangent` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>sat_id</code>	long *	-	Satellite ID	-	Complete
<code>attitude_id</code>	<code>xp_attitude_id*</code>	-	Structure that contains the Attitude. (input/output)	-	-
<code>atmos_id</code>	<code>xp_atmos_id*</code>	-	Structure that contains the atmosphere initialization.	-	-
<code>dem_id</code>	<code>xp_dem_id*</code>	-	Structure that contains the DEM initialization.	-	-
<code>deriv</code>	long *	-	Derivative ID	-	Allowed values: (0) XP_NO_DER (1) XP_DER_1ST (2) XP_DER_2ND
<code>los_az</code>	double *	-	Azimuth of the LOS (Attitude Frame)	deg	$\geq 0$ $< 360$
<code>los_el</code>	double *	-	Elevation of the LOS (Attitude Frame)	deg	$\geq -90$ $\leq 90$
<code>los_az_rate</code>	double *	-	Azimuth-rate of the LOS (Attitude Frame)	deg/s	-
<code>los_el_rate</code>	double *	-	Elevation-rate of the LOS (Attitude Frame)	deg/s	-
<code>iray</code>	long *	-	Not used. The atmosphere refraction model can be defined via <code>atmos_id</code> initialization.	-	-
<code>freq</code>	double *	-	Frequency of the signal	Hz	$\geq 0$

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Derivative switch: `deriv`. See current document, Table 3 .

## 7.76.4 Output Parameters

The output parameters of the `xp_target_tangent` CFI function are:

**Table 196: Output parameters of `xp_target_tangent`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
num_user_target	long*	-	Number of user defined targets calculated	-	$\geq 0$ (Set to 1 for non multi-target routines)
num_los_target	long*	-	Number of LOS targets calculated	-	$\geq 0$
target_id	xp_target_id*	-	Structure that contains the Target results	-	-
ierr	long	-	Error vector	-	-

## 7.76.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_tangent` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_tangent` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 197: Error messages of `xp_target_tangent` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Attitude Id. is not initialized	No calculation performed	XP_CFI_TARGET_TANGENT_ATTITUDE_STATUS_ERR	0
ERR	Deriv flag is not correct	No calculation performed	XP_CFI_TARGET_TANGENT_DERIV_FLAG_ERR	1
ERR	Invalid LOS Azimuth	No calculation performed	XP_CFI_TARGET_TANGENT_LOS_AZIMUTH_ERR	2
ERR	Invalid LOS Elevation	No calculation performed	XP_CFI_TARGET_TANGENT_LOS_ELEVATION_ERR	3
ERR	Ray Tracing Model ID is not correct	No calculation performed	XP_CFI_TARGET_TANGENT_IRAY_ID_ERR	4
ERR	Invalid Frequency	No calculation performed	XP_CFI_TARGET_TANGENT_	5

			FREQ_ERR	
ERR	Input state vector does not satisfy loose tolerance requirement	No calculation performed	XP_CFI_TARGET_TANGENT_INVALID_SV_ERR	6
ERR	Memory allocation error	No calculation performed	XP_CFI_TARGET_TANGENT_MEMORY_ERR	7
ERR	Internal computation error # 3	No calculation performed	XP_CFI_TARGET_TANGENT_INITIAL_LOOK_DIRECTION_PLANE_ERR	8
ERR	Time Reference not initialised	No calculation performed	XP_CFI_TARGET_TANGENT_TIME_REF_INIT_ERR	9
ERR	No target was found	No calculation performed	XP_CFI_TARGET_TANGENT_TARGET_NOT_FOUND_ERR	10
ERR	Error computing target when it is behind looking direction	No calculation performed	XP_CFI_TARGET_TANGENT_PT_BEHIND_LOOK_DIRECTION_ERR	11
ERR	Internal computation error # 4	No calculation performed	XP_CFI_TARGET_TANGENT_RANGE_OR_POINTING_CALC_ERR	12
WARN	Input state vector does not satisfy tight tolerance requirement	Calculation performed. A message informs the user.	XP_CFI_TARGET_TANGENT_INVALID_SV_WARN	13
WARN	Path from satellite to target occulted by the Earth	Calculation performed. A message informs the user.	XP_CFI_TARGET_TANGENT_NEGATIVE_ALTITUDE_WARN	14
WARN	Tangent point latitude is outside the selected corrective function latitude band	Calculation performed. A message informs the user.	XP_CFI_TARGET_TANGENT_PRED_WRONG_LAT_WARN	15
WARN	Tangent point is behind looking direction	Calculation performed. A message informs the user.	XP_CFI_TARGET_TANGENT_PT_BEHIND_LOOK_DIRECTION_WARN	16
WARN	The ray tracing flag (iray) is ignored	Calculation performed. A message informs the user that this parameter is not used. If the variable iray is equal to XP_NO_REF_INIT (=0), the warning is avoided	XP_CFI_TARGET_TANGENT_RAY_ID_WARN	17

## 7.77 xp\_target\_altitude

### 7.77.1 Overview

The `xp_target_altitude` CFI function computes the location of the tangent point over the Earth that is located on a surface at a certain geodetic altitude over the Earth and that is on a line of sight that forms a certain azimuth angle in the selected Attitude Frame.

The light travel time (from the satellite to the target or vice versa) can be taken into account by the computations. For details about light propagation mode see the section Error: Reference source not found.

### 7.77.2 Calling Interface

The calling interface of the `xp_target_altitude` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long          sat_id;
    xp_attitude_id attitude_id = {NULL};
    xp_atmos_id   atmos_id = {NULL};
    xp_dem_id     dem_id = {NULL};
    xp_target_id  target_id = {NULL};
    long deriv,   iray;
    double los_az, geod_alt, los_az_rate, freq;
    long ierr[XP_NUM_ERR_TARGET_ALTITUDE], status, num_user_target,
        num_los_target;

    status = xp_target_altitude(sat_id, &attitude_id,
                                &atmos_id, &dem_id,
                                &deriv, &los_az, &geod_alt,
                                &los_az_rate, &iray, &freq,
                                &num_user_target, &num_los_target,
                                &target_id, ierr);

    /* Or, using the run_id */
    long run_id;

    status = xp_target_altitude_run(run_id, &attitude_id,
                                    &deriv, &los_az, &geod_alt,
                                    &los_az_rate, &iray, &freq,
```



```
&num_user_target, &num_los_target,  
&target_id, ierr);
```

```
}
```

The `XP_NUM_ERR_TARGET_ALTITUDE` constant is defined in the file *explorer\_pointing.h*.

### 7.77.3 Input Parameters

The `xp_target_altitude` CFI function has the following input parameters:

*Table 198: Input parameters of `xp_target_altitude` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>sat_id</code>	long *	-	Satellite ID	-	Complete
<code>attitude_id</code>	<code>xp_attitude_id*</code>	-	Structure that contains the Attitude. (input/output)	-	-
<code>atmos_id</code>	<code>xp_atmos_id*</code>	-	Structure that contains the atmosphere initialization.	-	-
<code>dem_id</code>	<code>xp_dem_id*</code>	-	Structure that contains the DEM initialization.	-	-
<code>deriv</code>	long *	-	Derivative ID	-	Allowed values: (0) XP_NO_DER (1) XP_DER_1ST (2) XP_DER_2ND
<code>los_az</code>	double *	-	Azimuth of the LOS (Attitude Frame)	deg	$\geq 0$ $< 360$
<code>geod_alt</code>	double *	-	Geodetic altitude over the Earth	m	$\geq -bWGS$
<code>los_az_rate</code>	double *	-	Azimuth-rate of the LOS (Attitude Frame)	deg/s	-
<code>iray</code>	long *	-	Not used. The atmosphere refraction model can be defined via <code>atmos_id</code> initialization.	-	-
<code>freq</code>	double *	-	Frequency of the signal	Hz	$\geq 0$

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Derivative switch: `deriv`. See current document, Table 3 .

### 7.77.4 Output Parameters

The output parameters of the `xp_target_altitude` CFI function are:

**Table 199: Output parameters of `xp_target_altitude`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
num_user_target	long*	-	Number of user defined targets calculated	-	>= 0 (Set to 1 for non multi-target routines)
num_los_target	long*	-	Number of LOS targets calculated	-	>= 0
target_id	xp_target_id*	-	Structure that contains the Target results	-	-
ierr	long	-	Error vector	-	-

### 7.77.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_altitude` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_altitude` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 200: Error messages of `xp_target_altitude` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Attitude Id. is not initialized	No calculation performed	XP_CFI_TARGET_ALT_ATTITUDE_STATUS_ERR	0
ERR	Deriv flag is not correct	No calculation performed	XP_CFI_TARGET_ALT_DERIV_FLAG_ERR	1
ERR	Invalid LOS Azimuth	No calculation performed	XP_CFI_TARGET_ALT_LOS_AZIMUTH_ERR	2
ERR	Invalid Geodetic Altitude	No calculation performed	XP_CFI_TARGET_ALT_GEODETTIC_ALT_ERR	3
ERR	Ray Tracing Model ID is not correct	No calculation performed	XP_CFI_TARGET_ALT_IRRAY_ID_ERR	4
ERR	Invalid Frequency	No calculation performed	XP_CFI_TARGET_ALT_FR	5

			EQ_ERR	
ERR	Input state vector does not satisfy loose tolerance requirement	No calculation performed	XP_CFI_TARGET_ALT_INVALID_SV_ERR	6
ERR	Memory allocation error	No calculation performed	XP_CFI_TARGET_ALT_MEMORY_ERR	7
ERR	Time Reference not initialised	No calculation performed	XP_CFI_TARGET_ALT_TIME_REF_INIT_ERR	8
ERR	Internal computation error #3	No calculation performed	XP_CFI_TARGET_ALT_INITIAL_LOOK_DIR_OR_PLANE_ERR	9
ERR	No target was found	No calculation performed	XP_CFI_TARGET_ALT_TARGET_NOT_FOUND_ERR	10
ERR	Internal computation error #4	No calculation performed	XP_CFI_TARGET_ALT_RANGE_OR_POINTING_CALC_ERR	11
WARN	Input state vector does not satisfy tight tolerance requirement	Calculation performed. A message informs the user.	XP_TARGET_ALT_INVALID_SV_WARN	12
WARN	Path from satellite to target occulted by the Earth	Calculation performed. A message informs the user.	XP_CFI_TARGET_ALT_NEGATIVE_ALTITUDE_WARN	13
WARN	Tangent point latitude is outside the selected corrective function latitude band	Calculation performed. A message informs the user.	XP_CFI_TARGET_ALT_PRED_WRONG_LAT_WARN	14
WARN	The ray tracing flag (iray) is ignored	Calculation performed. A message informs the user that this parameter is not used. If the variable iray is equal to XP_NO_REF_INIT (=0), the warning is avoided.	XP_CFI_TARGET_ALT_IRAY_INVALID_WARN	15

## 7.78 xp\_target\_star

### 7.78.1 Overview

The `xp_target_star` CFI function computes the location of the tangent point over the Earth that is located on the line of sight that points to a star defined by its right ascension and declination coordinates.

The light travel time (from the satellite to the target or vice versa) can be taken into account by the computations. For details about light propagation mode see the section Error: Reference source not found.

### 7.78.2 Calling Interface

The calling interface of the `xp_target_star` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long          sat_id;
    xp_attitude_id attitude_id = {NULL};
    xp_atmos_id   atmos_id = {NULL};
    xp_dem_id     dem_id = {NULL};
    xp_target_id  target_id = {NULL};
    long deriv, iray;
    double star_ra, star_dec, star_ra_rate, star_dec_rate, freq;
    long ierr[XP_NUM_ERR_TARGET_STAR], status, num_user_target,
        num_los_target;

    status = xp_target_star(&sat_id, &attitude_id,
        &atmos_id, &dem_id,
        &deriv, &star_ra, star_dec,
        &star_ra_rate, &star_dec_rate, &iray, &freq,
        &num_user_target, &num_los_target,
        &target_id, ierr);

    /* Or, using the run_id */
    long run_id;

    status = xp_target_star_run(&run_id, &attitude_id,
        &deriv, &star_ra, star_dec,
        &star_ra_rate, &star_dec_rate, &iray, &freq,
        &num_user_target, &num_los_target,
        &target_id, ierr);
}
```

}

The `XP_NUM_ERR_TARGET_STAR` constant is defined in the file *explorer\_pointing.h*.

### 7.78.3 Input Parameters

The `xp_target_star` CFI function has the following input parameters:

*Table 201: Input parameters of `xp_target_star` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>sat_id</code>	long *	-	Satellite ID	-	Complete
<code>attitude_id</code>	<code>xp_attitude_id*</code>	-	Structure that contains the Attitude. (input/output)	-	-
<code>atmos_id</code>	<code>xp_atmos_id*</code>	-	Structure that contains the atmosphere initialization.	-	-
<code>dem_id</code>	<code>xp_dem_id*</code>	-	Structure that contains the DEM initialization.	-	-
<code>deriv</code>	long *	-	Derivative ID	-	Allowed values: (0) XP_NO_DER (1) XP_DER_1ST (2) XP_DER_2ND
<code>star_ra</code>	double *	-	Right ascension of the star (True of Date CS)	deg	$\geq 0$ $< 360$
<code>star_dec</code>	double *	-	Declination of the star (True of Date CS)	deg	$\geq -90$ $\leq +90$
<code>star_ra_rate</code>	double *	-	Right ascension rate of the star (True of Date CS)	deg/s	-
<code>star_dec_rate</code>	double *	-	Declination rate of the star (True of Date CS)	deg/s	-
<code>iray</code>	long *	-	Not used. The atmosphere refraction model can be defined via <code>atmos_id</code> initialization.	-	-
<code>freq</code>	double *	-	Frequency of the signal	Hz	$\geq 0$

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Derivative switch: `deriv`. See current document, Table 3 .

### 7.78.4 Output Parameters

The output parameters of the `xp_target_star` CFI function are:

**Table 202: Output parameters of `xp_target_star`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
num_user_target	long*	-	Number of user defined targets calculated	-	$\geq 0$ (Set to 1 for non multi-target routines)
num_los_target	long*	-	Number of LOS targets calculated	-	$\geq 0$
target_id	xp_target_id*	-	Structure that contains the Target results	-	-
ierr	long	-	Error vector	-	-

### 7.78.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_star` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_star` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 203: Error messages of `xp_target_star` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Attitude Id. is not initialized	No calculation performed	XP_CFI_TARGET_STAR_ATTITUDE_STATUS_ERR	0
ERR	Deriv flag is not correct	No calculation performed	XP_CFI_TARGET_STAR_DERIV_FLAG_ERR	1
ERR	Invalid Right Ascension of the star	No calculation performed	XP_CFI_TARGET_STAR_RA_ERR	2
ERR	Invalid Declination of the star	No calculation performed	XP_CFI_TARGET_STAR_DEC_ERR	3
ERR	Ray Tracing Model ID is not correct	No calculation performed	XP_CFI_TARGET_STAR_IRAY_ID_ERR	4
ERR	Invalid Frequency	No calculation performed	XP_CFI_TARGET_STAR_FREQ_ERR	5



			REQ_ERR	
ERR	Input state vector does not satisfy loose tolerance requirement	No calculation performed	XP_CFI_TARGET_STAR_I NVALID_SV_ERR	6
ERR	Memory allocation error	No calculation performed	XP_CFI_TARGET_STAR_ MEMORY_ERR	7
ERR	Internal computation error # 3	No calculation performed	XP_CFI_TARGET_STAR_I NITIAL_LOOK_DIR_OR_P LANE_ERR	8
ERR	Time reference ID is not correct	No calculation performed	XP_CFI_TARGET_STAR_T IME_REF_INIT_ERR	9
ERR	No target was found	No calculation performed	XP_CFI_TARGET_STAR_T ARGET_NOT_FOUND_ER R	10
ERR	Tangent point is behind looking direction	No calculation performed	XP_CFI_TARGET_STAR_T G_PT_BEHIND_LOOK_DIR _ERR	11
ERR	Internal computation error # 4	No calculation performed	XP_CFI_TARGET_STAR_R ANGE_OR_POINTING_CA LC_ERR	12
WARN	Input state vector does not satisfy tight tolerance requirement	Calculation performed. A message informs the user.	XP_CFI_TARGET_STAR_I NVALID_SV_WARN	13
WARN	Path from satellite to target occulted by the Earth	Calculation performed. A message informs the user.	XP_CFI_TARGET_STAR_N EGATIVE_ALTITUDE_WA RN	14
WARN	Tangent point latitude is outside the selected corrective function latitude band	Calculation performed. A message informs the user.	XP_CFI_TARGET_STAR_P RED_WRONG_LAT_WA RN	15
WARN	Tangent point is behind looking direction		XP_CFI_TARGET_STAR_TG_ PT_BEHIND_LOOK_DIR_WA RN	16
WARN	The ray tracing flag (iray) is ignored	Calculation performed. A message informs the user that this parameter is not used. If the variable iray is equal to XP_NO_REF_INIT (=0), the warning is avoided	XP_CFI_TARGET_STAR_IRAY _ID_WARN	17

## 7.79 xp\_target\_station

### 7.79.1 Overview

The **xp\_target\_station** CFI function computes the most relevant observation parameters of the link between the satellite and a ground station.

The light travel time (from the satellite to the target or vice versa) can be taken into account by the computations. For details about light propagation mode see the section Error: Reference source not found.

### 7.79.2 Calling Interface

The calling interface of the **xp\_target\_station** CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long          sat_id;
    xp_attitude_id attitude_id = {NULL};
    xp_dem_id      dem_id = {NULL};
    xp_target_id   target_id = {NULL};
    long deriv;
    double geoc_long, geod_lat, geod_alt, min_link_el;
    long ierr[XP_NUM_ERR_TARGET_STATION], status, num_user_target,
        num_los_target;

    status = xp_target_station(&sat_id,
        &attitude_id, &dem_id,
        &deriv, &geoc_long, &geod_lat,
        &geod_alt, &min_link_el,
        &num_user_target, &num_los_target,
        &target_id, ierr);

    /* Or, using the run_id */
    long run_id;

    status = xp_target_station_run(&run_id,
        &attitude_id,
        &deriv, &geoc_long, &geod_lat,
        &geod_alt, &min_link_el,
        &num_user_target, &num_los_target,
```

```
        &target_id, ierr);  
    }
```

The `XP_NUM_ERR_TARGET_STATION` constant is defined in the file *explorer\_pointing.h*.

### 7.79.3 Input Parameters

The `xp_target_station` CFI function has the following input parameters:

*Table 204: Input parameters of `xp_target_station` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>sat_id</code>	long *	-	Satellite ID	-	Complete
<code>attitude_id</code>	<code>xp_attitude_id*</code>	-	Structure that contains the Attitude. (input/output)	-	-
<code>dem_id</code>	<code>xp_dem_id*</code>	-	Structure that contains the DEM initialization.	-	-
<code>deriv</code>	long *	-	Derivative ID	-	Allowed values: (0) XP_NO_DER (1) XP_DER_1ST (2) XP_DER_2ND
<code>geoc_long</code>	double *	-	GS geocentric longitude (Earth fixed CS)	deg	$\geq 0$ $< 360$
<code>geod_lat</code>	double *	-	GS geodetic latitude (Earth fixed CS)	deg	$\geq -90$ $\leq 90$
<code>geod_alt</code>	double *	-	GS geodetic altitude (Earth fixed CS)	m	$\geq -bWGS$
<code>min_link_el</code>	double *	-	GS minimum link elevation (Topocentric CS)	deg	$\geq -90$ $\leq 90$

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Derivative switch: `deriv`. See current document, Table 3 .

### 7.79.4 Output Parameters

The output parameters of the `xp_target_station` CFI function are:

**Table 205: Output parameters of `xp_target_station`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
num_user_target	long*	-	Number of user defined targets calculated	-	>= 0 (Set to 1 for non multi-target routines)
num_lostarget	long*	-	Number of LOS targets calculated	-	>= 0
target_id	xp_target_id*	-	Structure that contains the Target results	-	-
ierr	long	-	Error vector	-	-

### 7.79.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_station` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_station` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 206: Error messages of `xp_target_station` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Attitude Id. is not initialized	No calculation performed	XP_CFI_TARGET_STATION_ATTITUDE_STATUS_ERR	0
ERR	Deriv flag is not correct	No calculation performed	XP_CFI_TARGET_STATION_DERIV_FLAG_ERR	1
ERR	Invalid GS Geocentric Longitude	No calculation performed	XP_CFI_TARGET_STATION_GEOC_LONG_ERR	2
ERR	Invalid GS Geodetic Latitude	No calculation performed	XP_CFI_TARGET_STATION_GEOD_LAT_ERR	3
ERR	Invalid GS Geodetic Altitude	No calculation performed	XP_CFI_TARGET_STATION_GEODETTIC_ALT_ERR	4
ERR	Invalid GS Minimum Link	No calculation performed	XP_CFI_TARGET_STATION	5

	Elevation		N_MIN_LINK_EL_ERR	
ERR	Input state vector does not satisfy loose tolerance requirement	No calculation performed	XP_CFI_TARGET_STATIO N_INVALID_SV_ERR	6
ERR	Memory allocation error	No calculation performed	XP_CFI_TARGET_STATIO N_MEMORY_ERR	7
ERR	Internal computation error #3	No calculation performed	XP_CFI_TARGET_STATIO N_STAVIS_COMP_FAILED _ERR	8
WARN	Input state vector does not satisfy tight tolerance requirement	Calculation performed. A message informs the user.	XP_CFI_TARGET_STATIO N_INVALID_SV_WARN	17

## 7.80 xp\_target\_generic

### 7.80.1 Overview

The `xp_target_generic` CFI function allows the user to provide the target location (position and velocity) and later calculate extra results from it.

The light travel time (from the satellite to the target or vice versa) can be taken into account by the computations. For details about light propagation mode see the section Error: Reference source not found.

### 7.80.2 Calling Interface

The calling interface of the `xp_target_generic` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long          sat_id;
    xp_attitude_id attitude_id = {NULL};
    xp_dem_id     dem_id = {NULL};
    xp_target_id  target_id = {NULL};
    long deriv;
    double targ_pos[3], targ_vel[3], targ_acc[3];
    long ierr[XP_NUM_ERR_TARGET_GENERIC], status, num_user_target,
        num_los_target;

    status = xp_target_generic(&sat_id,
        &attitude_id,
        &dem_id,
        &deriv, targ_pos, targ_vel, targ_acc,
        &num_user_target, &num_los_target,
        &target_id, ierr);

    /* Or, using the run_id */
    long run_id;

    status = xp_target_generic_run(&run_id,
        &attitude_id,
        &deriv, targ_pos, targ_vel, targ_acc,
        &num_user_target, &num_los_target,
        &target_id, ierr);
```

}

The `XP_NUM_ERR_TARGET_GENERIC` constant is defined in the file *explorer\_pointing.h*.

### 7.80.3 Input Parameters

The `xp_target_generic` CFI function has the following input parameters:

**Table 207: Input parameters of `xp_target_generic` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_id	long *	-	Satellite ID	-	Complete
attitude_id	xp_attitude_id*	-	Structure that contains the Attitude. (input/output)	-	-
dem_id	xp_dem_id*	-	Structure that contains the DEM initialization.	-	-
deriv	long *	-	Derivative ID	-	Allowed values: (0) XP_NO_DER (1) XP_DER_1ST (2) XP_DER_2ND
targ_pos	double[3]	[0-2]	Target position vector (Earth Fixed CS)	m	-
targ_vel	double[3]	[0-2]	Target velocity vector (Earth Fixed CS)	m/s	-
targ_acc	double[3]	[0-2]	Target acceleration vector (Earth Fixed CS)	m/s <sup>2</sup>	-

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Derivative switch: `deriv`. See current document, Table 3 .

### 7.80.4 Output Parameters

The output parameters of the `xp_target_generic` CFI function are:

**Table 208: Output parameters of `xp_target_generic`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
num_user_target	long*	-	Number of user defined targets calculated	-	>= 0 (Set to 1 for non multi-target routines)
num_los_tar	long*	-	Number of LOS targets calculated	-	>= 0



get					
target_id	xp_target_id*	-	Structure that contains the Target results	-	-
ierr	long	-	Error vector	-	-

### 7.80.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the **xp\_target\_generic** CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library **xp\_get\_msg** (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the **xp\_target\_generic** function by calling the function of the EO\_POINTING software library **xp\_get\_code** (see [GEN\_SUM]).

**Table 209: Error messages of xp\_target\_generic function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Attitude Id. is not initialized	No calculation performed	XP_CFI_TARGET_GENERIC_ATTITUDE_STATUS_ERR	0
ERR	Deriv flag is not correct	No calculation performed	XP_CFI_TARGET_GENERIC_DERIV_FLAG_ERR	1
ERR	Input state vector does not satisfy loose tolerance requirement	No calculation performed	XP_CFI_TARGET_GENERIC_INVALID_SV_ERR	2
ERR	Memory allocation error	No calculation performed	XP_CFI_TARGET_GENERIC_MEMORY_ERR	3
ERR	Internal computation error # 3	No calculation performed	XP_CFI_TARGET_GENERIC_INITIAL_LOOK_DIR_OR_PLANE_ERR	4
WARN	Input state vector does not satisfy tight tolerance requirement	Calculation performed. A message informs the user.	XP_CFI_TARGET_GENERIC_INVALID_SV_WARN	5

## 7.81 xp\_target\_reflected

### 7.81.1 Overview

The `xp_target_reflected` CFI function allows the user to compute, from S/C position and attitude, and emitting source position, the point of reflection from the source towards the SC at a certain geodetic altitude.

### 7.81.2 Calling Interface

The calling interface of the `xp_target_reflected` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long          sat_id, deriv, source_type;
    long          status, num_user_target, num_los_target;
    xp_attitude_id attitude_id = {NULL};
    xp_target_id  target_id = {NULL};
    double        geod_alt, deflection_north, deflection_east,
                 source_param[XP_NUM_SOURCE_PARAM];
    long          ierr[XP_NUM_ERR_TARGET_REFLECTED]

    status = xp_target_reflected( &sat_id, &attitude_id,
                                   &deriv, &geod_alt,
                                   &deflection_north, &deflection_east,
                                   &source_type, source_param,
                                   /* outputs */
                                   &num_user_target, &num_los_target,
                                   &target_id, ierr);

    /* Or, using the run_id */
    long run_id;
    status = xp_target_reflected_run( &run_id,
                                       &attitude_id, &deriv, &geod_alt,
                                       &deflection_north, &deflection_east,
                                       &source_type, source_param,
                                       /* outputs */
                                       &num_user_target, &num_los_target,
                                       &target_id, ierr);
```

}

The `XP_NUM_ERR_TARGET_GENERIC` constant is defined in the file *explorer\_pointing.h*.

### 7.81.3 Input Parameters

The `xp_target_reflected` CFI function has the following input parameters:

**Table 210: Input parameters of `xp_target_reflected` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>sat_id</code>	<code>long *</code>	-	Satellite ID	-	Complete
<code>attitude_id</code>	<code>xp_attitude_id*</code>	-	Structure that contains the Attitude. (input/output)	-	-
<code>deriv</code>	<code>long *</code>	-	Derivative ID	-	Allowed values: (0) <code>XP_NO_DER</code> (1) <code>XP_DER_1ST</code> (2) <code>XP_DER_2ND</code>
<code>geod_lat</code>	<code>double *</code>	-	GS geodetic latitude (Earth fixed CS)	deg	$\geq -90$ $\leq 90$
<code>deflection_north</code>	<code>double *</code>	-	North-South component of the vertical deflection	deg	$\geq -90$ $\leq 90$
<code>deflection_east</code>	<code>double *</code>	-	East-West component of the vertical deflection	deg	$\geq -90$ $\leq 90$
<code>source_type</code>	<code>long *</code>	-	The type of source	-	Allowed values: <code>XP_SOURCE_STAR</code> <code>XP_SOURCE_SUN</code> <code>XP_SOURCE_MOON</code> <code>XP_SOURCE_GENERIC</code>
<code>source_param</code>	<code>double[XP_NUM_SOURCE_PARAM]</code>	[0-5]	<ul style="list-style-type: none"> <li>if <code>source_type</code> is <code>XP_SRC_STAR</code> is selected, <code>source_param</code> = [ra (deg), dec (deg), paralax, 0.0, 0.0, 0.0], i.e. star coordinates in BM2000 CS.</li> <li>if <code>source_type</code> is <code>XP_SOURCE_GENERIC</code> <code>source_param</code> = [x, y, z, vx,vy,vz] position and velocity in EF</li> <li>else dummy values.</li> </ul>	Right ascension and declination in degrees.  Position vector in meters, velocity in meters/second	-

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Derivative switch: `deriv`. See current document, Table 3 .
- Source Identification: `source_type`. See current document, Table 3 .

### 7.81.4 Output Parameters

The output parameters of the `xp_target_reflected` CFI function are:

**Table 211: Output parameters of `xp_target_reflected`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>num_user_target</code>	<code>long*</code>	-	Number of user defined targets calculated	-	$\geq 0$ (Set to 1 for non multi-target routines)
<code>num_los_target</code>	<code>long*</code>	-	Number of LOS targets calculated	-	$\geq 0$
<code>target_id</code>	<code>xp_target_id*</code>	-	Structure that contains the Target results	-	-
<code>ierr</code>	<code>long</code>	-	Error vector	-	-

### 7.81.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_reflected` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_reflected` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 212: Error messages of `xp_target_reflected` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Attitude Id. is not initialized	No calculation performed	XP_CFI_TARGET_REFLECTED_ATTITUDE_STATUS_ERR	0
ERR	Error when calling <code>xp_target_star</code>	No calculation performed	XP_CFI_TARGET_REFLECTED_TARGET_STAR_ERR	1
ERR	Error when calling <code>xp_target_tangent_sun</code>	No calculation performed	XP_CFI_TARGET_REFLECTED_TARGET_TG_SUN_ERR	2
ERR	Error when calling	No calculation performed	XP_CFI_TARGET_REFLECT	3

	xp_target_tangent_moon		ED_TARGET_TG_MOON_ER R	
ERR	Error when calling xl_change_cart_cs	No calculation performed	XP_CFI_TARGET_REFLECT ED_CHANGE_CS_ERR	4
ERR	Could not get direction pointing	No calculation performed	XP_CFI_TARGET_REFLECT ED_DIR_POINT_ERR	5
ERR	Error when calling xp_target_tangent	No calculation performed	XP_CFI_TARGET_REFLECT ED_TARGET_TG_ERR	6
ERR	Wrong input parameter "source_type"	No calculation performed	XP_CFI_TARGET_REFLECT ED_WRONG_SRC_TYPE_ER R	7
ERR	Error when calling xp_target_extra_main	No calculation performed	XP_CFI_TARGET_REFLECT ED_TGT_EXTRA_MAIN_ER R	8
ERR	Target tangent altitude is less than the requested altitude	No calculation performed	XP_CFI_TARGET_REFLECT ED_WRONG_ALTITUDE_ER R	9
ERR	Could not get cartesian coordinates for the star	No calculation performed	XP_CFI_TARGET_REFLECT ED_RADEC_TO_CART_ERR	10
ERR	Could not get the Sun coordinates	No calculation performed	XP_CFI_TARGET_REFLECT ED_SUN_ERR	11
ERR	Could not get the Moon coordinates	No calculation performed	XP_CFI_TARGET_REFLECT ED_MOON_ERR	12
ERR	Iteration did not converge. Impossible to find the deflection point	No calculation performed	XP_CFI_TARGET_REFLECT ED_ITER_ERR	13
ERR	Could not compute GPM attitude frame	No calculation performed	XP_CFI_TARGET_REFLECT ED_SAT_NOM_ATT_INIT_E RR	14
ERR	Could not initialise the attitude frame	No calculation performed	XP_CFI_TARGET_REFLECT ED_ATT_INIT_ERR	15
ERR	Could not compute the attitude frame	No calculation performed	XP_CFI_TARGET_REFLECT ED_ATT_COMPUTE_ERR	16
ERR	Error when calling xp_target_extra_specular_reflection	No calculation performed	XP_CFI_TARGET_REFLECT ED_TGT_EXTRA_REF_ERR	17
ERR	Error when calling xp_target_inter	No calculation performed	XP_CFI_TARGET_REFLECT ED_TARGET_INTER_ERR	18
ERR	Error when calling xp_target_extra_vector	No calculation performed	XP_CFI_TARGET_REFLECT ED_TARGET_EXTRA_ERR	19
ERR	Error when calling xp_target_generic	No calculation performed	XP_CFI_TARGET_REFLECT ED_TARGET_GENERIC_ERR	20
ERR	Could not change EF coordinates to topocentric	No calculation performed	XP_CFI_TARGET_REFLECT ED_EF_TO_TOP_ERR	21
ERR	Could not change topocentric	No calculation performed	XP_CFI_TARGET_REFLECT	22

	coordinates to EF		ED_TOP_TO_EF_ERR	
ERR	Could not close target	No calculation performed	XP_CFI_TARGET_REFLECT ED_TGT_CLOSE_ERR	23
ERR	Could not close attitude	No calculation performed	XP_CFI_TARGET_REFLECT ED_ATT_CLOSE_ERR	24
ERR	Memory allocation error	No calculation performed	XP_CFI_TARGET_REFLECT ED_MEMORY_ERR	25
ERR	Could not compute the satellite to target range	No calculation performed	XP_CFI_TARGET_REFLECT ED_RANGE_CALC_ERR	26

## 7.82 xp\_target\_travel\_time

### 7.82.1 Overview

The `xp_target_travel_time` CFI function computes the point of the line or sight from the satellite (defined by an elevation and an azimuth angle expressed in the selected Attitude Frame) at a given travel time along the (curved) line of sight.

The light travel time (from the satellite to the target or vice versa) can be taken into account by the computations. For details about light propagation mode see the section Error: Reference source not found.

### 7.82.2 Calling Interface

The calling interface of the `xp_target_travel_time` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long          sat_id;
    xp_attitude_id attitude_id = {NULL};
    xp_atmos_id   atmos_id = {NULL};
    xp_dem_id     dem_id = {NULL};
    xp_target_id  target_id = {NULL};
    long deriv, iray;
    double los_az, los_el, travel_time
    double los_az_rate, los_el_rate, travel_time_rate, freq;
    long ierr[XP_NUM_ERR_TARGET_TRAVEL_TIME], status,
        num_user_target, num_los_target;

    status = xp_target_travel_time(&sat_id,
        &attitude_id,
        &atmos_id,
        &dem_id,
        &deriv, &los_az,
        &los_el, &travel_time, &los_az_rate, &los_el_rate,
        &travel_time_rate, &iray, &freq,
        &num_user_target, &num_los_target,
        &target_id, ierr);

    /* Or, using the run_id */
    long run_id;
```

```
status = xp_target_travel_time_run(&run_id,  
    &attitude_id,  
    &deriv, &los_az,  
    &los_el, &travel_time, &los_az_rate, &los_el_rate,  
    &travel_time_rate, &iray, &freq,  
    &num_user_target, &num_los_target,  
    &target_id, ierr);  
}
```

The `XP_NUM_ERR_TARGET_TRAVEL_TIME` constant is defined in the file *explorer\_pointing.h*.



### 7.82.3 Input Parameters

The `xp_target_travel_time` CFI function has the following input parameters:

**Table 213: Input parameters of `xp_target_travel_time` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>sat_id</code>	long *	-	Satellite ID	-	Complete
<code>attitude_id</code>	<code>xp_attitude_id*</code>	-	Structure that contains the Attitude. (input/output)	-	-
<code>atmos_id</code>	<code>xp_atmos_id*</code>	-	Structure that contains the atmosphere initialization.	-	The <code>atmos_id</code> has to be initialized with any of these modes: - <code>XP_NO_REF_INIT</code> - <code>XP_STD_INIT</code> - <code>XP_USER_INIT</code>
<code>dem_id</code>	<code>xp_dem_id*</code>	-	Structure that contains the DEM initialization.	-	-
<code>deriv</code>	long *	-	Derivative ID	-	Allowed values: (0) <code>XP_NO_DER</code> (1) <code>XP_DER_1ST</code> (2) <code>XP_DER_2ND</code>
<code>los_az</code>	double *	-	Azimuth of the LOS (Attitude Frame)	deg	$\geq 0$ $< 360$
<code>los_el</code>	double *	-	Elevation of the LOS (Attitude Frame)	deg	$\geq -90$ $\leq 90$
<code>travel_time</code>	double *	-	Travel time along the (curved) line of sight	s	$> 0$
<code>los_az_rate</code>	double *	-	Azimuth-rate of the LOS (Attitude Frame)	deg/s	-
<code>los_el_rate</code>	double *	-	Elevation-rate of the LOS (Attitude Frame)	deg/s	-
<code>travel_time_rate</code>	double *	-	Travel time-rate along the (curved) line of sight	s/s	-
<code>iray</code>	long *	-	Not used. The atmosphere refraction model can be defined via <code>atmos_id</code> initialization.	-	-
<code>freq</code>	double *	-	Frequency of the signal	Hz	$\geq 0$

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Derivative switch: deriv. See current document, Table 3 .

### 7.82.4 Output Parameters

The output parameters of the `xp_target_travel_time` CFI function are:

**Table 214: Output parameters of `xp_target_travel_time`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
num_user_target	long*	-	Number of user defined targets calculated	-	>= 0 (Set to 1 for non multi-target routines)
num_los_target	long*	-	Number of LOS targets calculated	-	>= 0
target_id	xp_target_id*	-	Structure that contains the Target results	-	-
ierr	long	-	Error vector	-	-

### 7.82.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_travel_time` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_travel_time` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 215: Error messages of `xp_target_travel_time` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Attitude Id. is not initialized	No calculation performed	XP_CFI_TARGET_TRAVEL_TIME_ATTITUDE_STATUS_ERR	0
ERR	Intersection flag is not correct	No calculation performed	XP_CFI_TARGET_TRAVEL_TIME_INTER_FLAG_ERR	1
ERR	Invalid Frequency	No calculation performed	XP_CFI_TARGET_TRAVEL_TIME_FREQ_ERR	2
ERR	Time reference ID is not	No calculation performed	XP_CFI_TARGET_TRAVE	3

	correct		L_TIME_TIME_REF_ERR	
ERR	Deriv flag is not correct	No calculation performed	XP_CFI_TARGET_TRAVE L_TIME_DERIV_FLAG_ER R	4
ERR	Ray Tracing Model ID is not correct	No calculation performed	XP_CFI_TARGET_TRAVE L_TIME_IRAY_ID_ERR	5
ERR	Input state vector does not satisfy loose tolerance requirement	No calculation performed	XP_CFI_TARGET_TRAVE L_TIME_INVALID_SV_ER R	6
ERR	Invalid LOS Azimuth	No calculation performed	XP_CFI_TARGET_TRAVE L_TIME_LOS_AZIMUTH_E RR	7
ERR	Invalid LOS Elevation	No calculation performed	XP_CFI_TARGET_TRAVE L_TIME_LOS_ELEVATION _ERR	8
ERR	Invalid Geodetic Altitude	No calculation performed	XP_CFI_TARGET_TRAVE L_TIME_GEODETTIC_ALT_ ERR	9
ERR	Memory allocation error	No calculation performed	XP_CFI_TARGET_TRAVE L_TIME_MEMORY_ERR	10
ERR	Internal computation error # 3	No calculation performed	XP_CFI_TARGET_TRAVE L_TIME_INITIAL_LOOK_ DIR_OR_PLANE_ERR	11
ERR	Time Reference not initialised	No calculation performed	XP_CFI_TARGET_TRAVE L_TIME_TIME_REF_INIT_ ERR	12
ERR	No target was found	No calculation performed	XP_CFI_TARGET_TRAVE L_TIME_TARGET_NOT_F OUND_ERR	13
ERR	Internal computation error # 4	No calculation performed	XP_CFI_TARGET_TRAVE L_TIME_RANGE_OR_POI NTING_CALC_ERR	14
WARN	Input state vector does not satisfy tight tolerance requirement	Calculation performed. A message informs the user.	XP_CFI_TARGET_TRAVE L_TIME_INVALID_SV_WA RN	15
WARN	Path from satellite to target occulted by the Earth	Calculation performed. A message informs the user.	XP_CFI_TARGET_TRAVE L_TIME_NEGATIVE_ALTI TUDE_WARN	16
WARN	The ray tracing flag (iray) is ignored	Calculation performed. A message informs the user that this parameter is not used. If the variable iray is equal to XP_NO_REF_INIT (=0), the warning is avoided	XP_CFI_TARGET_TRAVEL_TI ME_IRAY_ID_WARN	17



## 7.83 xp\_target\_tangent\_sun

### 7.83.1 Overview

The `xp_target_tangent_sun` CFI function computes the location of the tangent point over the Earth that is located on the line of sight that points to the Sun.

Note: a correction can be applied in order to compensate the travel time of Sun light travel time. This correction is not applied with default model. To activate this correction, the Sun model in `xl_model_id` must be initialized with the enum `XL_MODEL_SUN_TRAVEL_TIME` using the function `xl_model_init` (see `[LIB_SUM]`).

The light travel time (from the satellite to the target or vice versa) can be taken into account by the computations. For details about light propagation mode see the section `Error: Reference source not found`.

### 7.83.2 Calling Interface

The calling interface of the `xp_target_tangent_sun` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long          sat_id;
    xp_attitude_id attitude_id = {NULL};
    xp_atmos_id   atmos_id = {NULL};
    xp_dem_id     dem_id = {NULL};
    xp_target_id  target_id = {NULL};
    long deriv,   iray;
    double freq;
    long ierr[XP_NUM_ERR_TARGET_TANGENT_SUN], status,
        num_user_target, num_los_target;

    status = xp_target_tangent_sun(&sat_id,
                                   &attitude_id, &atmos_id, &dem_id,
                                   &deriv, &iray, &freq,
                                   &num_user_target, &num_los_target,
                                   &target_id, ierr);

    /* Or, using the run_id */
    long run_id;

    status = xp_target_tangent_sun_run(&run_id,
```

```
    &attitude_id,  
    &deriv, &iray, &freq,  
    &num_user_target, &num_los_target,  
    &target_id, ierr);  
}
```

The XP\_NUM\_ERR\_TARGET\_TANGENT\_SUN constant is defined in the file *explorer\_pointing.h*.

### 7.83.3 Input Parameters

The `xp_target_tangent_sun` CFI function has the following input parameters:

**Table 216: Input parameters of `xp_target_tangent_sun` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_id	long *	-	Satellite ID	-	Complete
attitude_id	xp_attitude_id*	-	Structure that contains the Attitude. (input/output)	-	-
atmos_id	xp_atmos_id*	-	Structure that contains the atmosphere initialization.	-	-
dem_id	xp_dem_id*	-	Structure that contains the DEM initialization.	-	-
deriv	long *	-	Derivative ID	-	Allowed values: (0) XP_NO_DER (1) XP_DER_1ST (2) XP_DER_2ND
iray	long *	-	Not used. The atmosphere refraction model can be defined via <code>atmos_id</code> initialization.	-	-
freq	double *	-	Frequency of the signal	Hz	$\geq 0$

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Derivative switch: `deriv`. See current document, Table 3 .

### 7.83.4 Output Parameters

The output parameters of the `xp_target_tangent_sun` CFI function are:

**Table 217: Output parameters of `xp_target_tangent_sun`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
num_user_target	long*	-	Number of user defined targets calculated	-	$\geq 0$ (Set to 1 for non multi-target routines)
num_los_target	long*	-	Number of LOS targets calculated	-	$\geq 0$
target_id	xp_target_id*	-	Structure that contains the Target results	-	-
ierr	long	-	Error vector	-	-

### 7.83.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_tangent_sun` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_tangent_sun` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 218: Error messages of `xp_target_tangent_sun` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Attitude ID is not initialized	No calculation performed	XP_CFI_SUN_ATTITUDE_STATUS_ERR	0
ERR	Deriv flag is not correct	No calculation performed	XP_CFI_SUN_DERIV_FLAG_ERR	1
ERR	Ray Tracing Model ID is not correct	No calculation performed	XP_CFI_SUN_IRAY_ID_ERR	2
ERR	Invalid Frequency	No calculation performed	XP_CFI_SUN_FREQ_ERR	3
ERR	Input state vector does not satisfy loose tolerance requirement	No calculation performed	XP_CFI_SUN_INVALID_SV_ERR	4
ERR	Time Reference not initialised	No calculation performed	XP_CFI_SUN_TIME_REF_INIT_ERR	5
ERR	Internal computation error # 1	No calculation performed	XP_CFI_SUN_SUN_POSITION_CALC_ERR	6
ERR	Internal computation error # 2	No calculation performed	XP_CFI_SUN_SUN_CS_CALC_ERR	7
ERR	Internal computation error # 3	No calculation performed	XP_CFI_SUN_SUN_POINTING_CALC_ERR	8
ERR	Internal computation error # 4	No calculation performed	XP_CFI_SUN_TARGET_STAR_ERR	9
ERR	Internal computation error # 5	No calculation performed	XP_CFI_SUN_TG_PT_BEHIND_LOOK_DIR_ERR	10
WARN	Input state vector does not satisfy tight tolerance requirement	Calculation performed. A message informs the user.	XP_CFI_SUN_INVALID_SV_WARN	11



WARN	Tangent point is behind looking direction	Calculation performed. A message informs the user.	XP_CFI_SUN_TG_PT_BEHI ND_LOOK_DIR_WARN	12
WARN	The ray tracing flag (iray) is ignored	Calculation performed. A message informs the user that this parameter is not used. If the variable iray is equal to XP_NO_REF_INIT (=0), the warning is avoided.	XP_CFI_SUN_IRAY_ID_WARN	13

## 7.84 xp\_target\_tangent\_moon

### 7.84.1 Overview

The `xp_target_tangent_moon` CFI function computes the location of the tangent point over the Earth that is located on the line of sight that points to the Moon.

### 7.84.2 Calling Interface

The calling interface of the `xp_target_tangent_moon` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
{
    long          sat_id;
    xp_attitude_id attitude_id = {NULL};
    xp_atmos_id   atmos_id = {NULL};
    xp_dem_id     dem_id = {NULL};
    xp_target_id  target_id = {NULL};
    long deriv,   iray;
    double freq;
    long ierr[XP_NUM_ERR_TARGET_TANGENT_MOON], status,
        num_user_target, num_los_target;

    status = xp_target_tangent_moon(&sat_id,
        &attitude_id, &atmos_id, &dem_id,
        &deriv, &iray, &freq,
        &num_user_target, &num_los_target,
        &target_id, ierr);

    /* Or, using the run_id */
    long run_id;

    status = xp_target_tangent_moon_run(&run_id,
        &attitude_id,
        &deriv, &iray, &freq,
        &num_user_target, &num_los_target,
        &target_id, ierr);
}
}
```

The `XP_NUM_ERR_TARGET_TANGENT_MOON` constant is defined in the file *explorer\_pointing.h*.

### 7.84.3 Input Parameters

The `xp_target_tangent_moon` CFI function has the following input parameters:

**Table 219: Input parameters of `xp_tangent_target_moon` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_id	long *	-	Satellite ID	-	Complete
attitude_id	xp_attitude_id*	-	Structure that contains the Attitude. (input/output)	-	-
atmos_id	xp_atmos_id*	-	Structure that contains the atmosphere initialization.	-	-
dem_id	xp_dem_id*	-	Structure that contains the DEM initialization.	-	-
deriv	long *	-	Derivative ID	-	Allowed values: (0) XP_NO_DER (1) XP_DER_1ST (2) XP_DER_2ND
iray	long *	-	Not used. The atmosphere refraction model can be defined via <code>atmos_id</code> initialization.	-	-
freq	double *	-	Frequency of the signal	Hz	>= 0

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Derivative switch: `deriv`. See current document, Table 3 .

### 7.84.4 Output Parameters

The output parameters of the `xp_target_tangent_moon` CFI function are:

**Table 220: Output parameters of `xp_tangent_target_moon`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
num_user_target	long*	-	Number of user defined targets calculated	-	>= 0 (Set to 1 for non multi-target routines)
num_los_target	long*	-	Number of LOS targets calculated	-	>= 0

target_id	xp_target_id*	-	Structure that contains the Target results	-	-
ierr	long	-	Error vector	-	-

### 7.84.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the **xp\_target\_tangent\_moon** CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library **xp\_get\_msg** (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the **xp\_target\_tangent\_moon** function by calling the function of the EO\_POINTING software library **xp\_get\_code** (see [GEN\_SUM]).

**Table 221: Error messages of xp\_target\_tangent\_moon function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Attitude ID is not initialized	No calculation performed	XP_CFI_MOON_ATTITUDE_STATUS_ERR	0
ERR	Deriv flag is not correct	No calculation performed	XP_CFI_MOON_DERIV_FLAG_ERR	1
ERR	Ray Tracing Model ID is not correct	No calculation performed	XP_CFI_MOON_IRAY_ID_ERR	2
ERR	Invalid Frequency	No calculation performed	XP_CFI_MOON_FREQ_ERR	3
ERR	Input state vector does not satisfy loose tolerance requirement	No calculation performed	XP_CFI_MOON_INVALID_STATE_VECTOR_ERR	4
ERR	Time Reference not initialised	No calculation performed	XP_CFI_MOON_TIME_REFERENCE_INIT_ERR	5
ERR	Internal computation error #1	No calculation performed	XP_CFI_MOON_MOON_POSITION_CALC_ERR	6
ERR	Internal computation error #2	No calculation performed	XP_CFI_MOON_MOON_CS_CALC_ERR	7
ERR	Internal computation error #3	No calculation performed	XP_CFI_MOON_MOON_POINTING_CALC_ERR	8
ERR	Internal computation error #4	No calculation performed	XP_CFI_MOON_TARGET_STAR_ERR	9
ERR	Internal computation error #5	No calculation performed	XP_CFI_MOON_TARGET_PT_BE	10

			HIND_LOOK_DIR_ERR	
WARN	Input state vector does not satisfy tight tolerance requirement	Calculation performed. A message informs the user.	XP_CFI_MOON_INVALID_SV_WARN	11
WARN	Tangent point is behind looking direction	Calculation performed. A message informs the user.	XP_CFI_MOON_TG_PT_BE HIND_LOOK_DIR_WARN	12
WARN	The ray tracing flag (iray) is ignored	Calculation performed. A message informs the user that this parameter is not used. If the variable iray is equal to XP_NO_REF_INIT (=0), the warning is avoided.	XP_CFI_MOON_IRAY_ID_WARN	13

## 7.85 xp\_target\_sc

### 7.85.1 Overview

The `xp_target_sc` CFI function computes the pointing from one satellite to another satellite.

The light travel time (from the satellite to the target or vice versa) can be taken into account by the computations. For details about light propagation mode see the section Error: Reference source not found.

### 7.85.2 Calling Interface

The calling interface of the `xp_target_sc` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long sat_id1, sat_id2;
    xp_attitude_id attitude_id1 = {NULL};
    xp_attitude_id attitude_id2 = {NULL};
    xp_target_id target_id = {NULL};
    long deriv;
    long ierr[XP_NUM_ERR_TARGET_SC], status, num_user_target,
        num_los_target;

    status = xp_target_sc(&sat_id1, &attitude_id1,
                        &sat_id2, &attitude_id2,
                        &deriv,
                        &num_user_target, &num_los_target,
                        &target_id, ierr);
}
```

The `XP_NUM_ERR_TARGET_SC` constant is defined in the file `explorer_pointing.h`.

### 7.85.3 Input Parameters

The `xp_target_sc` CFI function has the following input parameters:

**Table 222: Input parameters of `xp_target_sc` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_id1	long *	-	Satellite ID of source satellite	-	Complete
attitude_id1	xp_attitude_id*	-	Structure that contains the Attitude (input/output) of source satellite	-	-

sat_id2	long *	-	Satellite ID of target satellite	-	Complete
attitude_id2	xp_attitude_id*	-	Structure that contains the Attitude (input/output) of target satellite	-	-
deriv	long *	-	Derivative ID	-	Allowed values: (0) XP_NO_DER (1) XP_DER_1ST (2) XP_DER_2ND

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Derivative switch: deriv. See current document, Table 3.

### 7.85.4 Output Parameters

The output parameters of the `xp_target_sc` CFI function are:

*Table 223: Output parameters of xp\_target\_sc*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
num_user_target	long*	-	Number of user defined targets calculated	-	>= 0 (Set to 1 for non multi-target routines)
num_los_target	long*	-	Number of LOS targets calculated	-	>= 0
target_id	xp_target_id*	-	Structure that contains the Target results	-	-
ierr	long	-	Error vector	-	-

### 7.85.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_sc` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_sc` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 224: Error messages of xp\_target\_sc function**

<b>Error type</b>	<b>Error message</b>	<b>Cause and impact</b>	<b>Error code</b>	<b>Error No</b>
ERR	Attitude Id. is not initialized	No calculation performed	XP_CFI_TARGET_SC_ATTITUDE_STATUS_ERR	0
ERR	Deriv flag is not correct	No calculation performed	XP_CFI_TARGET_SC_DERIV_FLAG_ERR	1
ERR	Input state vector does not satisfy loose tolerance requirement	No calculation performed	XP_CFI_TARGET_SC_INVALID_SV_ERR	2
WARN	Input state vector does not satisfy tight tolerance requirement	Calculation performed. A message informs the user	XP_CFI_TARGET_SC_INVALID_SV_WARN	3
ERR	Error in call to xp_target_generic	No calculation performed	XP_CFI_TARGET_SC_TARGET_GENERIC_ERR	4
ERR	Error changing reference frame	No calculation performed.	XP_CFI_TARGET_SC_CHANGE_FRAME_ERR	5
ERR	Error computing pointing parameters	No calculation performed	XP_CFI_TARGET_SC_POINTING_PARAMETERS_COMPUTE_ERR	6



## 7.86 xp\_multi\_target\_inter

### 7.86.1 Overview

The `xp_multi_target_inter` CFI function computes the first or the second intersection points of the line of sight from the satellite (defined by an elevation and an azimuth angle expressed in the selected Attitude Frame) with surfaces located at certain geodetic altitudes over the Earth.

The light travel time (from the satellite to the target or vice versa) can be taken into account by the computations. For details about light propagation mode see the section Error: Reference source not found.

### 7.86.2 Calling Interface

The calling interface of the `xp_multi_target_inter` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long          sat_id;
    xp_attitude_id attitude_id = {NULL};
    xp_atmos_id   atmos_id = {NULL};
    xp_dem_id     dem_id = {NULL};
    xp_target_id  target_id = {NULL};
    long deriv, inter_flag, iray;
    double los_az, los_el, geod_alt[XP_MAX_NUM_MULTI_TARGET],
           los_az_rate, los_el_rate, freq;
    long ierr[XP_NUM_ERR_MULTI_TARGET_INTER], num_target, status
          num_user_target, num_los_target;

    status = xp_multi_target_inter(&sat_id,
                                   &attitude_id,
                                   &atmos_id,
                                   &dem_id,
                                   &deriv, &inter_flag, &los_az,
                                   &los_el, &num_target, geod_alt, &los_az_rate,
                                   &los_el_rate, &iray, &freq,
                                   &num_user_target, &num_los_target,
                                   &target_id, ierr);

    /* Or, using the run_id */
    long run_id;
```

```
status = xp_multi_target_inter_run(&run_id,  
    &attitude_id,  
    &deriv, &inter_flag, &los_az,  
    &los_el, &num_target, geod_alt, &los_az_rate,  
    &los_el_rate, &iray, &freq,  
    &num_user_target, &num_los_target,  
    &target_id, ierr);  
}
```

The `XP_NUM_ERR_MULTI_TARGET_INTER` constant is defined in the file *explorer\_pointing.h*.

### 7.86.3 Input Parameters

The `xp_multi_target_inter` CFI function has the following input parameters:

**Table 225: Input parameters of `xp_multi_target_inter` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_id	long *	-	Satellite ID	-	Complete
attitude_id	xp_attitude_id*	-	Structure that contains the Attitude. (input/output)	-	-
atmos_id	xp_atmos_id*	-	Structure that contains the atmosphere initialization.	-	The atmos_id has to be initialized with any of these modes: - XP_NO_REF_INIT - XP_STD_INIT - XP_USER_INIT
dem_id	xp_dem_id *	-	Structure that contains the DEM initialization.	-	-
deriv	long *	-	Derivative ID	-	Allowed values: (0) XP_NO_DER (1) XP_DER_1ST (2) XP_DER_2ND
inter_flag	long *	-	Flag for first or second inter section point selection	-	Allowed values: (1) XP_INTER_1ST (2) XP_INTER_2ND
los_az	double *	-	Azimuth of the LOS (Attitude Frame)	deg	>= 0 < 360
los_el	double *	-	Elevation of the LOS (Attitude Frame)	deg	>= -90 <= 90
num_target	long *	-	Number of user defined altitudes	-	> 0
geod_alt	double [XP_MAX_NUM_MULTI_TARGET]	-	Geodetic altitude over the Earth, sorted vector, strict monotonic decreasing	m	>= -bWGS
los_az_rate	double *	-	Azimuth-rate of the LOS (Attitude Frame)	deg/s	-
los_el_rate	double *	-	Elevation-rate of the LOS (Attitude Frame)	deg/s	-
iray	long *	-	Not used. The atmosphere refraction model can be	-	-

			defined via <code>atmos_id</code> initialization.		
<code>freq</code>	<code>double *</code>	-	Frequency of the signal	Hz	$\geq 0$

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Derivative switch: `deriv`. See current document, Table 3 .
- Intersection flag: `inter_flag`. See current document, Table 3 .

### 7.86.4 Output Parameters

The output parameters of the `xp_multi_target_inter` CFI function are:

*Table 226: Output parameters of `xp_multi_target_inter`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>num_user_target</code>	<code>long*</code>		Number of user defined targets calculated		$\geq 0$ $\leq \text{num\_target}$
<code>num_los_target</code>	<code>long*</code>		Number of LOS targets calculated		$\geq 0$
<code>target_id</code>	<code>xp_target_id*</code>	-	Structure that contains the Target results	-	-
<code>ierr</code>	<code>long</code>	-	Error vector	-	-

### 7.86.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_multi_target_inter` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_multi_target_inter` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

*Table 227: Error messages of `xp_multi_target_inter` function*

Error	Error message	Cause and impact	Error code	Error
-------	---------------	------------------	------------	-------

type				No
ERR	Attitude Id. is not initialized	No calculation performed	XP_CFI_MULTI_TARGET_INTER_ATTITUDE_STATU S_ERR	0
ERR	Intersection flag is not correct	No calculation performed	XP_CFI_MULTI_TARGET_INTER_INTER_FLAG_ERR	1
ERR	Invalid Frequency	No calculation performed	XP_CFI_MULTI_TARGET_INTER_FREQ_ERR	2
ERR	Time reference ID is not correct	No calculation performed	XP_CFI_MULTI_TARGET_INTER_TIME_REF_ERR	3
ERR	Deriv flag is not correct	No calculation performed	XP_CFI_MULTI_TARGET_INTER_DERIV_FLAG_ERR	4
ERR	Ray Tracing Model ID is not correct	No calculation performed	XP_CFI_MULTI_TARGET_INTER_IRAY_ID_ERR	5
ERR	Input state vector does not satisfy loose tolerance requirement	No calculation performed	XP_CFI_MULTI_TARGET_INTER_INVALID_SV_ERR	6
ERR	Invalid LOS Azimuth	No calculation performed	XP_CFI_MULTI_TARGET_INTER_LOS_AZIMUTH_E RR	7
ERR	Invalid LOS Elevation	No calculation performed	XP_CFI_MULTI_TARGET_INTER_LOS_ELEVATION_ ERR	8
ERR	Invalid Geodetic Altitude	No calculation performed	XP_CFI_MULTI_TARGET_INTER_GEODETTIC_ALT_E RR	9
ERR	Memory allocation error	No calculation performed	XP_CFI_MULTI_TARGET_INTER_MEMORY_ERR	10
ERR	Internal computation error #3	No calculation performed	XP_CFI_MULTI_TARGET_INTER_INITIAL_LOOK_DI R_OR_PLANE_ERR	11
ERR	Time Reference not initialised	No calculation performed	XP_CFI_MULTI_TARGET_INTER_TIME_REF_INIT_E RR	12
ERR	No target was found	No calculation performed	XP_CFI_MULTI_TARGET_INTER_TARGET_NOT_FO UND_ERR	13
ERR	Internal computation error #4	No calculation performed	XP_CFI_MULTI_TARGET_INTER_RANGE_OR_POIN TING_CALC_ERR	14
WARN	Input state vector does not satisfy tight tolerance requirement	Calculation performed. A message informs the user.	XP_CFI_MULTI_TARGET_INTER_INVALID_SV_WA RN	15
WARN	Path from satellite to target occulted by the Earth	Calculation performed. A message informs the	XP_CFI_MULTI_TARGET_INTER_NEGATIVE_ALTIT	16

		user.	UDE_WARN	
WARN	The ray tracing flag (iray) is ignored	Calculation performed. A message informs the user that this parameter is not used. If the variable iray is equal to XP_NO_REF_INIT (=0), the warning is avoided.	XP_CFI_MULTI_TARGET_INT ER_IRAY_ID_WARN	17

## 7.87 xp\_multi\_target\_travel\_time

### 7.87.1 Overview

The `xp_multi_target_travel_time` CFI function computes the points of the line of sight from the satellite (defined by an elevation and an azimuth angle expressed in the selected Attitude Frame) at given travel times along the (curved) line of sight.

The light travel time (from the satellite to the target or vice versa) can be taken into account by the computations. For details about light propagation mode see the section Error: Reference source not found.

### 7.87.2 Calling Interface

The calling interface of the `xp_multi_target_travel_time` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long          sat_id;
    xp_attitude_id attitude_id = {NULL};
    xp_atmos_id   atmos_id = {NULL};
    xp_dem_id     dem_id = {NULL};
    xp_target_id target_id = {NULL};
    long deriv, iray;
    double los_az, los_el, travel_time[XP_MAX_NUM_MULTI_TARGET];
    double los_az_rate, los_el_rate, travel_time_rate, freq;
    long num_target, num_user_target, num_los_target;
    long ierr[XP_NUM_ERR_MULTI_TARGET_TRAVEL_TIME], status;

    status = xp_multi_target_travel_time(&sat_id,
                                         &attitude_id,
                                         &atmos_id,
                                         &dem_id,
                                         &deriv, &los_az, &los_el,
                                         &num_target, &travel_time, &los_az_rate,
                                         &los_el_rate, &travel_time_rate, &iray, &freq,
                                         &num_user_target, &num_los_target,
                                         &target_id, ierr);

    /* Or, using the run_id */
    long run_id;
```

```
status = xp_multi_target_travel_time_run(&run_id,  
    &attitude_id,  
    &deriv, &los_az, &los_el,  
    &num_target, travel_time, &los_az_rate,  
    &los_el_rate, &travel_time_rate, &iray, &freq,  
    &num_user_target, &num_los_target,  
    &target_id, ierr);  
}
```

The `XP_NUM_ERR_MULTI_TARGET_TRAVEL_TIME` constant is defined in the file *explorer\_pointing.h*.



### 7.87.3 Input Parameters

The `xp_multi_target_travel_time` CFI function has the following input parameters:

**Table 228: Input parameters of `xp_multi_target_travel_time` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>sat_id</code>	long *	-	Satellite ID	-	Complete
<code>attitude_id</code>	<code>xp_attitude_id*</code>	-	Structure that contains the Attitude. (input/output)	-	-
<code>atmos_id</code>	<code>xp_atmos_id*</code>	-	Structure that contains the atmosphere initialization.	-	The <code>atmos_id</code> has to be initialized with any of these modes: - <code>XP_NO_REF_INIT</code> - <code>XP_STD_INIT</code> - <code>XP_USER_INIT</code>
<code>dem_id</code>	<code>xp_dem_id*</code>	-	Structure that contains the DEM initialization.	-	-
<code>deriv</code>	long *	-	Derivative ID	-	Allowed values: (0) <code>XP_NO_DER</code> (1) <code>XP_DER_1ST</code> (2) <code>XP_DER_2ND</code>
<code>los_az</code>	double *	-	Azimuth of the LOS (Attitude Frame)	deg	$\geq 0$ $< 360$
<code>los_el</code>	double *	-	Elevation of the LOS (Attitude Frame)	deg	$\geq -90$ $\leq 90$
<code>num_target</code>	long *	-	Number of user defined times	-	$> 0$
<code>travel_time</code>	double [ <code>XP_MAX_NUM_MULTI_TARGET</code> ]	-	Travel time along the (curved) line of sight,sorted vector, strict monotonic increasing	s	$> 0$
<code>los_az_rate</code>	double *	-	Azimuth-rate of the LOS (Attitude Frame)	deg/s	-
<code>los_el_rate</code>	double *	-	Elevation-rate of the LOS (Attitude Frame)	deg/s	-
<code>travel_time_rate</code>	double *	-	Travel time-rate along the (curved) line of sight. Constant number.	s/s	-
<code>iray</code>	long *	-	Not used. The atmosphere refraction model can be defined via <code>atmos_id</code> initialization.	-	-

---

freq	double *	-	Frequency of the signal	Hz	>= 0
------	----------	---	-------------------------	----	------

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Derivative switch: deriv. See current document, Table 3 .

### 7.87.4 Output Parameters

The output parameters of the `xp_multi_target_travel_time` CFI function are:

**Table 229: Output parameters of `xp_multi_target_travel_time`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
num_user_target	long*	-	Number of user defined targets calculated	-	$\geq 0$ $\leq$ num_target
num_los_target	long*	-	Number of LOS targets calculated	-	$\geq 0$
target_id	xp_target_id*	-	Structure that contains the Target results	-	-
ierr	long	-	Error vector	-	-

### 7.87.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_multi_target_travel_time` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_multi_target_travel_time` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 230: Error messages of `xp_multi_target_travel_time` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Attitude Id. is not initialized	No calculation performed	XP_CFI_MULTI_TARGET_TRAVEL_TIME_ATTITUDE_STATUS_ERR	0
ERR	Intersection flag is not correct	No calculation performed	XP_CFI_MULTI_TARGET_TRAVEL_TIME_INTER_FLAG_ERR	1
ERR	Invalid Frequency	No calculation performed	XP_CFI_MULTI_TARGET_TRAVEL_TIME_FREQ_ERR	2
ERR	Time reference ID is not correct	No calculation performed	XP_CFI_MULTI_TARGET_TRAVEL_TIME_TIME_REF_ERR	3
ERR	Deriv flag is not correct	No calculation performed	XP_CFI_MULTI_TARGET_TRAVEL_TIME_DERIV_FLAG_ERR	4

			AG_ERR	
ERR	Ray Tracing Model ID is not correct	No calculation performed	XP_CFI_MULTI_TARGET_TRAVEL_TIME_IRAY_ID_ERR	5
ERR	Input state vector does not satisfy loose tolerance requirement	No calculation performed	XP_CFI_MULTI_TARGET_TRAVEL_TIME_INVALID_SV_ERR	6
ERR	Invalid LOS Azimuth	No calculation performed	XP_CFI_MULTI_TARGET_TRAVEL_TIME_LOS_AZIMUTH_ERR	7
ERR	Invalid LOS Elevation	No calculation performed	XP_CFI_MULTI_TARGET_TRAVEL_TIME_LOS_ELEVATION_ERR	8
ERR	Invalid Geodetic Altitude	No calculation performed	XP_CFI_MULTI_TARGET_TRAVEL_TIME_GEODETI C_ALT_ERR	9
ERR	Memory allocation error	No calculation performed	XP_CFI_MULTI_TARGET_TRAVEL_TIME_MEMORY_ERR	10
ERR	Internal computation error #3	No calculation performed	XP_CFI_MULTI_TARGET_TRAVEL_TIME_INITIAL_L OOK_DIR_OR_PLANE_ERR	11
ERR	Time Reference not initialised	No calculation performed	XP_CFI_MULTI_TARGET_TRAVEL_TIME_TIME_REF _INIT_ERR	12
ERR	No target was found	No calculation performed	XP_CFI_MULTI_TARGET_TRAVEL_TIME_TARGET NOT_FOUND_ERR	13
ERR	Internal computation error #4	No calculation performed	XP_CFI_MULTI_TARGET_TRAVEL_TIME_RANGE_O R_POINTING_CALC_ERR	14
WARN	Input state vector does not satisfy tight tolerance requirement	Calculation performed. A message informs the user.	XP_CFI_MULTI_TARGET_TRAVEL_TIME_INVALID_SV_WARN	15
WARN	Path from satellite to target occulted by the Earth	Calculation performed. A message informs the user.	XP_CFI_MULTI_TARGET_TRAVEL_TIME_NEGATIV E_ALTITUDE_WARN	16
WARN	The ray tracing flag (iray) is ignored	Calculation performed. A message informs the user that this parameter is not used. If the variable iray is equal to XP_NO_REF_INIT (=0), the warning is avoided.	XP_MULTI_TARGET_TRAVEL_TIME_IRAY_ID_WARN	17

## 7.88 xp\_target\_list\_inter

### 7.88.1 Overview

The `xp_target_list_inter` CFI function computes the first or the second intersection point of the line of sight from the satellite (expressed as pairs of azimuth and elevation angles in the selected Attitude Frame) with a surface located at a certain geodetic altitude over the Earth.

The sets of azimuth and elevation points can be defined in 3 different ways:

- A list of azimuth and elevation pairs.
- A strip of lines of sight, with a fixed azimuth and elevation angles changing with a given step.
- A grid of lines of sight, with both azimuth and elevation angles changing with a given step.

For each pair a user target is computed. To obtain the extra values for all the targets, the functions `xp_target_list_extra_xxx` can be used. The position of the target in the output array of these extra functions has the following criterion (note also that `xp_target_extra_xxx` functions can also be used to obtain the results of only one target with the same index criterion, but `xp_target_list_extra_xxx` are optimized to obtain the results for all the targets):

- 1) In case of a list, the index of the list.
- 2) In case of a strip: being `n_el` the number of elevation values (note that minimum and maximum elevation values are always included in the list):

$$n\_el = \text{TRUNC}((\text{max\_elevation} - \text{min\_elevation}) / \text{step\_elevation} + 1)$$

The target number is computed in increasing elevation order, from lower to upper elevation:

- For  $0 \leq i < n\_el - 1$ : target number  $i$  corresponds to pair (azimuth,  $\text{min\_elevation} + i * \text{step\_elevation}$ ).
- For  $i = n\_el - 1$ : target number  $n\_el - 1$  corresponds to pair (azimuth,  $\text{max\_elevation}$ ).

- 3) In case of a grid: being `n_el` the number of elevation values (note that minimum and maximum elevation values are always included in the list):

$$n\_el = \text{TRUNC}((\text{max\_elevation} - \text{min\_elevation}) / \text{step\_elevation} + 1)$$

being `n_az` the number of azimuth values (note that minimum and maximum azimuth values are always included in the list):

$$n\_az = \text{TRUNC}((\text{max\_azimuth} - \text{min\_azimuth}) / \text{step\_azimuth} + 1)$$

The target number is computed by increasing azimuth and elevation order: from minimum azimuth to maximum azimuth and, for every azimuth value, from minimum elevation to maximum elevation. That is:

- For  $0 \leq i < n\_el - 1$ : target number  $i$  corresponds to pair ( $\text{min\_azimuth}$ ,  $\text{min\_elevation} + i * \text{step\_elevation}$ ).
- For  $i = n\_el - 1$ : target number  $n\_el - 1$  corresponds to pair ( $\text{min\_azimuth}$ ,  $\text{max\_elevation}$ ).
- For  $n\_el \leq i < 2 * n\_el - 1$  target number  $i$  corresponds to pair ( $\text{min\_azimuth} + \text{step\_azimuth}$ ,  $\text{min\_elevation} + i * \text{step\_elevation}$ ).

...

(for  $0 \leq j < n\_az-1$  and defining  $k = i-j*n\_el$ )

- For  $j*n\_el \leq i < (j+1)*n\_el-1$  target number  $i$  corresponds to pair ( $min\_azimuth + j*step\_azimuth$ ,  $min\_elevation + k*step\_elevation$ ).
- For  $i = (j+1)*n\_el-1$  target number  $i$  corresponds to pair ( $min\_azimuth + j*step\_azimuth$ ,  $max\_elevation$ ).

(for  $j = n\_az-1$  and defining  $k=i-(n\_az-1)*n\_el$ )

- For  $(n\_az-1)*n\_el \leq i < n\_az*n\_el-1$ : target number  $i$  corresponds to pair ( $max\_azimuth$ ,  $min\_elevation + k*step\_elevation$ ).
- For  $i = n\_az*n\_el-1$  target number  $i$  corresponds to pair ( $max\_azimuth$ ,  $max\_elevation$ )

The light travel time (from the satellite to the target or vice versa) can be taken into account by the computations. For details about light propagation mode see the section Error: Reference source not found.

## 7.88.2 Calling Interface

The calling interface of the `xp_target_list_inter` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long          sat_id;
    xp_attitude_id attitude_id = {NULL};
    xp_atmos_id   atmos_id = {NULL};
    xp_dem_id     dem_id = {NULL};
    xp_target_id  target_id = {NULL};
    long deriv, inter_flag;
    xp_instrument_data instrument_data;
    double geod_alt;
    long ierr[XP_NUM_ERR_TARGET_LIST_INTER], status;
    xp_target_output target_out;

    status = xp_target_list_inter(&sat_id,
                                &attitude_id,
                                &atmos_id,
                                &dem_id,
                                &deriv, &inter_flag,
```

```

    &instrument_data, &geod_alt,
    &target_out,
    &target_id, ierr);
}

```

The `XP_NUM_ERR_TARGET_INTER` constant is defined in the file *explorer\_pointing.h*.

### 7.88.3 Input Parameters

The `xp_target_list_inter` CFI function has the following input parameters:

**Table 231: Input parameters of `xp_target_lists_inter` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sat_id	long *	-	Satellite ID	-	Complete
attitude_id	xp_attitude_id*	-	Structure that contains the Attitude. (input/output)	-	-
atmos_id	xp_atmos_id*	-	Structure that contains the atmosphere initialization.	-	The <code>atmos_id</code> has to be initialized with any of these modes: - <code>XP_NO_REF_INIT</code> - <code>XP_STD_INIT</code> - <code>XP_USER_INIT</code>
dem_id	xp_dem_id*	-	Structure that contains the DEM initialization.	-	-
deriv	long *	-	Derivative ID	-	Allowed values: (0) <code>XP_NO_DER</code> (1) <code>XP_DER_1ST</code> (2) <code>XP_DER_2ND</code>
inter_flag	long *	-	Flag for first or second inter section point selection	-	Allowed values: (1) <code>XP_INTER_1ST</code> (2) <code>XP_INTER_2ND</code>
instrument_data	xp_instrument_data	-	Azimuth/elevation input data and frequency	deg	$0 \leq \text{azimuth} < 360$ $-90 \leq \text{elevation} \leq 90$
geod_alt	double *	-	Geodetic altitude over the Earth	m	$\geq -bWGS$

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Derivative switch: `deriv`. See current document, Table 3.
- Intersection flag: `inter_flag`. See current document, Table 3.
- Azimuth elevation input type. See current document, Table 3.

### 7.88.4 Output Parameters

The output parameters of the `xp_target_list_inter` CFI function are:

**Table 232: Output parameters of `xp_target_list_inter`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
target_out	xp_target_output*	-	Number of user and LOS defined targets calculated. Note: the memory allocated in this struct must be freed by the user	-	≥ 0
target_id	xp_target_id*	-	Structure that contains the Target results	-	-
ierr	long	-	Error vector	-	-

### 7.88.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_list_inter` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_list_inter` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 233: Error messages of `xp_target_list_inter` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Attitude Id. is not initialized	No calculation performed	XP_CFI_TARGET_LIST_INTER_ATTITUDE_STATUS_ERR	0
ERR	Intersection flag is not correct	No calculation performed	XP_CFI_TARGET_LIST_INTER_FLAG_ERR	1
ERR	Invalid Frequency	No calculation performed	XP_CFI_TARGET_LIST_INTER_FREQ_ERR	2
ERR	Time reference ID is not correct	No calculation performed	XP_CFI_TARGET_LIST_INTER_TIME_REF_ERR	3
ERR	Deriv flag is not correct	No calculation performed	XP_CFI_TARGET_LIST_INTER_DERIV_FLAG_ERR	4
ERR	Ray Tracing Model ID is not correct	No calculation performed	XP_CFI_TARGET_LIST_INTER_RAY_ID_ERR	5



ERR	Input state vector does not satisfy loose tolerance requirement	No calculation performed	XP_CFI_TARGET_LIST_INTE R_I NVALID_SV_ERR	6
ERR	Invalid LOS Azimuth	No calculation performed	XP_CFI_TARGET_LIST_INTE R_LOS_AZIMUTH_ERR	7
ERR	Invalid LOS Elevation	No calculation performed	XP_CFI_TARGET_LIST_INTE R_LOS_ELEVATION_ERR	8
ERR	Invalid Geodetic Altitude	No calculation performed	XP_CFI_TARGET_LIST_INTE R_GEODETTIC_ALT_ERR	9
ERR	Memory allocation error	No calculation performed	XP_CFI_TARGET_LIST_INTE R_MEMORY_ERR	10
ERR	Internal computation error # 3	No calculation performed	XP_CFI_TARGET_LIST_INTE R_I NITIAL_LOOK_DIR_OR_P LANE_ERR	11
ERR	Time Reference not initialized	No calculation performed	XP_CFI_TARGET_LIST_INTE R_TIME_REF_INIT_ERR	12
ERR	No target was found	No calculation performed	XP_CFI_TARGET_LIST_INTE R_TARGET_NOT_FOUND_E RR	13
ERR	Internal computation error # 4	No calculation performed	XP_CFI_TARGET_LIST_INTE R_RANGE_OR_POINTING_C ALC_ERR	14
WARN	Input state vector does not satisfy tight tolerance requirement	Calculation performed. A message informs the user.	XP_CFI_TARGET_LIST_INTE R_I NVALID_SV_WARN	15
WARN	Path from satellite to target occulted by the Earth	Calculation performed. A message informs the user.	XP_CFI_TARGET_LIST_INTE R_NEGATIVE_ALTITUDE_W ARN	16
ERR	Wrong instrument data type	No calculation performed	XP_CFI_TARGET_LIST_INTE R_INSTRUMENT_TYPE_ERR	17
ERR	Error linking IDs	No calculation performed	XP_CFI_TARGET_LIST_INTE R_LINK_IDS_ERR	18
ERR	Maximum number of targets exceeded	No calculation performed	XP_CFI_TARGET_LIST_INTE R_MAX_TARGETS_ERR	19

## 7.89 xp\_target\_extra\_vector

### 7.89.1 Overview

The `xp_target_extra_vector` CFI function provides the following output parameters for the target(s) in input data structure.: target position, velocity and acceleration vectors, line of sight direction, range, travel time and their corresponding derivatives.

Note on `target_number` with targets computed with `xp_target_list_inter`:

the `target_number` to be used to get a specific LOS target is an incremental number. That is, if there are  $N$  user targets `US1`, `US2`, ... `USN` and a number of LOS targets for every user target `NLOS1`, `NLOS2`, ..., `NLOS $N$` , if we want to get LOS target with index 1 corresponding to user target `US3`, the `target_number` to be used is `NLOS1+NLOS2+1`.

The `target_number` can also be got with the array returned by `xp_target_get_id_data`.

### 7.89.2 Calling Interface

The calling interface of the `xp_target_extra_vector` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long choice, target_type, target_number;
    xp_target_id target_id = {NULL};
    double vector_results[XP_SIZE_TARGET_RESULT_VECTOR],
           vector_results_rate[XP_SIZE_TARGET_RESULT_VECTOR],
           vector_results_rate_rate[XP_SIZE_TARGET_RESULT_VECTOR];
    long ierr[XP_NUM_ERR_TARGET_EXTRA_VECTOR], status;

    status = xp_target_extra_vector (&target_id, &choice,
                                     &target_type, &target_number,
                                     vector_results,
                                     vector_results_rate,
                                     vector_results_rate_rate, ierr);
}
```

The `XP_SIZE_TARGET_RESULT_VECTOR` and `XP_NUM_ERR_TARGET_EXTRA_VECTOR` constants are defined in the file `explorer_pointing.h`.

### 7.89.3 Input Parameters

The `xp_target_extra_vector` CFI function has the following input parameters:

*Table 234: Input parameters of `xp_target_extra_vector` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>target_id</code>	<code>xp_target_id*</code>	-	Structure that contains the Target results	-	-
<code>choice</code>	<code>long *</code>	-	Flag to select the extra results to be computed. Even though derivatives could be requested by user, they will not be calculated if the target was computed without derivatives (a warning is raised in this case).	-	Allowed values: (0) <code>XP_NO_DER</code> (1) <code>XP_DER_1ST</code> (2) <code>XP_DER_2ND</code>
<code>target_type</code>	<code>long *</code>		Flag to select the type of target		<code>XP_USER_TARGET_TYPE</code> <code>XP_LOS_TARGET_TYPE</code> <code>XP_DEM_TARGET_TYPE</code>
<code>target_number</code>	<code>long *</code>	-	Target number		<code>&gt;= 0</code>

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Choice. (See Table 3).

### 7.89.4 Output Parameters

The output parameters of the `xp_target_extra_vector` CFI function are:

**Table 235: Output parameters of `xp_target_extra_vector`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
vector_results double[XP_SIZE_TARGET_RESULT_VECTOR]		[0]	Target Position X (Earth-Fixed)	m	
		[1]	Target Position Y (Earth-Fixed)	m	
		[2]	Target Position Z (Earth-Fixed)	m	
		[3]	Direction LOS X (Earth-Fixed)	-	
		[4]	Direction LOS Y (Earth-Fixed)	-	
		[5]	Direction LOS Z (Earth-Fixed)	-	
		[6]	Range to Attitude Frame Origin	m	
		[7]	Travel Time to Attitude Frame Origin	s	
		[8]	Target time UTC	days	
		[9:XP_SIZE_TARGET_RESULT_VECTOR]	(dummy)	-	-
vector_results_rate double[XP_SIZE_TARGET_RESULT_VECTOR]		[0]	Target Velocity X (Earth-Fixed)	m/ s	
		[1]	Target Velocity Y (Earth-Fixed)	m/ s	
		[2]	Target Velocity Z (Earth-Fixed)	m/ s	
		[3]	Direction Rate LOS X (Earth-Fixed)	1/s	
		[4]	Direction Rate LOS Y (Earth-Fixed)	1/s	
		[5]	Direction Rate LOS Z (Earth-Fixed)	1/s	
		[6]	Range Rate to Attitude Frame Origin	m/s	
		[7]	Travel Time Rate to Attitude Frame Origin	s/s	
		[8]	Dummy		
		[9:XP_SIZE_TARGET_RESULT_VECTOR]	(dummy)	-	-
vector_results_rate_rate double[XP_SIZE_TARGET_RESULT_VECTOR]		[0]	Target Acceleration X (Earth-Fixed)	m/s <sup>2</sup>	
		[1]	Target Acceleration Y (Earth-Fixed)	m/s <sup>2</sup>	
		[2]	Target Acceleration Z (Earth-Fixed)	m/s <sup>2</sup>	
		[3]	Direction Rate Rate LOS X (Earth-	1/s <sup>2</sup>	

			Fixed)		
	[4]		Direction Rate Rate LOS Y (Earth-Fixed)	1/s <sup>2</sup>	
	[5]		Direction Rate Rate LOS Z (Earth-Fixed)	1/s <sup>2</sup>	
	[6]		Range Rate Rate to Attitude Frame Origin	m/s <sup>2</sup>	
	[7]		Travel Time Rate Rate to Attitude Frame Origin	s/s <sup>2</sup>	
	[8]		Dummy		
	[9:XP_SIZ E_TARGE T_RESUL T_VECTO R]		(dummy)	-	-
ierr	long	-	Error vector	-	-

Note that:

- first derivative parameters (vector\_results\_rate) are returned as zeros if derivative flag (deriv) was set to NO\_DER when the target was computed and that second derivative parameters (vector\_results\_rate\_rate) are returned as zeros if derivative flag (deriv) was set to NO\_DER or 1ST\_DER.
- when a refraction mode is selected, the second derivative parameters (vector\_results\_rate\_rate) are returned as zeros.
- when light propagation mode is used the target position is at **target time** (see section Error: Reference source not found).

### 7.89.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the **xp\_target\_extra\_vector** CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library **xp\_get\_msg** (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the **xp\_target\_extra\_vector** function by calling the function of the EO\_POINTING software library **xp\_get\_code** (see [GEN\_SUM]).

**Table 236: Error messages of xp\_target\_extra\_vector function**

Error type	Error message	Cause and impact	Error code	Error No
------------	---------------	------------------	------------	----------

ERR	The Target ID does not contain any data	No calculation performed	XP_CFI_TARGET_EXTRA_V ECTOR_NO_DATA_ERR	0
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_EXTRA_V ECTOR_NO_SUCH_USER_T ARGET_ERR	1
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_EXTRA_V ECTOR_NO_SUCH_LOS_TA RGET_ERR	2
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_EXTRA_V ECTOR_NO_SUCH_EARTH_ TARGET_ERR	3
ERR	Could not compute the DEM target	No calculation performed	XP_CFI_TARGET_EXTRA_V ECTOR_EARTH_TARGET_C OMPUT_ERR	4
ERR	Wrong target type	No calculation performed	XP_CFI_TARGET_EXTRA_V ECTOR_WRONG_TARGET_T YPE_ERR	5
ERR	Wrong deriv input flag	No calculation performed	XP_CFI_TARGET_EXTRA_V ECTOR_DERIV_FLAG_ERR	6
WARN	1st. Derivatives are not available	Calculation performed. A message informs the user.	XP_CFI_TARGET_EXTRA_V ECTOR_DER_1ST_NOT_AVA IL_WARN	7
WARN	2nd. Derivatives are not available	Calculation performed. A message informs the user.	XP_CFI_TARGET_EXTRA_V ECTOR_DER_2ND_NOT_AV AIL_WARN	8
WARN	DEM files were not found	Calculation performed.	XP_CFI_TARGET_EXTRA_VECT OR_ELLIPSOID_WARN	9
WARN	Warning in XP_DEM_inter	Calculation performed.	XP_CFI_TARGET_EXTRA_VECT OR_DEM_INTER_WARN	10
ERR	Error converting time to UTC	No calculation performed	XP_CFI_TARGET_EXTRA_VECT OR_CONVERT_TO_UTC_ERR	11
WARN	No precise intersection found with DEM. Degraded solution returned	Calculation performed	XP_CFI_TARGET_EXTRA_VECT OR_DEM_DEGRADED_SOLUTI ON_WARN	12

## 7.90 xp\_target\_list\_extra\_vector

### 7.90.1 Overview

The `xp_target_list_extra_vector` CFI function provides the same results as `xp_target_extra_vector` function but for all the targets computed with `xp_target_list_inter` function.

This function has been optimized to improve the run-time performance of the target computation of all the targets and runs in multithreading (Remark: multithreading is not enabled on MacOS platforms, see section 6).

#### 7.90.1.1 Note on multithreading:

Improvement in performance due to multithread parallelization depends on many factors, including hardware set-up (i.e. multicore processor) and number of targets computed. In some cases (e.g. low number of targets), due to the high overhead of starting threads, parallelization may even degrade performances. In this case, it is recommended to disable multithreading or reduce the number of threads by using `omp_set_num_threads` openmp function.

#### NOTE for MACIN64 platform, Xcode 5 users:

As of version 5, `llvm-gcc` has been removed from Xcode and the default compiler is `clang`.

`clang` can build an application linking against the EO\_CFI C / C++ libraries.

However `openmp` is not supported by `clang`. Therefore, the `-fopenmp` shall not be used.

Functions using parallelized computations, e.g. `xp_target_list...` functions will work in single-thread mode.

### 7.90.2 Calling Interface

The calling interface of the `xp_target_list_extra_vector` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long choice, target_type, target_number;
    xp_target_id target_id = {NULL};
    xp_target_extra_vector_results_list list;
    long ierr[XP_NUM_ERR_TARGET_LIST_EXTRA_VECTOR], status;

    status = xp_target_list_extra_vector (&target_id, &choice,
                                         &target_type,
                                         &list, ierr);
}
```

The `XP_NUM_ERR_TARGET_LIST_EXTRA_VECTOR` constant is defined in the file `explorer_pointing.h`.





### 7.90.3 Input Parameters

The `xp_target_list_extra_vector` CFI function has the following input parameters:

*Table 237: Input parameters of `xp_target_list_extra_vector` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>target_id</code>	<code>xp_target_id*</code>	-	Structure that contains the Target results	-	-
<code>choice</code>	<code>long *</code>	-	Flag to select the extra results to be computed. Even though derivatives could be requested by user, they will not be calculated if the target was computed without derivatives (a warning is raised in this case).	-	Allowed values: (0) <code>XP_NO_DER</code> (1) <code>XP_DER_1ST</code> (2) <code>XP_DER_2ND</code>
<code>target_type</code>	<code>long *</code>		Flag to select the type of target		<code>XP_USER_TARGET_T TYPE</code> <code>XP_LOS_TARGET_T TYPE</code> <code>XP_DEM_TARGET_T TYPE</code>

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Choice. (See Table 3 ).

## 7.90.4 Output Parameters

The output parameters of the `xp_target_list_extra_vector` CFI function are:

**Table 238: Output parameters of `xp_target_list_extra_vector`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
list	<code>xp_target_extra_vector_results_list</code>	-	List of extra results	-	-
ierr	long	-	Error vector	-	-

The values corresponding to returned arrays are the same as in the case of `xp_target_extra_vector` (see 7.89.4).

## 7.90.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_list_extra_vector` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_list_extra_vector` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 239: Error messages of `xp_target_list_extra_vector` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	The Target ID does not contain any data	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_VECTOR_NO_DATA_ERR</code>	0
ERR	The target does not exist	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_VECTOR_NO_SUCH_USER_TARGET_ERR</code>	1
ERR	The target does not exist	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_VECTOR_NO_SUCH_EARTH_TARGET_ERR</code>	2
ERR	Could not compute the DEM target	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_VECTOR_EARTH_TARGET_COMPUT_ERR</code>	3
ERR	Wrong target type	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_VECTOR_WRONG_TARGET_TYPE_ERR</code>	4
ERR	Wrong deriv input flag	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_VECTOR_WRONG_DERIV_FLAG_ERR</code>	5

			V E C T O R _ D E R I V _ F L A G _ E R R	
WARN	1st. Derivatives are not available	Calculation performed. A message informs the user.	XP_CFI_TARGET_LIST_EXTRA_VECTOR_DER_1ST_NOT_AVAILABLE_WARN	6
WARN	2nd. Derivatives are not available	Calculation performed. A message informs the user.	XP_CFI_TARGET_LIST_EXTRA_VECTOR_DER_2ND_NOT_AVAILABLE_WARN	7
WARN	DEM files were not found	Calculation performed.	XP_CFI_TARGET_LIST_EXTRA_VECTOR_ELLIPSOID_WARN	8
WARN	Warning in XP_DEM_inter	Calculation performed.	XP_CFI_TARGET_LIST_EXTRA_VECTOR_DEM_INTER_WARN	9
ERR	Error allocating memory	No calculation performed	XP_CFI_TARGET_LIST_EXTRA_VECTOR_MEMORY_ERR	10
WARN	No precise intersection found with DEM. Degraded solution returned	Calculation performed	XP_CFI_TARGET_LIST_EXTRA_VECTOR_DEM_DEGRADED_SOLUTION_WARN	11

## 7.91 xp\_target\_extra\_main

### 7.91.1 Overview

The `xp_target_extra_main` CFI function computes the extra parameter for the target(s) in input data structure.

Note on `target_number` with targets computed with `xp_target_list_inter`:

the `target_number` to be used to get a specific LOS target is an incremental number. That is, if there are N user targets US1, US2, ... USN and a number of LOS targets for every user target NLOS1, NLOS2, ..., NLOS<sub>N</sub>, if we want to get LOS target with index 1 corresponding to user target US3, the `target_number` to be used is NLOS1+NLOS2+1.

The `target_number` can also be got with the array returned by `xp_target_get_id_data`.

### 7.91.2 Calling Interface

The calling interface of the `xp_target_extra_main` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long choice, target_type, target_number;
    double main_results[XP_SIZE_TARGET_RESULT_MAIN],
           main_results_rate[XP_SIZE_TARGET_RESULT_MAIN],
           main_results_rate_rate[XP_SIZE_TARGET_RESULT_MAIN];
    xp_target_id target_id = {NULL};
    long ierr[XP_NUM_ERR_TARGET_EXTRA_MAIN], status;

    status = xp_target_extra_main (&target_id, &choice, &target_type,
                                   &target_number,
                                   main_results, main_results_rate,
                                   main_results_rate_rate, ierr);
}
```

The `XP_SIZE_TARGET_EXTRA_MAIN` and `XP_NUM_ERR_TARGET_RESULT_MAIN` constants are defined in the file `explorer_pointing.h`.

### 7.91.3 Input Parameters

The `xp_target_extra_main` CFI function has the following input parameters:

*Table 240: Input parameters of `xp_target_extra_main` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>target_id</code>	<code>xp_target_id*</code>	-	Structure that contains the Target results	-	-
<code>choice</code>	<code>long *</code>	-	Flag to select the extra results to be computed. Even though derivatives could be requested by user, they will not be calculated if the target was computed without derivatives (a warning is raised in this case).	-	Complete
<code>target_type</code>	<code>long *</code>	-	Flag to select the type of target	-	XP_USER_TARGET_TYPE XP_LOS_TARGET_TYPE XP_DEM_TARGET_TYPE
<code>target_number</code>	<code>long *</code>	-	Target number	-	$\geq 0$

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Choice. (See Table 3 ).

## 7.91.4 Output Parameters

The output parameters of the `xp_target_extra_main` CFI function are:

**Table 241: Output parameters of `xp_target_extra_main`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
main_results double[XP_SIZE_TARGET_RESULT_MAIN]		[0]	Target geocentric longitude (Earth Fixed CS)	deg	>= 0 < 360
		[1]	Target geocentric latitude (Earth Fixed CS)	deg	>= -90 <= +90
		[2]	Target geodetic latitude (Earth Fixed CS)	deg	>= -90 <= +90
		[3]	Target geodetic altitude (Earth Fixed CS)	m	-
		[4]	Satellite to target azimuth (Topocentric CS)	deg	>= 0 < 360
		[5]	Satellite to target elevation (Topocentric CS)	deg	>= -90 <= +90
		[6]	Satellite to target pointing: Azimuth (attitude frame)	deg	>= 0 < 360
		[7]	Satellite to target pointing: Elevation (attitude frame)	deg	>= -90 <= +90
		[8]	Target to satellite pointing: Azimuth (Topocentric)	deg	>= 0 < 360
		[9]	Target to satellite pointing: Elevation (Topocentric)	deg	>= -90 <= +90
		[10]	Target to source Satellite Pointing: Azimuth (attitude frame). Note: this value is only meaningful when target has been computed with <code>xp_target_sc</code>	deg	>= 0 < 360
		[11]	Target to source Satellite Pointing: Elevation (attitude frame). Note: this value is only meaningful when target has been computed with <code>xp_target_sc</code>	deg	>= -90 <= 90
		[12:XP_SIZE_TARGET_RESULT_MAIN]	(dummy)	-	-
main_results_rate		[0]	Target geocentric longitude rate	deg/s	-

double[XP_SIZE_TARGET_RESULT_MAIN]		(Earth Fixed CS)		
	[1]	Target geocentric latitude rate (Earth Fixed CS)	deg/s	-
	[2]	Target geodetic latitude rate (Earth Fixed CS)	deg/s	-
	[3]	Target geodetic altitude rate (Earth Fixed CS)	m/s	-
	[4]	Satellite to target azimuth rate (Topocentric CS)	deg/s	-
	[5]	Satellite to target elevation rate (Topocentric CS)	deg/s	-
	[6]	Satellite to target pointing: Azimuth rate (attitude frame)	deg/s	-
	[7]	Satellite to target pointing: Elevation rate (attitude frame)	deg/s	-
	[8]	Target to satellite pointing: Azimuth rate (Topocentric)	deg/s	-
	[9]	Target to satellite pointing: Elevation rate (Topocentric)	deg/s	-
	[10]	Target to source Satellite Pointing: Azimuth rate (attitude frame). Note: this value is only meaningful when target has been computed with xp_target_sc	deg	-
	[11]	Target to source Satellite Pointing: Elevation rate (attitude frame). Note: this value is only meaningful when target has been computed with xp_target_sc	deg	-
[12:XP_SIZE_TARGET_RESULT_MAIN]	(dummy)	-	-	
main_results_rate_rate double[XP_SIZE_TARGET_RESULT_MAIN]	[0]	Target geocentric longitude rate-rate (Earth Fixed CS)	deg/s <sup>2</sup>	-
	[1]	Target geocentric latitude rate-rate (Earth Fixed CS)	deg/s <sup>2</sup>	-
	[2]	Target geodetic latitude rate-rate (Earth Fixed CS)	deg/s <sup>2</sup>	-
	[3]	Target geodetic altitude rate-rate (Earth Fixed CS)	m/s <sup>2</sup>	-

	[4]	Satellite to target azimuth rate-rate (Topocentric CS)	deg/s2	-
	[5]	Satellite to target elevation rate-rate (Topocentric CS)	deg/s2	-
	[6]	Satellite to target pointing: Azimuth rate-rate (attitude frame)	deg/s2	-
	[7]	Satellite to target pointing: Elevation rate-rate (attitude frame)	deg/s2	-
	[8]	Target to satellite pointing: Azimuth rate-rate (Topocentric)	deg/s2	-
	[9]	Target to satellite pointing: Elevation rate-rate (Topocentric)	deg/s2	-
	[10]	Target to source Satellite Pointing: Azimuth rate rate (attitude frame). Note: this value is only meaningful when target has been computed with xp_target_sc	deg	-
	[11]	Target to source Satellite Pointing: Elevation rate rate (attitude frame) Note: this value is only meaningful when target has been computed with xp_target_sc	deg	-
	[12:XP_SIZETARGET_RESULT_MAIN]	(dummy)	-	-
ierr	long	-	Error vector	-

Note that first derivative parameters (vector\_results\_rate) are returned as zeros if derivative flag (deriv) was set to NO\_DER when the target was computed and that second derivative parameters (vector\_results\_rate\_rate) are returned as zeros if derivative flag (deriv) was set to NO\_DER or 1ST\_DER.

Note also that when a refraction mode is selected, the second derivative parameters (vector\_results\_rate\_rate) are returned as zeros.

### 7.91.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the **xp\_target\_extra\_main** CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library **xp\_get\_msg** (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.



The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the **xp\_target\_extra\_main** function by calling the function of the EO\_POINTING software library **xp\_get\_code** (see [GEN\_SUM]).

**Table 242: Error messages of xp\_target\_extra\_main function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	No target data available	No calculation performed	XP_CFI_TARGET_EXTRA_M AIN_NO_DATA_ERR	0
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_EXTRA_M AIN_NO_SUCH_USER_TARG ET_ERR	1
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_EXTRA_M AIN_NO_SUCH_LOS_TARGE T_ERR	2
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_EXTRA_M AIN_NO_SUCH_EARTH_TA RGET_ERR	3
ERR	Could not compute the DEM target	No calculation performed	XP_CFI_TARGET_EXTRA_M AIN_EARTH_TARGET_COM PUT_ERR	4
ERR	Wrong target type	No calculation performed	XP_CFI_TARGET_EXTRA_M AIN_WRONG_TARGET_TYP E_ERR	5
ERR	Invalid time reference in target data	No calculation performed	XP_CFI_TARGET_EXTRA_M AIN_INVALID_TIME_REF_E RR	6
ERR	Error calling to XL_Car_Geo CFI function	No calculation performed	XP_CFI_TARGET_EXTRA_M AIN_CAR_TO_GEO_ERR	7
ERR	Error getting tranformation matrix to Topocentric CS	No calculation performed	XP_CFI_TARGET_EXTRA_M AIN_TOPO_ERR	8
ERR	Error getting direction angles	No calculation performed	XP_CFI_TARGET_EXTRA_M AIN_DIR_POINTING_ERR	9
ERR	Error while changing coordinate system	No calculation performed	XP_CFI_TARGET_EXTRA_M AIN_CS_CHANGE_ERR	10
WARN	Warning: Derivatives cannot be calculated	Calculation performed	XP_CFI_TARGET_EXTRA_M AIN_DERIV_WARN	11
WARN	Warning calling to XL_Car_Geo CFI function	Calculation performed, but derivatives will not be computed	XP_CFI_TARGET_EXTRA_M AIN_ambiguous_SINGUL AR_WARN	12
WARN	DEM files were not found. Intersection with the ellipsoid is returned	Calculation performed	XP_CFI_TARGET_EXTRA_MAIN _ELLIPSOID_WARN	13
WARN	Warnnging in XP_DEM_inter	Calculation performed	XP_CFI_TARGET_EXTRA_MAIN	14

			_DEM_INTER_WARN	
WARN	No precise intersection found with DEM. Degraded solution returned	Calculation performed	XP_CFI_TARGET_EXTRA_MAIN _DEM_DEGRADED_SOLUTION_WARN	15

## 7.92 xp\_target\_list\_extra\_main

### 7.92.1 Overview

The `xp_target_list_extra_main` CFI function provides the same results as `xp_target_extra_main` function but for all the targets computed with `xp_target_list_inter` function.

This function has been optimized to improve the run-time performance of the target computation of all the targets and runs in multithreading (Remark: multithreading is not enabled on MacOS platforms, see section 6).

See note on multithreading in section 7.90.1.1.

### 7.92.2 Calling Interface

The calling interface of the `xp_target_list_extra_main` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long choice, target_type, target_number;
    xp_target_id target_id = {NULL};
    xp_target_extra_main_results_list list;
    long ierr[XP_NUM_ERR_TARGET_LIST_EXTRA_MAIN], status;

    status = xp_target_list_extra_main (&target_id, &choice,
                                       &target_type,
                                       &list, ierr);
}
```

The `XP_NUM_ERR_TARGET_LIST_EXTRA_MAIN` constant is defined in the file *explorer\_pointing.h*.

### 7.92.3 Input Parameters

The `xp_target_list_extra_main` CFI function has the following input parameters:

*Table 243: Input parameters of `xp_target_list_extra_main` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>target_id</code>	<code>xp_target_id*</code>	-	Structure that contains the Target results	-	-
<code>choice</code>	<code>long *</code>	-	Flag to select the extra results to be computed. Even though derivatives could be requested by user, they will not be calculated if the target was computed without derivatives (a warning is raised in this case).	-	Complete
<code>target_type</code>	<code>long *</code>		Flag to select the type of target		XP_USER_TARGET_TYPE XP_LOS_TARGET_TYPE XP_DEM_TARGET_TYPE

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Choice. (See Table 3 ).

## 7.92.4 Output Parameters

The output parameters of the `xp_target_list_extra_main` CFI function are:

**Table 244: Output parameters of `xp_target_list_extra_main`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
list	<code>xp_target_extra_main_results_list</code>	-	List of extra results	-	-
ierr	long	-	Error vector	-	-

The values corresponding to returned arrays are the same as in the case of `xp_target_extra_main` (see section 7.91.4).

## 7.92.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_list_extra_main` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_list_extra_main` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 245: Error messages of `xp_target_list_extra_main` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	No target data available	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_MAIN_NO_DATA_ERR</code>	0
ERR	Invalid time reference in target data	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_MAIN_INVALID_TIME_REF_ERR</code>	1
ERR	Error calling to <code>XL_Car_Geo</code> CFI function	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_MAIN_CAR_TO_GEO_ERR</code>	2
ERR	Error getting transformation matrix to Topocentric CS	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_MAIN_TOPO_ERR</code>	3
ERR	Error getting direction angles	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_MAIN_DIR_POINTING_ERR</code>	4
ERR	Error while changing coordinate system	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_MAIN_CS_CHANGE_ERR</code>	5

WARN	Warning: Derivatives cannot be calculated	Calculation performed	XP_CFI_TARGET_LIST_EXTRA_MAIN_DERIV_WARN	6
WARN	Warning calling to XL_Car_Geo CFI function	Calculation performed, but derivatives will not be computed	XP_CFI_TARGET_LIST_EXTRA_MAIN_ambiguous_singular_WARN	7
ERR	Error allocating memory	Calculation performed	XP_CFI_TARGET_LIST_EXTRA_MAIN_MEMORY_ERR	8
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_LIST_EXTRA_MAIN_NO_SUCH_EARTH_TARGET_ERR	9
ERR	Could not compute the DEM target	No calculation performed	XP_CFI_TARGET_LIST_EXTRA_MAIN_EARTH_TARGET_COMPUT_ERR	10
WARN	DEM files were not found. Intersection with the ellipsoid is returned	Calculation performed	XP_CFI_TARGET_LIST_EXTRA_MAIN_ELLIPSOID_WARN	11
WARN	Warning in XP_DEM_inter	Calculation performed	XP_CFI_TARGET_LIST_EXTRA_MAIN_DEM_INTER_WARN	12
ERR	Wrong target type	No calculation performed	XP_CFI_TARGET_LIST_EXTRA_MAIN_WRONG_TARGET_TYPE_ERR	13
WARN	No precise intersection found with DEM. Degraded solution returned	Calculation performed	XP_CFI_TARGET_LIST_EXTRA_MAIN_DEM_DEGRADED_SOLUTION_WARN	14

## 7.93 xp\_target\_extra\_aux

### 7.93.1 Overview

The `xp_target_extra_aux` CFI function computes auxiliary parameters for the target in input data structure.

Note on `target_number` with targets computed with `xp_target_list_inter`:

the `target_number` to be used to get a specific LOS target is an incremental number. That is, if there are  $N$  user targets `US1`, `US2`, ... `USN` and a number of LOS targets for every user target `NLOS1`, `NLOS2`, ..., `NLOS $N$` , if we want to get LOS target with index 1 corresponding to user target `US3`, the `target_number` to be used is `NLOS1+NLOS2+1`.

The `target_number` can also be got with the array returned by `xp_target_get_id_data`.

### 7.93.2 Calling Interface

The calling interface of the `xp_target_extra_aux` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long choice, target_type, target_number;
    double aux_results[XP_SIZE_TARGET_RESULT_AUX],
           aux_results_rate[XP_SIZE_TARGET_RESULT_AUX],
           aux_results_rate_rate[XP_SIZE_TARGET_RESULT_AUX];
    xp_target_id target_id = {NULL};
    long ierr[XP_NUM_ERR_TARGET_EXTRA_AUX], status;

    status = xp_target_extra_aux(&target_id, &choice, &target_type,
                               &target_number,
                               aux_results, aux_results_rate,
                               aux_results_rate_rate, ierr);
}
```

The `XP_SIZE_TARGET_RESULT_AUX` and `XP_NUM_ERR_TARGET_EXTRA_AUX` constants are defined in the file `explorer_pointing.h`.

### 7.93.3 Input Parameters

The `xp_target_extra_aux` CFI function has the following input parameters:

**Table 246: Input parameters of `xp_target_extra_aux`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>target_id</code>	<code>xp_target_id*</code>	-	Structure that contains the Target results	-	-
<code>choice</code>	<code>long *</code>	-	Flag to select the extra results to be computed. Even though derivatives could be requested by user, they will not be calculated if the target was computed without derivatives (a warning is raised in this case).	-	Complete
<code>target_type</code>	<code>long *</code>	-	Flag to select the type of target	-	XP_USER_TARGET_TYPE XP_LOS_TARGET_TYPE XP_DEM_TARGET_TYPE
<code>target_number</code>	<code>long *</code>	-	Target number	-	$\geq 0$

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Choice. (See Table 3).



### 7.93.4 Output Parameters

The output parameters of the `xp_target_extra_aux` CFI function are:

**Table 247: Output parameters of `xp_target_extra_aux`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
aux_results double[XP_SIZE_TARGET_RESULT_AUX]		[0]	Radius of curvature in the look direction at the nadir of the target (Earth fixed CS)	m	$\geq 0$
		[1]	Distance from the nadir of the target to the satellite nadir. (Earth fixed CS)	m	$\geq 0$
		[2]	Minimum distance from the nadir of the target to the ground track (Earth Fixed CS). It is regarded as positive distance when the nadir of the target is located on the left hand side of the ground track.	m	-
		[3]	Distance from the SSP to the point located on the ground track that is at a minimum distance from the nadir of the target (Earth fixed CS) It is regarded as positive distance when that point is located on the ground track ahead the SSP (in the direction of the motion of the SSP)	m	-
		[4]	Mean Local Solar Time at target.	decimal hour	$\geq 0$ < 24
		[5]	True Local Solar Time at target.	decimal hour	$\geq 0$ < 24
		[6]	Right ascension at which the look direction from the satellite to the target points at target point. (True of Date CS)	deg	$\geq 0$ < 360
		[7]	Declination at which the look direction from the satellite to the target points at target point. (True of Date CS)	deg	$\geq -90$ < 90
		[8:XP_SIZE_TARGET_RESULT_AUX]	(dummy)	-	-
aux_results_rate double[XP_SIZE_TARGET_RESULT_AUX]		[0]	Radius of curvature-rate in the look direction at the nadir of the target (Earth fixed CS)	m/s	-

		[1]	Distance-rate from the nadir of the target to the satellite nadir. (Earth fixed CS)	m	$\geq 0$
		[2]	Distance-rate from the nadir of the target to the ground track (Earth fixed CS)	m/s	-
		[3]	Distance-rate from the SSP to the point located on the ground track that is at a minimum distance from the nadir of the target (Earth fixed CS)		
		[4:7]	(dummy)	-	-
		[8]	Northward component of the velocity relative to the Earth of the nadir of the target (Topocentric CS)	m/s	-
		[9]	Eastward component of the velocity relative to the Earth of the nadir of the target (Topocentric CS)	m/s	-
		[10]	Azimuth of the velocity relative to the Earth of the nadir of the target. (Topocentric CS)	deg	$\geq 0$ $< 360$
		[11]	Magnitude of the velocity relative to the Earth of the nadir of the target. (Topocentric CS)	m/s	$\geq 0$
		[12:XP_SI ZE_TARG ET_RESU LT_AUX]	(dummy)	-	-
aux_results_ rate_rate	double[XP_ SI ZE_TARG ET_RESU LT_AUX]	[0]	Radius of curvature-rate-rate in the look direction at the nadir of the target (Earth fixed CS)	m/s	-
		[1]	Distance-rate-rate from the nadir of the target to the satellite nadir. (Earth fixed CS)	m	$\geq 0$
		[2]	Distance-rate-rate from the nadir of the target to the ground track (Earth fixed CS)	m/s	-
		[3]	Distance-rate-rate from the SSP to the point located on the ground track that is at a minimum distance from the nadir of the target (Earth fixed CS)		
		[4:XP_SIZ E_TARGE T_RESUL T_AUX]	(dummy)	-	-

ierr	long	-	Error vector	-	-
------	------	---	--------------	---	---

### 7.93.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the **xp\_target\_extra\_aux** CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library **xp\_get\_msg** (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the **xp\_target\_extra\_aux** function by calling the function of the EO\_POINTING software library **xp\_get\_code** (see [GEN\_SUM]).

**Table 248: Error messages of xp\_target\_extra\_aux function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	No target data available	No calculation performed	XP_CFI_TARGET_EXTRA_A UX_NO_DATA_ERR	0
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_EXTRA_A UX_NO_SUCH_USER_TARGET_ERR	1
ERR	The target does not exist	No calculation performed.	XP_CFI_TARGET_EXTRA_A UX_NO_SUCH_LOS_TARGET_ERR	2
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_EXTRA_A UX_NO_SUCH_EARTH_TARGET_ERR	3
ERR	Could not compute the DEM target	No calculation performed	XP_CFI_TARGET_EXTRA_A UX_EARTH_TARGET_COMPUT_ERR	4
ERR	Wrong target type	No calculation performed	XP_CFI_TARGET_EXTRA_A UX_WRONG_TARGET_TYPE_ERR	5
ERR	Invalid time reference in target data	No calculation performed	XP_CFI_TARGET_EXTRA_A UX_INVALID_TIME_REFERENCE_ERR	6
ERR	Error calling to XL_Car_Geo CFI function	No calculation performed	XP_CFI_TARGET_EXTRA_A UX_CAR_TO_GEO_ERR	7
ERR	Error getting transformation matrix to Topocentric CS.	No calculation performed	XP_CFI_TARGET_EXTRA_AUX_TOPO_ERR	8
ERR	Error getting direction angles	No calculation performed	XP_CFI_TARGET_EXTRA_A UX_DIR_POINTING_ERR	9
ERR	Error computing radius of	No calculation performed	XP_CFI_TARGET_EXTRA_A	10

	curvature		UX_RADII_CURVATURE_C ALC_ERR	
ERR	Error computing pointing after crossing the Earth atmosphere	No calculation performed	XP_CFI_TARGET_EXTRA_A UX_POINTING_AFTER_ATM _CALC_ERR	11
ERR	Error computing distance	No calculation performed	XP_CFI_TARGET_EXTRA_A UX_DISTANCE_CALC_ERR	12
ERR	Error computing velocity of the target's nadir	No calculation performed	XP_CFI_TARGET_EXTRA_A UX_TOP_VEL_CALC_ERR	13
WARN	Error computing MLST of TLST	Calculation performed	XP_CFI_TARGET_EXTRA_A UX_MLST_OR_TLST_CALC_ ERR	14
WARN	Warning: Path from satellite to target occulted by the Earth	Calculation performed	XP_CFI_TARGET_EXTRA_A UX_NEGATIVE_ALTITUDE_ WARN	15
WARN	Warning calling to XL_Car_Geo CFI function	Calculation performed	XP_CFI_TARGET_EXTRA_A UX_AMBIGUOUS_SINGULA R_WARN	16
WARN	Warning: Derivatives cannot be calculated	Calculation performed	XP_CFI_TARGET_EXTRA_A UX_DERIV_WARN	17
WARN	DEM files were not found. Intersection with the ellipsoid is returned	Calculation performed	XP_CFI_TARGET_EXTRA_AUX_ ELLIPSOID_WARN, WARN	18
WARN	Warning in XP_DEM_inter	Calculation performed	XP_CFI_TARGET_EXTRA_AUX_ DEM_INTER_WARN	19
ERR	This function cannot be used with a target id computed with target S/C	Calculation not performed	XP_CFI_TARGET_EXTRA_AUX_ SC_ERR	20
WARN	No precise intersection found with DEM. Degraded solution returned	Calculation performed	XP_CFI_TARGET_EXTRA_AUX_ DEM_DEGRADED_SOLUTION_ WARN	21

## 7.94 xp\_target\_list\_extra\_aux

### 7.94.1 Overview

The `xp_target_list_extra_aux` CFI function provides the same results as `xp_target_extra_aux` function but for all the targets computed with `xp_target_list_inter` function.

This function has been optimized to improve the run-time performance of the target computation of all the targets and runs in multithreading (Remark: multithreading is not enabled on MacOS platforms, see section 6).

See note on multithreading in section 7.90.1.1.

### 7.94.2 Calling Interface

The calling interface of the `xp_target_list_extra_aux` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long choice, target_type, target_number;
    xp_target_id target_id = {NULL};
    xp_target_extra_aux_results_list list;
    long ierr[XP_NUM_ERR_TARGET_LIST_EXTRA_AUX], status;

    status = xp_target_list_extra_aux (&target_id, &choice,
                                     &target_type,
                                     &list, ierr);
}
```

The `XP_NUM_ERR_TARGET_LIST_EXTRA_AUX` constant is defined in the file *explorer\_pointing.h*.

### 7.94.3 Input Parameters

The `xp_target_list_extra_aux` CFI function has the following input parameters:

**Table 249: Input parameters of `xp_target_list_extra_aux` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>target_id</code>	<code>xp_target_id*</code>	-	Structure that contains the Target results	-	-
<code>choice</code>	<code>long *</code>	-	Flag to select the extra results to be computed. Even though derivatives could be requested by user, they will not be calculated if the target was computed without derivatives (a warning is raised in this case).	-	Complete
<code>target_type</code>	<code>long *</code>		Flag to select the type of target		XP_USER_TARGET_TYPE XP_LOS_TARGET_TYPE XP_DEM_TARGET_TYPE

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Choice. (See Table 3 ).

### 7.94.4 Output Parameters

The output parameters of the `xp_target_list_extra_aux` CFI function are:

*Table 250: Output parameters of `xp_target_list_extra_aux`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
list	<code>xp_target_extra_aux_results_list</code>	-	List of extra results	-	-
ierr	long	-	Error vector	-	-

The values corresponding to returned arrays are the same as in the case of `xp_target_extra_aux` (see section 7.93.4).

### 7.94.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_list_extra_aux` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_list_extra_aux` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

*Table 251: Error messages of `xp_target_list_extra_aux` function*

Error type	Error message	Cause and impact	Error code	Error No
ERR	No target data available	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_AUX_NO_DATA_ERR</code>	0
ERR	The target does not exist	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_AUX_NO_SUCH_EARTH_TARGET_ERR</code>	1
ERR	Could not compute the DEM target	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_AUX_EARTH_TARGET_COMPUT_ERR</code>	2
ERR	Wrong target type	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_AUX_WRONG_TARGET_TYPE_ERR</code>	3
ERR	Invalid time reference in target data	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_AUX_INVALID_TIME_REFERENCE_ERR</code>	4
ERR	Error calling to <code>XL_Car_Geo</code>	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_AUX_ERROR_CALLING_TO_XL_CAR_GEO_ERR</code>	5

	CFI function		A UX_CAR_TO_GEO_ERR	
ERR	Error getting tranformation matrix to Topocentric CS.	No calculation performed	XP_CFI_TARGET_LIST_EXTRA_AUX_TOPO_ERR	6
ERR	Error getting direction angles	No calculation performed	XP_CFI_TARGET_LIST_EXTRA_AUX_DIR_POINTING_ERR	7
ERR	Error computing radius of curvature	No calculation performed	XP_CFI_TARGET_LIST_EXTRA_AUX_RADII_CURVATURE_CALC_ERR	8
ERR	Error computing pointing after crossing the Earth atmosphere	No calculation performed	XP_CFI_TARGET_LIST_EXTRA_AUX_POINTING_AFTER_ATM_CALC_ERR	9
ERR	Error computing distance	No calculation performed	XP_CFI_TARGET_LIST_EXTRA_AUX_DISTANCE_CALC_ERR	10
ERR	Error computing velocity of the target's nadir	No calculation performed	XP_CFI_TARGET_LIST_EXTRA_AUX_TOP_VEL_CALC_ERR	11
WARN	Error computing MLST of TLST	Calculation performed	XP_CFI_TARGET_LIST_EXTRA_AUX_MLST_OR_TLST_CALC_ERR	12
WARN	Warning: Path from satellite to target occulted by the Earth	Calculation performed	XP_CFI_TARGET_LIST_EXTRA_AUX_NEGATIVE_ALTITUDE_WARN	13
WARN	Warning calling to XL_Car_Geo CFI function	Calculation performed	XP_CFI_TARGET_LIST_EXTRA_AUX_AMBIGUOUS_SINGULAR_WARN	14
WARN	Warning: Derivatives cannot be calculated	Calculation performed	XP_CFI_TARGET_LIST_EXTRA_AUX_DERIV_WARN	15
WARN	DEM files were not found. Intersection with the ellipsoid is returned	Calculation performed	XP_CFI_TARGET_LIST_EXTRA_AUX_ELLIPSOID_WARN, WARN	16
WARN	Warnging in XP_DEM_inter	Calculation performed	XP_CFI_TARGET_LIST_EXTRA_AUX_DEM_INTER_WARN	17
ERR	This function cannot be used with a target id computed with target S/C	No calculation performed	XP_CFI_TARGET_LIST_EXTRA_AUX_SC_ERR	18
ERR	Memory allocation error	No calculation performed	XP_CFI_TARGET_LIST_EXTRA_AUX_MEMORY_ERR	19
WARN	No precise intersection found with DEM. Degraded solution returned	Calculation performed	XP_CFI_TARGET_LIST_EXTRA_AUX_DEM_DEGRADED_SOLUTION_WARN	20



## 7.95 xp\_target\_extra\_ef\_target

### 7.95.1 Overview

The `xp_target_extra_ef_target` CFI function computes the parameter for an Earth fixed target related to the target in input data structure.

Note on `target_number` with targets computed with `xp_target_list_inter`:

the `target_number` to be used to get a specific LOS target is an incremental number. That is, if there are N user targets US1, US2, ... USN and a number of LOS targets for every user target NLOS1, NLOS2, ..., NLOS<sub>N</sub>, if we want to get LOS target with index 1 corresponding to user target US3, the `target_number` to be used is NLOS1+NLOS2+1.

The `target_number` can also be got with the array returned by `xp_target_get_id_data`.

### 7.95.2 Calling Interface

The calling interface of the `xp_target_extra_ef_target` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long target_type, target_number, choice;
    double freq;
    double ef_target_results_rate[XP_SIZE_EF_TARGET_RESULT],
    ef_target_results_rate_rate[XP_SIZE_EF_TARGET_RESULT];
    xp_target_id target_id = {NULL};
    long ierr[XP_NUM_ERR_TARGET_EXTRA_EF_TARGET], status;

    status = xp_target_extra_ef_target(&target_id, &choice,
                                     &target_type, &target_number, &freq,
                                     ef_target_results_rate,
                                     ef_target_results_rate_rate, ierr);
}
```

The `XP_SIZE_TARGET_RESULT_EF_TARGET` and `XP_NUM_ERR_TARGET_EXTRA_EF_TARGET` constants are defined in the file `explorer_pointing.h`.

### 7.95.3 Input Parameters

The `xp_target_extra_ef_target` CFI function has the following input parameters:

**Table 252: Input parameters of `xp_target_extra_ef_target` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>target_id</code>	<code>xp_target_id*</code>	-	Structure that contains the Target results	-	-
<code>choice</code>	<code>long *</code>	-	Flag to select the extra results to be computed. Even though derivatives could be requested by user, they will not be calculated if the target was computed without derivatives (a warning is raised in this case).	-	Allowed values: (0) <code>XP_NO_DER</code> (1) <code>XP_DER_1ST</code> (2) <code>XP_DER_2ND</code>
<code>target_type</code>	<code>long *</code>	-	Flag to select the type of target	-	<code>XP_USER_TARGET_TYPE</code> <code>XP_LOS_TARGET_TYPE</code> <code>XP_DEM_TARGET_TYPE</code>
<code>target_number</code>	<code>long *</code>	-	Target number	-	$\geq 0$
<code>freq</code>	<code>double *</code>	-	Frequency of the signal	Hz	$\geq 0$

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Choice. (See Table 3).

## 7.95.4 Output Parameters

The output parameters of the `xp_target_extra_ef_target` CFI function are:

**Table 253: Output parameters of `xp_target_extra_ef_target`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
ef_target_results_rate	double [XP_SIZE_EF_TARGET_RESULT]	[0]	2-way Doppler shift of the signal (Earth Fixed CS)	Hz	-
		[1]	Earthfixed target to satellite range-rate. (Earth Fixed CS)	m/s	-
		[2]	Earthfixed target to satellite azimuth-rate. (Topocentric CS)	deg/s	-
		[3]	Earthfixed target to satellite elevation-rate. (Topocentric CS)	deg/s	-
		[4]	Satellite to earthfixed target azimuth-rate. (Topocentric CS)	deg/s	-
		[5]	Satellite to earthfixed target elevation-rate. (Topocentric CS)	deg/s	-
		[6]	Satellite to earthfixed target azimuth-rate. (Attitude Frame)	deg/s	-
		[7]	Satellite to earthfixed target elevation-rate. (Attitude Frame)	deg/s	-
ef_target_results_rate_rate	double [XP_SIZE_EF_TARGET_RESULT]	[0]	(dummy)	-	-
		[1]	Earthfixed target to satellite range-rate-rate. (Earth Fixed CS)	m/s <sup>2</sup>	-
		[2]	Earthfixed target to satellite azimuth-rate-rate. (Topocentric CS)	deg/s <sup>2</sup>	-
		[3]	Earthfixed target to satellite elevation-rate-rate. (Topocentric CS)	deg/s <sup>2</sup>	-
		[4]	Satellite to earthfixed target azimuth-rate-rate. (Topocentric CS)	deg/s <sup>2</sup>	-
		[5]	Satellite to earthfixed target elevation-rate-rate. (Topocentric CS)	deg/s <sup>2</sup>	-
		[6]	Satellite to earthfixed target azimuth-rate-rate. (Attitude Frame)	deg/s <sup>2</sup>	-
		[7]	Satellite to earthfixed target elevation-rate-rate.	deg/s <sup>2</sup>	-

			(Attitude Frame)		
ierr	long	-	Error vector	-	-

### 7.95.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_extra_ef_target` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_extra_ef_target` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 254: Error messages of `xp_target_extra_ef_target` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	No target data available	No calculation performed	XP_CFI_TARGET_EXTRA_E F_TARGET_NO_DATA_ERR	0
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_EXTRA_E F_TARGET_NO_SUCH_USER _TARGET_ERR	1
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_EXTRA_E F_TARGET_NO_SUCH_LOS_ TARGET_ERR	2
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_EXTRA_E F_TARGET_NO_SUCH_EAR TH_TARGET_ERR	3
ERR	Could not compute the DEM target	No calculation performed	XP_CFI_TARGET_EXTRA_E F_TARGET_EARTH_TARGE T_COMPUT_ERR	4
ERR	Wrong target type	No calculation performed	XP_CFI_TARGET_EXTRA_E F_TARGET_WRONG_TARGE T_TYPE_ERR	5
ERR	Wrong input deriv flag	No calculation performed	XP_CFI_TARGET_EXTRA_E F_TARGET_DERIV_FLAG_E RR	6
ERR	Error getting target geodetic coordinates	No calculation performed	XP_CFI_TARGET_EXTRA_E F_TARGET_GEO_COORD_E RR	7
ERR	Invalid time reference in target data	No calculation performed	XP_CFI_TARGET_EXTRA_E F_TARGET_INVALID_TIME_ REF_ERR	8
ERR	Internal computation error	No calculation performed	XP_CFI_TARGET_EXTRA_E F_TARGET_RANGE_OR_POI	9

			NTING_CALC_ERR	
ERR	Wrong Atmospheric model in target data	No calculation performed	XP_CFI_TARGET_EXTRA_E F_TARGET_MODE_COMBIN ATION_SWITCHES_ERR	10
ERR	Error calling to XL_Car_Geo CFI function	No calculation performed	XP_CFI_TARGET_EXTRA_E F_TARGET_CAR_GEO_ERR	11
WARN	2nd. Derivatives are not available	Calculation performed	XP_CFI_TARGET_EXTRA_E F_TARGET_DER_2ND_NOT_ AVAIL_WARN	12
WARN	Warning calling to XL_Car_Geo CFI function	Calculation performed	XP_CFI_TARGET_EXTRA_E F_TARGET_AMBIGUOUS_SI NGULAR_WARN	13
WARN	1ST Derivative not computed for target. Satellite to target azimuth and elevation rates (SRAR CS) cannot be calculated	Calculation performed, except for azimuth and elevation rates in SRAR coordinate system.	XP_CFI_TARGET_EXTRA_E F_TARGET_DERIV_FLAG_W ARN	14
WARN	DEM files were not found. Intersection with the ellipsoid is returned	Calculation performed	XP_CFI_TARGET_EXTRA_E F_TARGET_DEM_INTER_W ARN	15
WARN	Warning in XP_DEM_inter	Calculation performed	XP_CFI_TARGET_EXTRA_E F_TARGET_DEM_INTER_W ARN	16
ERR	This function cannot be used with a target id computed with target S/C	No calculation performed	XP_CFI_TARGET_EXTRA_E F_TARGET_ID_COMPUTED WITH_TARGET_SC_ERR	17
WARN	No precise intersection found with DEM. Degraded solution returned	Calculation performed	XP_CFI_TARGET_EXTRA_E F_TARGET_DEM_DEGRADE D_SOLUTION_WARN	18

## 7.96 xp\_target\_list\_extra\_ef\_target

### 7.96.1 Overview

The `xp_target_list_extra_ef_target` CFI function provides the same results as `xp_target_extra_ef_target` function but for all the targets computed with `xp_target_list_inter` function.

This function has been optimized to improve the run-time performance of the target computation of all the targets and runs in multithreading (Remark: multithreading is not enabled on MacOS platforms, see section 6).

See note on multithreading in section 7.90.1.1.

### 7.96.2 Calling Interface

The calling interface of the `xp_target_list_extra_ef_target` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long choice, target_type, target_number;
    double freq;
    xp_target_id target_id = {NULL};
    xp_target_extra_ef_target_results_list list;
    long ierr[XP_NUM_ERR_TARGET_LIST_EXTRA_EF_TARGET], status;

    status = xp_target_list_extra_ef_target (&target_id, &choice,
                                             &target_type, &freq,
                                             &list, ierr);
}
```

The `XP_NUM_ERR_TARGET_LIST_EXTRA_EF_TARGET` constant is defined in the file `explorer_pointing.h`.

### 7.96.3 Input Parameters

The `xp_target_list_extra_ef_target` CFI function has the following input parameters:

*Table 255: Input parameters of `xp_target_list_extra_ef_target` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>target_id</code>	<code>xp_target_id*</code>	-	Structure that contains the Target results	-	-
<code>choice</code>	<code>long *</code>	-	Flag to select the extra results to be computed. Even though derivatives could be requested by user, they will not be calculated if the target was computed without derivatives (a warning is raised in this case).	-	Allowed values: (0) <code>XP_NO_DER</code> (1) <code>XP_DER_1ST</code> (2) <code>XP_DER_2ND</code>
<code>target_type</code>	<code>long *</code>	-	Flag to select the type of target		<code>XP_USER_TARGET_TYPE</code> <code>XP_LOS_TARGET_TYPE</code> <code>XP_DEM_TARGET_TYPE</code>
<code>freq</code>	<code>double *</code>	-	Frequency of the signal	Hz	<code>&gt;=0</code>

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Choice. (See Table 3 ).

## 7.96.4 Output Parameters

The output parameters of the `xp_target_list_extra_ef_target` CFI function are:

**Table 256: Output parameters of `xp_target_list_extra_ef_target`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
list	<code>xp_target_extra_ef_target_results_list</code>	-	List of extra results	-	-
ierr	long	-	Error vector	-	-

The values corresponding to returned arrays are the same as in the case of `xp_target_extra_ef_target` (see section 7.95.4).

## 7.96.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_list_extra_ef_target` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_list_extra_ef_target` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 257: Error messages of `xp_target_list_extra_ef_target` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	No target data available	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_E F_TARGET_NO_DATA_ERR</code>	0
ERR	Wrong target type	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_E F_TARGET_WRONG_TARGET_TYPE_ERR</code>	1
ERR	Wrong input deriv flag	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_E F_TARGET_DERIV_FLAG_ERR</code>	2
ERR	Error getting target geodetic coordinates	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_E F_TARGET_GEO_COORD_ERR</code>	3
ERR	Invalid time reference in target data	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_E F_TARGET_INVALID_TIME_REF_ERR</code>	4
ERR	Internal computation error	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_</code>	5



			EF_TARGET_RANGE_OR_POINTING_CALC_ERR	
ERR	Wrong Atmospheric model in target data	No calculation performed	XP_CFI_TARGET_LIST_EXTRA_EF_TARGET_MODE_COMBINATION_SWITCHES_ERR	6
ERR	Error calling to XL_Car_Geo CFI function	No calculation performed	XP_CFI_TARGET_LIST_EXTRA_EF_TARGET_CAR_GEO_ERR	7
WARN	2nd. Derivatives are not available	Calculation performed	XP_CFI_TARGET_LIST_EXTRA_EF_TARGET_DER_2ND_NOT_AVAIL_WARN	8
WARN	Warning calling to XL_Car_Geo CFI function	Calculation performed	XP_CFI_TARGET_LIST_EXTRA_EF_TARGET_AMBIGUOUS_SINGULAR_WARN	9
WARN	1ST Derivative not computed for target. Satellite to target azimuth and elevation rates (SRAR CS) cannot be calculated	Calculation performed, except for azimuth and elevation rates in SRAR coordinate system.	XP_CFI_TARGET_LIST_EXTRA_EF_TARGET_DERIV_FLAG_WARN	10
WARN	DEM files were not found. Intersection with the ellipsoid is returned	Calculation performed	XP_CFI_TARGET_LIST_EXTRA_EF_ELLIPSOID_WARN	11
WARN	Warning in XP_DEM_inter	Calculation performed	XP_CFI_TARGET_LIST_EXTRA_EF_DEM_INTER_WARN	12
ERR	This function cannot be used with a target id computed with target S/C	No calculation performed	XP_CFI_TARGET_LIST_EXTRA_EF_TARGET_SC_ERR	13
ERR	Memory allocation error	No calculation performed	XP_CFI_TARGET_LIST_EXTRA_AUX_MEMORY_ERR	14
WARN	No precise intersection found with DEM. Degraded solution returned	Calculation performed	XP_CFI_TARGET_LIST_EXTRA_EF_TARGET_DEM_DEGRADED_SOLUTION_WARN	15
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_LIST_EXTRA_EF_TARGET_NO_SUCH_EARTH_TARGET_ERR	16
ERR	Could not compute the DEM target	No calculation performed	XP_CFI_TARGET_LIST_EXTRA_EF_TARGET_EARTH_TARGET_COMPUT_ERR	17

## 7.97 xp\_target\_extra\_target\_to\_sun

### 7.97.1 Overview

The `xp_target_extra_target_to_sun` CFI function computes extra parameters related to the pointing from the target in input data structure to the sun.

Notes:

1) On `target_number` with targets computed with `xp_target_list_inter`:

the `target_number` to be used to get a specific LOS target is an incremental number. That is, if there are  $N$  user targets `US1`, `US2`, ... `USN` and a number of LOS targets for every user target `NLOS1`, `NLOS2`, ..., `NLOS $N$` , if we want to get LOS target with index 1 corresponding to user target `US3`, the `target_number` to be used is `NLOS1+NLOS2+1`.

The `target_number` can also be got with the array returned by `xp_target_get_id_data`.

2) A correction can be applied in order to compensate the travel time of light. This correction is not applied with default model. To activate this correction, the Sun model in `xl_model_id` must be initialized with the enum `XL_MODEL_SUN_TRAVEL_TIME` using the function `xl_model_init` (see [LIB\_SUM]).

### 7.97.2 Calling Interface

The calling interface of the `xp_target_extra_target_to_sun` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long target_type, target_number, choice, iray;
    double freq;
    double sun_results[XP_SIZE_SUN_RESULT],
           sun_results_rate[XP_SIZE_SUN_RESULT],
           sun_results_rate_rate[XP_SIZE_SUN_RESULT];
    xp_target_id target_id = {NULL};
    long ierr[XP_NUM_ERR_TARGET_EXTRA_TARGET_TO_SUN], status;

    status = xp_target_extra_target_to_sun
              (&target_id, &choice, &target_type,
               &target_number, &iray, &freq,
               sun_results, sun_results_rate,
               sun_results_rate_rate, ierr);
}
```

---

The `XP_SIZE_TARGET_RESULT_TARGET_TO_SUN` and `XP_NUM_ERR_TARGET_EXTRA_TARGET_TO_SUN` constants are defined in the file *explorer\_pointing.h*.

### 7.97.3 Input Parameters

The `xp_target_extra_target_to_sun` CFI function has the following input parameters:

**Table 258: Input parameters of `xp_target_extra_target_to_sun` function**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>target_id</code>	<code>xp_target_id*</code>	-	Structure that contains the Target results	-	-
<code>choice</code>	<code>long *</code>	-	Flag to select the extra results to be computed. Even though derivatives could be requested by user, they will not be calculated if the target was computed without derivatives (a warning is raised in this case).	-	Allowed values: (0) <code>XP_NO_DER</code> (1) <code>XP_DER_1ST</code> (2) <code>XP_DER_2ND</code>
<code>target_type</code>	<code>long *</code>	-	Flag to select the type of target	-	<code>XP_USER_TARGET_T TYPE</code> <code>XP_LOS_TARGET_TY PE</code> <code>XP_DEM_TARGET_T YPE</code>
<code>target_number</code>	<code>long *</code>	-	Target number	-	$\geq 0$
<code>iray</code>	<code>long *</code>	-	Not used. The atmosphere refraction model can be defined via <code>atmos_id</code> initialization.	-	-
<code>freq</code>	<code>double *</code>	-	Frequency of the signal	Hz	$\geq 0$

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Choice. (See Table 3 ).

## 7.97.4 Output Parameters

The output parameters of the `xp_target_extra_target_to_sun` CFI function are:

**Table 259: Output parameters of `xp_target_extra_target_to_sun`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
sun_results	double [XP_SIZE_SUN_RESULT]	[0]	Target to Sun (centre) azimuth. (Topocentric CS)	deg	$\geq 0$ $< 360$
		[1]	Target to Sun (centre) elevation. (Topocentric CS)	deg	$\geq -90$ $\leq +90$
		[2]	Tangent altitude over the Earth in the target to Sun (centre) look direction. (Earth fixed CS)	m	-
		[3]	Target to Sun visibility flag: - 1: Sun eclipsed by the Earth. +1: Sun in sight.	-	+1, -1
		[4:XP_SIZE_SUN_RESULT]	(dummy)	-	-
sun_results_rate	double [XP_SIZE_SUN_RESULT]	[0]	Target to Sun (centre) azimuth-rate. (Topocentric CS)	deg/s	-
		[1]	Target to Sun (centre) elevation-rate. (Topocentric CS)	deg/s	-
		[2:XP_SIZE_SUN_RESULT]	(dummy)	-	-
sun_results_rate_rate	double [XP_SIZE_SUN_RESULT]	[0]	Target to Sun (centre) azimuth-rate. (Topocentric CS)	deg/s <sup>2</sup>	-
		[1]	Target to Sun (centre) elevation-rate. (Topocentric CS)	deg/s <sup>2</sup>	-
		[2:XP_SIZE_SUN_RESULT]	(dummy)	-	-
ierr	long	-	Error vector	-	-

## 7.97.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_extra_target_to_sun` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_extra_target_to_sun` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]) .

**Table 260: Error messages of `xp_target_extra_target_to_sun` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	No target data available	No calculation performed	XP_CFI_TARGET_TO_SUN_NO_DATA_ERR	0
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_TO_SUN_NO_SUCH_USER_TARGET_ERR	1
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_TO_SUN_NO_SUCH_LOS_TARGET_ERR	2
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_TO_SUN_NO_SUCH_EARTH_TARGET_ERR	3
ERR	Could not compute the DEM target	No calculation performed	XP_CFI_TARGET_TO_SUN_EARTH_TARGET_COMPUT_ERR	4
ERR	Wrong target type	No calculation performed	XP_CFI_TARGET_TO_SUN_WRONG_TARGET_TYPE_ERR	5
ERR	Wrong input deriv flag	No calculation performed	XP_CFI_TARGET_TO_SUN_DERIV_FLAG_ERR	6
ERR	Error getting Sun position	No calculation performed	XP_CFI_TARGET_TO_SUN_SUN_POS_ERR	7
ERR	Invalid time reference in target data.	No calculation performed	XP_CFI_TARGET_TO_SUN_INVALID_TIME_REF_ERR	8
ERR	Error changing from TOD to EF.	No calculation performed	XP_CFI_TARGET_TO_SUN_TOD_TO_EF_ERR	9
ERR	Error getting direction vector from target to Sun.	No calculation performed	XP_CFI_TARGET_TO_SUN_DIR_VECTOR_ERR	10
ERR	Error getting geodetic coordinates of the target	No calculation performed	XP_CFI_TARGET_TO_SUN_CAR_GEO_ERR	11
ERR	Internal Computation Error. Target not Found.	No calculation performed	XP_CFI_TARGET_TO_SUN_TARGET_NOT_FOUND_ERR	12
ERR	Wrong Atmospheric model in target data.	No calculation performed	XP_CFI_TARGET_TO_SUN_MODE_COMBINATION_SWITCHES_ERR	13

ERR	Error getting transformation matrix to Topocentric CS.	No calculation performed	XP_CFI_TARGET_TO_SUN_TOPO_ERR	14
ERR	Error getting Azimut/Elevation	No calculation performed	XP_CFI_TARGET_TO_SUN_DIR_POINTING_ERR	15
WARN	Input Derivative flag level is too high. Derivative flag set to the value used in the main target function	Calculation performed	XP_CFI_TARGET_TO_SUN_DERIV_FLAG_WARN	16
WARN	Precision not reached while calculating Sun pointing parameters	Calculation performed	XP_CFI_TARGET_TO_SUN_MAX_ALLOWED_ITERATIONS_WARN	17
WARN	DEM files were not found. Intersection with the ellipsoid is returned"	Calculation performed	XP_CFI_TARGET_TO_SUN_ELLIPSOID_WARN	18
WARN	Warning in XP_DEM_inter	Calculation performed	XP_CFI_TARGET_TO_SUN_DEM_INTER_WARN	19
WARN	The ray tracing flag (iray) is ignored	Calculation performed. A message informs the user that this parameter is not used. If the variable iray is equal to XP_NO_REF_INIT (=0), the warning is avoided	XP_CFI_TARGET_TO_SUN_IRAY_ID_WARN	20
WARN	No precise intersection found with DEM. Degraded solution returned	Calculation performed	XP_CFI_TARGET_TO_SUN_DEM_DEGRADED_SOLUTION_WARN	21

## 7.98 xp\_target\_list\_extra\_target\_to\_sun

### 7.98.1 Overview

The `xp_target_list_extra_target_to_sun` CFI function provides the same results as `xp_target_extra_target_to_sun` function but for all the targets computed with `xp_target_list_inter` function.

This function has been optimized to improve the run-time performance of the target computation of all the targets and runs in multithreading (Remark: multithreading is not enabled on MacOS platforms, see section 6).

See note on multithreading in section 7.90.1.1.

Note: a correction can be applied in order to compensate the travel time of Sun light travel time. This correction is not applied with default model. To activate this correction, the Sun model in `xl_model_id` must be initialized with the enum `XL_MODEL_SUN_TRAVEL_TIME` using the function `xl_model_init` (see [LIB\_SUM]).

### 7.98.2 Calling Interface

The calling interface of the `xp_target_list_extra_to_sun` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long choice, target_type, target_number;
    double freq;
    long iray;
    xp_target_id target_id = {NULL};
    xp_target_extra_sun_target_results_list list;
    long ierr[XP_NUM_ERR_TARGET_LIST_EXTRA_TARGET_TO_SUN], status;

    status = xp_target_list_extra_target_to_sun (&target_id, &choice,
                                                &target_type, &iray, &freq,
                                                &list, ierr);
}
```

The `XP_NUM_ERR_TARGET_LIST_EXTRA_TARGET_TO_SUN` constant is defined in the file `explorer_pointing.h`.



### 7.98.3 Input Parameters

The `xp_target_list_extra_target_to_sun` CFI function has the following input parameters:

*Table 261: Input parameters of `xp_target_list_extra_target_to_sun` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>target_id</code>	<code>xp_target_id*</code>	-	Structure that contains the Target results	-	-
<code>choice</code>	<code>long *</code>	-	Flag to select the extra results to be computed. Even though derivatives could be requested by user, they will not be calculated if the target was computed without derivatives (a warning is raised in this case).	-	Allowed values: (0) <code>XP_NO_DER</code> (1) <code>XP_DER_1ST</code> (2) <code>XP_DER_2ND</code>
<code>target_type</code>	<code>long *</code>	-	Flag to select the type of target	-	<code>XP_USER_TARGET_T TYPE</code> <code>XP_LOS_TARGET_TY PE</code> <code>XP_DEM_TARGET_T YPE</code>
<code>iray</code>	<code>long *</code>	-	Not used. The atmosphere refraction model can be defined via <code>atmos_id</code> initialization.	-	-
<code>freq</code>	<code>double *</code>	-	Frequency of the signal	Hz	$\geq 0$

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Choice. (See Table 3 ).

## 7.98.4 Output Parameters

The output parameters of the `xp_target_list_extra_target_to_sunCFI` function are:

**Table 262: Output parameters of `xp_target_list_extra_target_to_sun`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
list	<code>xp_target_extra_sun_target_results_list</code>	-	List of extra results	-	-
ierr	long	-	Error vector	-	-

The values corresponding to returned arrays are the same as in the case of `xp_target_extra_target_to_sun` (see section 7.97.4).

## 7.98.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_list_extra_target_to_sun` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_list_extra_target_to_sun` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 263: Error messages of `xp_target_list_extra_target_to_sun` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	No target data available	No calculation performed	<code>XP_CFI_TARGET_LIST_TO_SUN_NO_DATA_ERR</code>	0
ERR	The target does not exist	No calculation performed	<code>XP_CFI_TARGET_LIST_TO_SUN_NO_SUCH_EARTH_TARGET_ERR</code>	1
ERR	Could not compute the DEM target	No calculation performed	<code>XP_CFI_TARGET_LIST_TO_SUN_EARTH_TARGET_COMPUT_ERR</code>	2
ERR	Wrong target type	No calculation performed	<code>XP_CFI_TARGET_LIST_TO_SUN_WRONG_TARGET_TYPE_ERR</code>	3
ERR	Wrong input deriv flag	No calculation performed	<code>XP_CFI_TARGET_LIST_TO_SUN_DERIV_FLAG_ERR</code>	4
ERR	Error getting Sun position	No calculation performed	<code>XP_CFI_TARGET_LIST_TO_SUN</code>	5

			N_S UN_POS_ERR	
ERR	Invalid time reference in target data.	No calculation performed	XP_CFI_TARGET_LIST_TO_SUN_INVALID_TIME_REF_ERR	6
ERR	Error changing from TOD to EF.	No calculation performed	XP_CFI_TARGET_LIST_TO_SUN_TOD_TO_EF_ERR	7
ERR	Error getting direction vector from target to Sun.	No calculation performed	XP_CFI_TARGET_LIST_TO_SUN_DIR_VECTOR_ERR	8
ERR	Error getting geodetic coordinates of the target	No calculation performed	XP_CFI_TARGET_LIST_TO_SUN_CAR_GEO_ERR	9
ERR	Internal Computation Error. Target not Found.	No calculation performed	XP_CFI_TARGET_LIST_TO_SUN_TARGET_NOT_FOUND_ERR	10
ERR	Wrong Atmospheric model in target data.	No calculation performed	XP_CFI_TARGET_LIST_TO_SUN_MODE_COMBINATION_SWITCHES_ERR	11
ERR	Error getting tranformation matrix to Topocentric CS.	No calculation performed	XP_CFI_TARGET_LIST_TO_SUN_TOPO_ERR	12
ERR	Error getting Azimut/Elevation	No calculation performed	XP_CFI_TARGET_LIST_TO_SUN_DIR_POINTING_ERR	13
WARN	Input Derivative flag level is too high. Derivative flag set to the value used in the main target function	Calculation performed	XP_CFI_TARGET_LIST_TO_SUN_DERIV_FLAG_WARN	14
WARN	Precision not reached while calculating Sun pointing parameters	Calculation performed	XP_CFI_TARGET_LIST_TO_SUN_MAX_ALLOWED_ITERATIONS_WARN	15
WARN	DEM files were not found. Intersection with the ellipsoid is returned"	Calculation performed	XP_CFI_TARGET_LIST_TO_SUN_ELLIPSOID_WARN	16
WARN	Warning in XP_DEM_inter	Calculation performed	XP_CFI_TARGET_LIST_TO_SUN_DEM_INTER_WARN	17
WARN	The ray tracing flag (iray) is ignored	Calculation performed. A message informs the user that this parameter is not used. If the variable iray is equal to XP_NO_REF_INIT (=0), the warning is avoided	XP_CFI_TARGET_LIST_TO_SUN_IRAY_ID_WARN	18
ERR	Error allocating memory	No calculation performed	XP_CFI_TARGET_LIST_LIST_TO_SUN_MEMORY_ERR	19
WARN	No precise intersection found with DEM. Degraded solution returned	Calculation performed	XP_CFI_TARGET_LIST_TO_SUN_DEM_DEGRADED_SOLUTION_WARN	20

## 7.99 xp\_target\_extra\_target\_to\_moon

### 7.99.1 Overview

The `xp_target_extra_target_to_moon` CFI function computes extra parameters related to the pointing from the target in input data structure to the moon.

Note on `target_number` with targets computed with `xp_target_list_inter`:

the `target_number` to be used to get a specific LOS target is an incremental number. That is, if there are  $N$  user targets US1, US2, ... USN and a number of LOS targets for every user target NLOS1, NLOS2, ..., NLOS $N$ , if we want to get LOS target with index 1 corresponding to user target US3, the `target_number` to be used is NLOS1+NLOS2+1.

The `target_number` can also be got with the array returned by `xp_target_get_id_data`.

### 7.99.2 Calling Interface

The calling interface of the `xp_target_extra_target_to_moon` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long target_type, target_number, choice, iray;
    double freq;
    double moon_results[XP_SIZE_moon_RESULT],
           moon_results_rate[XP_SIZE_MOON_RESULT],
           moon_results_rate_rate[XP_SIZE_MOON_RESULT];
    xp_target_id target_id = {NULL};
    long ierr[XP_NUM_ERR_TARGET_EXTRA_TARGET_TO_MOON], status;

    status = xp_target_extra_target_to_moon
              (&target_id, &choice, &target_type,
               &target_number, &iray, &freq,
               moon_results, moon_results_rate,
               moon_results_rate_rate, ierr);
}
```

The `XP_SIZE_TARGET_RESULT_TARGET_TO_MOON` and `XP_NUM_ERR_TARGET_EXTRA_TARGET_TO_MOON` constants are defined in the file `explorer_pointing.h`.

### 7.99.3 Input Parameters

The `xp_target_extra_target_to_moon` CFI function has the following input parameters:

*Table 264: Input parameters of `xp_target_extra_target_to_moon` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>target_id</code>	<code>xp_target_id*</code>	-	Structure that contains the Target results	-	-
<code>choice</code>	<code>long *</code>	-	Flag to select the extra results to be computed. Even though derivatives could be requested by user, they will not be calculated if the target was computed without derivatives (a warning is raised in this case).	-	Allowed values: (0) <code>XP_NO_DER</code> (1) <code>XP_DER_1ST</code> (2) <code>XP_DER_2ND</code>
<code>target_type</code>	<code>long *</code>	-	Flag to select the type of target	-	<code>XP_USER_TARGET_T TYPE</code> <code>XP_LOS_TARGET_TY PE</code> <code>XP_DEM_TARGET_T YPE</code>
<code>target_number</code>	<code>long *</code>	-	Target number	-	$\geq 0$
<code>iray</code>	<code>long *</code>	-	Not used. The atmosphere refraction model can be defined via <code>atmos_id</code> initialization.	-	-
<code>freq</code>	<code>double *</code>	-	Frequency of the signal	Hz	$\geq 0$

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Choice. (See Table 3 ).

### 7.99.4 Output Parameters

The output parameters of the `xp_target_extra_target_to_moon` CFI function are:

**Table 265: Output parameters of `xp_target_extra_target_to_moon`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
moon_results	double [XP_SIZE_MOON_RESULT]	[0]	Target to Moon (centre) azimuth. (Topocentric CS)	deg	$\geq 0$ $< 360$
		[1]	Target to Moon (centre) el. (Topocentric CS)	deg	$\geq -90$ $\leq +90$
		[2]	Tangent altitude over the Earth in the target to Moon (centre) look direction. (Earth fixed CS)	m	-
		[3]	Target to Moon visibility flag: - 1: Moon eclipsed by the Earth. +1: Moon in sight.	-	+1, -1
		[4:XP_SIZE_MOON_RESULT]	(dummy)	-	-
moon_results_rate	double [XP_SIZE_MOON_RESULT]	[0]	Target to Moon (centre) azimuth-rate. (Topocentric CS)	deg/s	-
		[1]	Target to Moon (centre) elevation-rate. (Topocentric CS)	deg/s	-
		[2:XP_SIZE_MOON_RESULT]	(dummy)	-	-
moon_results_rate_rate	double [XP_SIZE_MOON_RESULT]	[0]	Target to Moon (centre) azimuth-rate. (Topocentric CS)	deg/s <sup>2</sup>	-
		[1]	Target to Moon (centre) elevation-rate. (Topocentric CS)	deg/s <sup>2</sup>	-
		[2:XP_SIZE_MOON_RESULT]	(dummy)	-	-
ierr	long	-	Error vector	-	-

### 7.99.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_extra_target_to_moon` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_extra_target_to_moon` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 266: Error messages of `xp_target_extra_target_to_moon` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	No target data available	No calculation performed	XP_CFI_TARGET_TO_MOON_NO_DATA_ERR	0
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_TO_MOON_NO_SUCH_USER_TARGET_ERR	1
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_TO_MOON_NO_SUCH_LOS_TARGET_ERR	2
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_TO_MOON_NO_SUCH_EARTH_TARGET_ERR	3
ERR	Could not compute the DEM target	No calculation performed	XP_CFI_TARGET_TO_MOON_EARTH_TARGET_COMPUT_ERR	4
ERR	Wrong target type	No calculation performed	XP_CFI_TARGET_TO_MOON_WRONG_TARGET_TYPE_ERR	5
ERR	Wrong input deriv flag	No calculation performed	XP_CFI_TARGET_TO_MOON_DERIV_FLAG_ERR	6
ERR	Error getting Moon position	No calculation performed	XP_CFI_TARGET_TO_MOON_MOON_POS_ERR	7
ERR	Invalid time reference in target data.	No calculation performed	XP_CFI_TARGET_TO_MOON_INVALID_TIME_REF_ERR	8
ERR	Error changing from TOD to EF.	No calculation performed	XP_CFI_TARGET_TO_MOON_TOD_TO_EF_ERR	9
ERR	Error getting direction vector from target to Moon.	No calculation performed	XP_CFI_TARGET_TO_MOON_DIR_VECTOR_ERR	10
ERR	Error getting geodetic coordinates of the target	No calculation performed	XP_CFI_TARGET_TO_MOON_CAR_GEO_ERR	11
ERR	Internal Computation Error. Target not Found.	No calculation performed	XP_CFI_TARGET_TO_MOON_TARGET_NOT_FOUND_ERR	12
ERR	Wrong Atmospheric model in target data.	No calculation performed	XP_CFI_TARGET_TO_MOON_MODE_COMBINATION_SW	13

			ITCHES_ERR	
ERR	Error getting tranformation matrix to Topocentric CS.	No calculation performed	XP_CFI_TARGET_TO_MOON_TOPO_ERR	14
ERR	Error getting Azimut/Elevation	No calculation performed	XP_CFI_TARGET_TO_MOON_DIR_POINTING_ERR	15
WARN	Input Derivative flag level is too high. Derivative flag set to the value used in the main target function	Calculation performed	XP_CFI_TARGET_TO_MOON_DERIV_FLAG_WARN	16
WARN	Precision not reached while calculating Moon pointing parameters	Calculation performed	XP_CFI_TARGET_TO_MOON_MAX_ALLOWED_ITERATIONS_WARN	17
WARN	DEM files were not found. Intersection with the ellipsoid is returned	Calculation performed	XP_CFI_TARGET_TO_MOON_ELLIPSOID_WARN	18
WARN	Warning in XP_DEM_inter	Calculation performed	XP_CFI_TARGET_TO_MOON_DEM_INTER_WARN	19
WARN	The ray tracing flag (iray) is ignored	Calculation performed A message informs the user that this parameter is not used. If the variable iray is equal to XP_NO_REF_INIT (=0), the warning is avoided	XP_CFI_TARGET_TO_MOON_IRAY_ID_WARN	20
WARN	No precise intersection found with DEM. Degraded solution returned	Calculation performed	XP_CFI_TARGET_TO_MOON_DEM_DEGRADED_SOLUTION_WARN	21



## 7.100 xp\_target\_list\_extra\_target\_to\_moon

### 7.100.1 Overview

The `xp_target_list_extra_target_to_moon` CFI function provides the same results as `xp_target_extra_target_to_moon` function but for all the targets computed with `xp_target_list_inter` function.

This function has been optimized to improve the run-time performance of the target computation of all the targets and runs in multithreading (Remark: multithreading is not enabled on MacOS platforms, see section 6).

See note on multithreading in section 7.90.1.1.

### 7.100.2 Calling Interface

The calling interface of the `xp_target_list_extra_to_moon` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long choice, target_type, target_number;
    double freq;
    long iray;
    xp_target_id target_id = {NULL};
    xp_target_extra_moon_target_results_list list;
    long ierr[XP_NUM_ERR_TARGET_LIST_EXTRA_TARGET_TO_MOON], status;

    status = xp_target_list_extra_target_to_moon (&target_id, &choice,
                                                &target_type, &iray, &freq,
                                                &list, ierr);
}
```

The `XP_NUM_ERR_TARGET_LIST_EXTRA_TARGET_TO_MOON` constant is defined in the file `explorer_pointing.h`.

### 7.100.3 Input Parameters

The `xp_target_list_extra_target_to_moon` CFI function has the following input parameters:

*Table 267: Input parameters of `xp_target_list_extra_target_to_moon` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>target_id</code>	<code>xp_target_id*</code>	-	Structure that contains the Target results	-	-
<code>choice</code>	<code>long *</code>	-	Flag to select the extra results to be computed. Even though derivatives could be requested by user, they will not be calculated if the target was computed without derivatives (a warning is raised in this case).	-	Allowed values: (0) <code>XP_NO_DER</code> (1) <code>XP_DER_1ST</code> (2) <code>XP_DER_2ND</code>
<code>target_type</code>	<code>long *</code>	-	Flag to select the type of target	-	<code>XP_USER_TARGET_T TYPE</code> <code>XP_LOS_TARGET_TY PE</code> <code>XP_DEM_TARGET_T YPE</code>
<code>iray</code>	<code>long *</code>	-	Not used. The atmosphere refraction model can be defined via <code>atmos_id</code> initialization.	-	-
<code>freq</code>	<code>double *</code>	-	Frequency of the signal	Hz	$\geq 0$

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Choice. (See Table 3).

### 7.100.4 Output Parameters

The output parameters of the `xp_target_list_extra_target_to_moon` CFI function are:

**Table 268: Output parameters of `xp_target_list_extra_target_to_moon`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
list	<code>xp_target_extra_moon_target_results_list</code>	-	List of extra results	-	-
ierr	long	-	Error vector	-	-

The values corresponding to returned arrays are the same as in the case of `xp_target_extra_target_to_moon` (see section 7.99.4).

### 7.100.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_list_extra_target_to_moon` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_list_extra_target_to_moon` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 269: Error messages of `xp_target_list_extra_target_to_moon` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	No target data available	No calculation performed	<code>XP_CFI_TARGET_LIST_TO_MOON_NO_DATA_ERR</code>	0
ERR	The target does not exist	No calculation performed	<code>XP_CFI_TARGET_LIST_TO_MOON_NO_SUCH_EARTH_TARGET_ERR</code>	1
ERR	Could not compute the DEM target	No calculation performed	<code>XP_CFI_TARGET_LIST_TO_MOON_EARTH_TARGET_COMPUT_ERR</code>	2
ERR	Wrong target type	No calculation performed	<code>XP_CFI_TARGET_LIST_TO_MOON_WRONG_TARGET_TYPE_ERR</code>	3
ERR	Wrong input deriv flag	No calculation performed	<code>XP_CFI_TARGET_LIST_TO_MOON_DERIV_FLAG_ERR</code>	4

ERR	Error getting Moon position	No calculation performed	XP_CFI_TARGET_LIST_TO_MOON_MOON_POS_ERR	5
ERR	Invalid time reference in target data.	No calculation performed	XP_CFI_TARGET_LIST_TO_MOON_INVALID_TIME_REF_ERR	6
ERR	Error changing from TOD to EF.	No calculation performed	XP_CFI_TARGET_LIST_TO_MOON_TOD_TO_EF_ERR	7
ERR	Error getting direction vector from target to Moon.	No calculation performed	XP_CFI_TARGET_LIST_TO_MOON_DIR_VECTOR_ERR	8
ERR	Error getting geodetic coordinates of the target	No calculation performed	XP_CFI_TARGET_LIST_TO_MOON_CAR_GEO_ERR	9
ERR	Internal Computation Error. Target not Found.	No calculation performed	XP_CFI_TARGET_LIST_TO_MOON_TARGET_NOT_FOUND_ERR	10
ERR	Wrong Atmospheric model in target data.	No calculation performed	XP_CFI_TARGET_LIST_TO_MOON_MODE_COMBINATION_SWITCHES_ERR	11
ERR	Error getting tranformation matrix to Topocentric CS.	No calculation performed	XP_CFI_TARGET_LIST_TO_MOON_TOPO_ERR	12
ERR	Error getting Azimut/Elevation	No calculation performed	XP_CFI_TARGET_LIST_TO_MOON_DIR_POINTING_ERR	13
WARN	Input Derivative flag level is too high. Derivative flag set to the value used in the main target function	Calculation performed	XP_CFI_TARGET_LIST_TO_MOON_DERIV_FLAG_WARN	14
WARN	Precision not reached while calculating Moon pointing parameters	Calculation performed	XP_CFI_TARGET_LIST_TO_MOON_MAX_ALLOWED_ITERATIONS_WARN	15
WARN	DEM files were not found. Intersection with the ellipsoid is returned	Calculation performed	XP_CFI_TARGET_LIST_TO_MOON_ELLIPSOID_WARN	16
WARN	Warning in XP_DEM_inter	Calculation performed	XP_CFI_TARGET_LIST_TO_MOON_DEM_INTER_WARN	17
WARN	The ray tracing flag (iray) is ignored	Calculation performed A message informs the user that this parameter is not used. If the variable iray is equal to XP_NO_REF_INIT (=0), the warning is avoided	XP_CFI_TARGET_LIST_TO_MOON_IRAY_ID_WARN	18
ERR	Error allocating memory	No calculation performed	XP_CFI_TARGET_LIST_TO_MOON_MEMORY_ERR	19
WARN	No precise intersection found	Calculation performed	XP_CFI_TARGET_LIST_TO_MOON	20

	with DEM. Degraded solution returned		ON_DEM_DEGRADED_SOLUTI ON_WARN	
--	--------------------------------------	--	-----------------------------------	--

## 7.101 xp\_target\_extra\_specular\_reflection

### 7.101.1 Overview

The `xp_target_extra_specular_reflection` CFI function calculates the direction of the specular reflection associated to a given target.

Note on `target_number` with targets computed with `xp_target_list_inter`:

the `target_number` to be used to get a specific LOS target is an incremental number. That is, if there are  $N$  user targets `US1`, `US2`, ... `USN` and a number of LOS targets for every user target `NLOS1`, `NLOS2`, ..., `NLOS $N$` , if we want to get LOS target with index 1 corresponding to user target `US3`, the `target_number` to be used is `NLOS1+NLOS2+1`.

The `target_number` can also be got with the array returned by `xp_target_get_id_data`.

### 7.101.2 Calling Interface

The calling interface of the `xp_target_extra_specular_reflection` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long target_type, target_number, choice, iray;
    double freq;
    double spec_reflec_results[XP_SIZE_TARGET_RESULT_SPEC_REFL],
           spec_reflec_results_rate[XP_SIZE_TARGET_RESULT_SPEC_REFL],
           spec_reflec_results_rate_rate[XP_SIZE_TARGET_RESULT_SPEC_REFL];
    xp_target_id target_id = {NULL};
    long ierr[XP_NUM_ERR_TARGET_EXTRA_SPEC_REFL], status;

    status = xp_target_extra_specular_reflection
              (&target_id, &choice, &target_type,
               &target_number,
               &deflection_north, &deflection_east,
               spec_reflec_results,
               spec_reflec_results_rate,
               spec_reflec_results_rate_rate, ierr);
}
```

The `XP_SIZE_TARGET_RESULT_SPEC_REFL` and `XP_NUM_ERR_TARGET_EXTRA_SPEC_REFL` constants are defined in the file `explorer_pointing.h`.

### 7.101.3 Input Parameters

The `xp_target_extra_specular_reflection` CFI function has the following input parameters:

*Table 270: Input parameters of `xp_target_extra_specular_reflection` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>target_id</code>	<code>xp_target_id*</code>	-	Structure that contains the Target results	-	-
<code>choice</code>	<code>long *</code>	-	Flag to select the extra results to be computed. Even though derivatives could be requested by user, they will not be calculated if the target was computed without derivatives (a warning is raised in this case).	-	Allowed values: (0) <code>XP_NO_DER</code> (1) <code>XP_DER_1ST</code> (2) <code>XP_DER_2ND</code>
<code>target_type</code>	<code>long *</code>	-	Flag to select the type of target	-	<code>XP_USER_TARGET_TYPE</code> <code>XP_LOS_TARGET_TYPE</code> <code>XP_DEM_TARGET_TYPE</code>
<code>target_number</code>	<code>long *</code>	-	Target number	-	$\geq 0$
<code>deflection_north</code>	<code>double *</code>	-	North-South component of the vertical deflection	deg	$\geq -90$ $\leq 90$
<code>deflection_east</code>	<code>double *</code>	-	East-West component of the vertical deflection	deg	$\geq -90$ $\leq 90$

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Choice. (See Table 3).

### 7.101.4 Output Parameters

The output parameters of the `xp_target_extra_specular_reflection` CFI function are:

**Table 271: Output parameters of `xp_target_extra_specular_reflection`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
spec_reflec_results	double [XP_SIZE_TARGET_RESULT_SPEC_REFL]	[0]	X coordinate of reflected pointing direction. (EF CS)	m	-
		[1]	Y coordinate of reflected pointing direction. (EF CS)	m	-
		[2]	Z coordinate of reflected pointing direction. (EF CS)	m	-
		[3]	Azimuth of the reflected pointing direction. (Topocentric CS)	deg	[0, 360]
		[4]	Elevation of the reflected pointing direction. (Topocentric CS)	deg	[-90, 90]
		[5]	Right ascension at which the reflected pointing direction points at target point. (True of Date CS)	deg	[0, 360]
		[6]	Declination at which the reflected pointing direction points at target point. (True of Date CS)	deg	[-90, 90]
spec_reflec_results_rate	double [XP_SIZE_TARGET_RESULT_SPEC_REFL]	[0]	X velocity of reflected pointing direction. (EF CS)	m/s	-
		[1]	Y velocity of reflected pointing direction. (EF CS)	m/s	-
		[2]	Z velocity of reflected pointing direction. (EF CS)	m/s	-
		[3]	Azimuth rate of the reflected pointing direction (Topocentric CS)	deg/s	-
		[4]	Elevation rate of the reflected pointing direction (Topocentric CS)	deg/s	-
		[5]	Right ascension rate at which the reflected pointing direction points at target point. (True of Date CS)	deg/s	-
		[6]	Declination rate at which the reflected pointing direction points at target point. (True of Date CS)	deg/s	-



spec_reflec_results_rate	double [XP_SIZE_TARGET_RESULT_SPEC_REFL]	[0]	X acceleration of reflected point in direction. (EF CS)	m/s <sup>2</sup>	-
		[1]	Y acceleration of reflected point in direction. (EF CS)	m/s <sup>2</sup>	-
		[2]	Z acceleration of reflected point in direction. (EF CS)	m/s <sup>2</sup>	-
		[3]	Azimuth rate rate of the reflected pointing direction (Topocentric CS)	deg/s <sup>2</sup>	-
		[4]	Elevation rate rate of the reflected pointing direction (Topocentric CS)	deg/s <sup>2</sup>	-
		[5]	Right ascension rate rate at which the reflected pointing direction points at target point. (True of Date CS)	deg/s <sup>2</sup>	-
		[6]	Declination rate rate at which the reflected pointing direction points at target point. (True of Date CS)	deg/s <sup>2</sup>	-
ierr	long	-	Error vector	-	-

### 7.101.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the **xp\_target\_extra\_specular\_reflection** CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library **xp\_get\_msg** (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the **xp\_target\_extra\_specular\_reflection** function by calling the function of the EO\_POINTING software library **xp\_get\_code** (see [GEN\_SUM]).

**Table 272: Error messages of xp\_target\_extra\_specular\_reflection function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	No target data available	No calculation performed	XP_CFI_TARGET_EXTRA_SPECULAR_REFLECT_NO_DATA_ERR	0
ERR	Input deflection angle is out of range	No calculation performed	XP_CFI_TARGET_EXTRA_SPECULAR_REFLECT_WRONG_DEF_ANGLE_ERR	1

ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_EXTRA_S PECULAR_REFLECT_NO_SU CH_USER_TARGET_ERR	2
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_EXTRA_S PECULAR_REFLECT_NO_SU CH_LOS_TARGET_ERR	3
ERR	Could not compute the DEM target	No calculation performed	XP_CFI_TARGET_EXTRA_S PECULAR_REFLECT_EART H_TARGET_COMPUT_ERR	4
ERR	The target does not exist	No calculation performed	XP_CFI_TARGET_EXTRA_S PECULAR_REFLECT_NO_SU CH_EARTH_TARGET_ERR	5
ERR	Wrong target type	No calculation performed	XP_CFI_TARGET_EXTRA_S PECULAR_REFLECT_WRON G_TARGET_TYPE_ERR	6
ERR	Error getting geodetic coordinates of the target	No calculation performed	XP_CFI_TARGET_EXTRA_S PECULAR_REFLECT_CAR_T O_GEO_ERR	7
ERR	Error getting tranformation matrix to Topocentric CS	No calculation performed	XP_CFI_TARGET_EXTRA_S PECULAR_REFLECT_TOPO_ CS_ERR	8
ERR	Error getting direction angles	No calculation performed	XP_CFI_TARGET_EXTRA_S PECULAR_REFLECT_DIR_P OINTING_ERR	9
ERR	Error while changing coordinate system	No calculation performed	XP_CFI_TARGET_EXTRA_S PECULAR_REFLECT_CHAN GE_CS_ERR	10
WARN	Input Derivative flag level is too high. Derivative flag set to the value used in the main target function	Calculation performed	XP_CFI_TARGET_EXTRA_S PECULAR_REFLECT_DERIV _WARN	11
WARN	DEM files were not found. Intersection with the ellipsoid is returned	Calculation performed	XP_CFI_TARGET_EXTRA_SPEC ULAR_REFLECT_WARN	12
WARN	Warning in XP_DEM_inter	Calculation performed	XP_CFI_TARGET_EXTRA_SPEC ULAR_REFLECT_DEM_INTER_ WARN	13
ERR	This function cannot be used with a target id computed with target S/C	No calculation performed	XP_CFI_TARGET_EXTRA_SPEC ULAR_REFLECT_SC_ERR	14
WARN	No precise intersection found with DEM. Degraded solution returned	Calculation performed	XP_CFI_TARGET_EXTRA_SPEC ULAR_REFLECT_DEM_DEGRA DED_SOLUTION_WARN	15

## 7.102 xp\_target\_list\_extra\_specular\_reflection

### 7.102.1 Overview

The `xp_target_list_extra_specular_reflection` CFI function provides the same results as `xp_target_extra_specular_reflection` function but for all the targets computed with `xp_target_list_inter` function.

This function has been optimized to improve the run-time performance of the target computation of all the targets and runs in multithreading (Remark: multithreading is not enabled on MacOS platforms, see section 6).

See note on multithreading in section 7.90.1.1.

### 7.102.2 Calling Interface

The calling interface of the `xp_target_list_extra_specular_reflection` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    long choice, target_type, target_number;
    double deflection_north, deflection_east;
    long iray;
    xp_target_id target_id = {NULL};
    xp_target_extra_spec_reflec_target_results_list list;
    long ierr[XP_NUM_ERR_TARGET_LIST_EXTRA_SPEC_REFL], status;

    status = xp_target_list_extra_specular_reflection (&target_id,
                                                    &choice, &target_type,
                                                    &deflection_north,
                                                    &deflection_east,
                                                    &list, ierr);
}
```

The `XP_NUM_ERR_TARGET_LIST_EXTRA_SPEC_REFL` constant is defined in the file *explorer\_pointing.h*.

### 7.102.3 Input Parameters

The `xp_target_list_extra_specular_reflection` CFI function has the following input parameters:

*Table 273: Input parameters of `xp_target_list_extra_specular_reflection` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>target_id</code>	<code>xp_target_id*</code>	-	Structure that contains the Target results	-	-
<code>choice</code>	<code>long *</code>	-	Flag to select the extra results to be computed. Even though derivatives could be requested by user, they will not be calculated if the target was computed without derivatives (a warning is raised in this case).	-	Allowed values: (0) <code>XP_NO_DER</code> (1) <code>XP_DER_1ST</code> (2) <code>XP_DER_2ND</code>
<code>target_type</code>	<code>long *</code>	-	Flag to select the type of target	-	<code>XP_USER_TARGET_T TYPE</code> <code>XP_LOS_TARGET_TY PE</code> <code>XP_DEM_TARGET_T YPE</code>
<code>deflection_north</code>	<code>double *</code>	-	North-South component of the vertical deflection	deg	$\geq -90$ $\leq 90$
<code>deflection_east</code>	<code>double *</code>	-	East-West component of the vertical deflection	deg	$\geq -90$ $\leq 90$

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Choice. (See Table 3).

### 7.102.4 Output Parameters

The output parameters of the `xp_target_list_extra_specular_reflection` CFI function are:

**Table 274: Output parameters of `xp_target_list_extra_specular_reflection`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
list	<code>xp_target_extra_spec_reflec_target_results_list</code>	-	List of extra results	-	-
ierr	long	-	Error vector	-	-

The values corresponding to returned arrays are the same as in the case of `xp_target_extra_specular_reflection` (see section 7.101.4).

### 7.102.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_list_extra_specular_reflection` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_list_extra_specular_reflection` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 275: Error messages of `xp_target_list_extra_specular_reflection` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	No target data available	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_SPECULAR_REFLECT_NO_DATA_ERR</code>	0
ERR	Input deflection angle is out of range	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_SPECULAR_REFLECT_WRONG_DEF_ANGLE_ERR</code>	1
ERR	Could not compute the DEM target	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_SPECULAR_REFLECT_EARTH_TARGET_COMPUT_ERR</code>	2
ERR	Wrong target type	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_SPECULAR_REFLECT_WRONG_TARGET_TYPE_ERR</code>	3
ERR	The target does not exist	No calculation performed	<code>XP_CFI_TARGET_LIST_EXTRA_</code>	4

			SPECULAR_REFLECT_NO_SUCH_EARTH_TARGET_ERR	
ERR	Error getting geodetic coordinates of the target	No calculation performed	XP_CFI_TARGET_LIST_EXTRASPECULAR_REFLECT_CARTO_GEO_ERR	5
ERR	Error getting transformation matrix to Topocentric CS	No calculation performed	XP_CFI_TARGET_LIST_EXTRASPECULAR_REFLECT_TOPOCS_ERR	6
ERR	Error getting direction angles	No calculation performed	XP_CFI_TARGET_LIST_EXTRASPECULAR_REFLECT_DIR_POINTING_ERR	7
ERR	Error while changing coordinate system	No calculation performed	XP_CFI_TARGET_LIST_EXTRASPECULAR_REFLECT_CHANGE_CS_ERR	8
WARN	Input Derivative flag level is too high. Derivative flag set to the value used in the main target function	Calculation performed	XP_CFI_TARGET_LIST_EXTRASPECULAR_REFLECT_DERIV_WARN	9
WARN	DEM files were not found. Intersection with the ellipsoid is returned	No calculation performed	XP_CFI_TARGET_LIST_EXTRASPECULAR_REFLECT_ELLIPSOID_WARN	10
WARN	Warning in XP_DEM_inter	Calculation performed	XP_CFI_TARGET_LIST_EXTRASPECULAR_REFLECT_DEM_INTER_WARN	11
ERR	This function cannot be used with a target id computed with target S/C	No calculation performed	XP_CFI_TARGET_LIST_EXTRASPECULAR_REFLECT_SC_ERR	12
ERR	Error allocating memory	No calculation performed	XP_CFI_TARGET_LIST_EXTRASPECULAR_REFLECT_MEMORY_ERR	13
WARN	No precise intersection found with DEM. Degraded solution returned	Calculation performed	XP_CFI_TARGET_LIST_EXTRASPECULAR_REFLECT_DEM_DEGRADED_SOLUTION_WARN	14

## 7.103xp\_target\_close

### 7.103.1 Overview

The `xp_target_close` CFI function cleans up any memory allocation performed by the Target functions.

### 7.103.2 Calling Interface

The calling interface of the `xp_target_close` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    xp_target_id target_id = {NULL};
    long ierr[XP_NUM_ERR_TARGET_CLOSE], status;

    status = xp_target_close(&target_id, ierr);
}
```

The `XP_NUM_ERR_TARGET_CLOSE` constant is defined in the file *explorer\_pointing.h*.

### 7.103.3 Input Parameters

The `xp_target_close` CFI function has the following input parameters:

*Table 276: Input parameters of `xp_target_close` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
target_id	xp_target_id*	-	Structure that contains the Target results	-	-

### 7.103.4 Output Parameters

The output parameters of the `xp_target_close` CFI function are:

*Table 277: Output parameters of `xp_target_close`*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
ierr	long	-	Error vector	-	-

### 7.103.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_target_close` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_target_close` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

*Table 278: Error messages of `xp_target_close` function*

Error type	Error message	Cause and impact	Error code	Error No
ERR	Target ID is not initialized or it is being used	No calculation performed	XP_CFI_TARGET_CLOSE_WRONG_ID_ERR	11



## 7.104 xp\_target\_get\_id\_data

### 7.104.1 Overview

The `xp_target_get_id_data` CFI function returns the target initialization data.

If the `target_id` has been computed with `xp_target_list_inter` function, this function returns an array with as many elements as `num_user_target`. for every element, the list of LOS targets corresponding to user target are provided.

If the `target_id` has been computed with any other function, the returned array has only one position with the list of user targets and the list of LOS targets.

Note on usage: the user must reserve the input-output array to the function, no internal allocation is done.

### 7.104.2 Calling interface

The calling interface of the `xp_target_get_id_data` CFI function is the following (input parameters are underlined>):

```
#include <explorer_lib.h>
{
    xp_target_id target_id;
    long status;
    xp_target_id_data *data;
    status = xp_target_get_id_data (&target_id, data);
}
```

### 7.104.3 Input parameters

The `xp_target_get_id_data` CFI function has the following input parameters:

*Table 279: Input parameters of xp\_target\_get\_id\_data function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
target_id	xp_target_id *	-	Target Id.	-	-

### 7.104.4 Output parameters

The output parameters of the `xp_target_get_id_data` CFI function are:

*Table 280: Output parameters of xp\_target\_get\_id\_data function*

C name	C type	Array	Description	Unit	Allowed Range
--------	--------	-------	-------------	------	---------------

		Element	(Reference)	(Format)	
xp_target_get_id_data	long	-	Status flag	-	-
data	xp_target_id_data*	-	Target initialization data	-	-

### **7.104.5 Warnings and errors**

This function does not return any error/warning code. Only the status of the function indicates if the execution was correct or not.

The possible causes of error are:

- The target\_id was not computed.

## 7.105 xp\_gen\_dem\_max\_altitude\_file

### 7.105.1 Overview

The `xp_gen_dem_max_altitude_file` CFI function generates a binary file with the maximum altitudes corresponding to every mini-tile, as described in input DEM configuration file. This file is needed to the maximum altitudes algo as described in section 7.65.4.

### 7.105.2 Calling Interface

The calling interface of the `xp_gen_dem_max_altitude_file` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    char *dem_config_file;
    long ierr[XP_NUM_ERR_DEM_MAX_ALT_FILE], status;

    status = xp_gen_dem_max_altitude_file(dem_config_file,
                                           ierr);
}
```

The `XP_NUM_ERR_DEM_MAX_ALT_FILE` constant is defined in the file *explorer\_pointing.h*.

### 7.105.3 Input Parameters

The `xp_gen_dem_max_altitude_file` CFI function has the following input parameters:

*Table 281: Input parameters of `xp_gen_dem_max_altitude_file` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>dem_config_file</code>	Char*	-	DEM configuration file with description of mini tiles	-	-

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Choice. (See Table 3).

### 7.105.4 Output Parameters

The output parameters of the `xp_gen_dem_max_altitude_file` CFI function are:

**Table 282: Output parameters of `xp_gen_dem_max_altitude_file`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
ierr	long	-	Error vector	-	-

### 7.105.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_gen_dem_max_altitude_file` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_gen_dem_max_altitude_file` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 283: Error messages of `xp_gen_dem_max_altitude` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Error reading DEM configuration file	No computation performed	XP_GEN_DEM_MAX_ALTITUDE_READ_DEM_CFG_ERR	0
ERR	Error allocating memory	No computation performed	XP_GEN_DEM_MAX_ALTITUDE_MEMORY_ERR	1
WARN	Some DEM tiles are not present. Corresponding altitudes set to zero.	Computation performed	XP_GEN_DEM_MAX_ALTITUDE_OPEN_TILE_WARN	2
ERR	Error reading DEM tile %s	No computation performed	XP_GEN_DEM_MAX_ALTITUDE_READ_TILE_ERR	3
ERR	Error initializing DEM ID	No computation performed	XP_GEN_DEM_MAX_ALTITUDE_DEM_INIT_ERR	4
ERR	Error closing DEM ID	No computation performed	XP_GEN_DEM_MAX_ALTITUDE_DEM_CLOSE_ERR	5
ERR	Error opening output file %s	No computation performed	XP_GEN_DEM_MAX_ALTITUDE_OPEN_OUTPUT_FILE_ERR	6
ERR	Error writing to output file %s	No computation performed	XP_GEN_DEM_MAX_ALTITUDE_WRITE_OUTPUT_ERR	7
ERR	No output file name provided	No computation performed	XP_GEN_DEM_MAX_ALTITUDE_CONFIG_ERR	8

### **7.105.6 Executable Program**

The `gen_dem_max_altitude_file` executable program can be called from a Unix shell as:

```
gen_dem_max_altitude_file -dem_cfg_file dem_configuration_file  
    [ -v ]  
    [ -xl_v ]  
    [ -xo_v ]  
    [ -xp_v ]  
    [ -help ]  
    [ -show ]
```

Note that:

- Order of parameters does not matter.
- Bracketed parameters are not mandatory.
- The input DEM configuration file must have the "MiniTiles\_Configuration" tag in "DEM\_User\_Parameters" section.
- [ **-xl\_v** ] option for EO\_LIB Verbose mode.
- [ **-xo\_v** ] option for EO\_ORBIT Verbose mode.
- [ **-xp\_v** ] option for EO\_POINTING Verbose mode.
- [ **-v** ] option for Verbose mode for all libraries (default is Silent).
- [ **-show** ] displays the inputs of the function and the results.

Example:

```
gen_dem_max_altitude_file -dem_config_file  
S1A_TEST_INT_DEMCFG_00000000T000000_99999999T999999_0003.EOF
```

## 7.106 xp\_gen\_dem\_altitudes\_from\_ellipsoid

### 7.106.1 Overview

The `xp_gen_dem_altitudes_from_ellipsoid` CFI function generates, for an input DEM ACE2 or GDEM V2 dataset, whose altitudes are expressed w.r.t the geoid, an equivalent DEM but with the heights referenced to the ellipsoid, not to the geoid. This way the geoid undulation computation can be avoided at runtime and performance can be improved.

It can be computed the whole DEM or only a set of tiles, depending on the inputs to the function. The field “set\_type” of `xp_gen_dem_alt_from_ellipsoid_inputs` struct can take the following values to select which DEM set to compute:

- `XP_ALL_DEM`: all DEM tiles will be computed.
- `XP_DEM_SET`: only the tiles of the DEM fully inside the interval provided by “lon\_min”, “lon\_max”, “lat\_min” and “lat\_max” fields of `xp_gen_dem_alt_from_ellipsoid_inputs` struct are computed.

### 7.106.2 Calling Interface

The calling interface of the `xp_gen_dem_altitudes_from_ellipsoid` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    char *dem_config_file, *output_dir;
    long num_harmonics;
    xp_gen_dem_alt_from_ellipsoid_inputs inputs;
    long ierr[XP_NUM_ERR_DEM_ALT_FROM_ELLIPSOID], status;

    status = xp_gen_dem_altitudes_from_ellipsoid(dem_config_file,
                                                &num_harmonics, output_dir,
                                                &inputs, ierr);
}
```

The `XP_NUM_ERR_DEM_ALT_FROM_ELLIPSOID` constant is defined in the file `explorer_pointing.h`.

### 7.106.3 Input Parameters

The `xp_gen_dem_altitudes_from_ellipsoid` CFI function has the following input parameters:

*Table 284: Input parameters of `xp_gen_dem_altitudes_from_ellipsoid` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>dem_config_file</code>	<code>char*</code>	-	DEM configuration file with description of mini tiles	-	-
<code>num_harmonics</code>	<code>long*</code>	-	Number of harmonics to be used in geoid computation.	-	>0
<code>output_dir</code>	<code>char*</code>	-	Output directory where generated DEM will be placed	-	-
<code>inputs</code>	<code>xp_gen_dem_alt_from_ellipsoid_inputs*</code>	-	DEM set to be processed	For range limits: deg	Longitude: [-180., 180.] Latitude: [-90., 90.]

It is possible to use enumeration values rather than integer values for some of the input arguments:

- Choice. (See Table 3).



### 7.106.4 Output Parameters

The output parameters of the `xp_gen_dem_altitudes_from_ellipsoid` CFI function are:

**Table 285: Output parameters of `xp_gen_dem_altitudes_from_ellipsoid`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
ierr	long	-	Error vector	-	-

### 7.106.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_gen_dem_altitudes_from_ellipsoid` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the `EO_POINTING` software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (`WARN`) or an error (`ERR`), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_gen_dem_altitudes_from_ellipsoid` function by calling the function of the `EO_POINTING` software library `xp_get_code` (see [GEN\_SUM]).

**Table 286: Error messages of `xp_gen_dem_max_altitude` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Error reading DEM configuration file	No computation performed	XP_CFI_GEN_DEM_ALTITUDE_FROM_ELLIPSOID_READ_DEM_CFG_ERR	0
ERR	Wrong input DEM type	No computation performed	XP_CFI_GEN_DEM_ALTITUDE_FROM_ELLIPSOID_WRONG_DEM_TYPE_ERR	1
ERR	Error allocating memory	No computation performed	XP_CFI_GEN_DEM_ALTITUDE_FROM_ELLIPSOID_MEMORY_ERR	2
ERR	Error reading DEM tile %s	No computation performed	XP_CFI_GEN_DEM_ALTITUDE_FROM_ELLIPSOID_READ_TILE_ERR	3
ERR	Error computing geoid undulation	No computation performed	XP_CFI_GEN_DEM_ALTITUDE_FROM_ELLIPSOID_GEOID_UNDU_ERR	4
ERR	Error opening output file %s	No computation performed	XP_CFI_GEN_DEM_ALTITUDE_FROM_ELLIPSOID_OPEN_OUTPUT_ERR	5
ERR	Error writing to output file %s	No computation performed	XP_CFI_GEN_DEM_ALTITUDE_FROM_ELLIPSOID_WRITE_OUT	6

			PUT_ERR	
WARN	Some DEM tiles are not present. Corresponding altitudes set to zero.	Computation performed	XP_CFI_GEN_DEM_ALTITUDE_FROM_ELLIPSOID_OPEN_TILE_WARN	7
ERR	Wrong input DEM set type	No computation performed	XP_CFI_GEN_DEM_ALTITUDE_FROM_ELLIPSOID_WRONG_DEM_SET_TYPE_ERR	8
ERR	Wrong input longitude interval (must be in interval [-180, 180] deg)	No computation performed	XP_CFI_GEN_DEM_ALTITUDE_FROM_ELLIPSOID_WRONG_SET_LONGITUDE_ERR	9
ERR	Wrong input latitude interval (must be in interval [-90, 90] deg)	No computation performed	XP_CFI_GEN_DEM_ALTITUDE_FROM_ELLIPSOID_WRONG_SET_LATITUDE_ERR	10

## 7.107 xp\_attitude\_transform

### 7.107.1 Overview

The `xp_attitude_transform` CFI function allows the user to change the reference frame in which the internal data of the attitude ids are expressed.

Remark: all attitude related computations are performed in the True of Date Coordinate System. This means that, if one attitude id has been initialized with data expressed in another reference frame (e.g. attitude file with quaternions expressed in EF), at each call of a function using such attitude id (e.g. `xp_attitude_compute`) one or more conversions to True of Date will be performed. If the reference frame is changed to True of Date (using `xp_attitude_transform`), such conversions will not be executed and this will result in a run-time performance improvement.

Note: transformation of attitude ids that are initialized with Start Tracker files is not supported.

### 7.107.2 Calling Interface

The calling interface of the `xp_attitude_transform` CFI function is the following (input parameters are underlined):

```
#include <explorer_pointing.h>
{
    xp_transform_cfg transform_cfg;
    xp_attitude_def attitude_def;
    long ierr[XP_NUM_ERR_ATTITUDE_TRANSFORM], status;

    status = xp_attitude_transform(&transform_cfg, &attitude_def,
                                   ierr);
}
```

The `XP_NUM_ERR_ATTITUDE_TRANSFORM` constant is defined in the file *explorer\_pointing.h*.

### 7.107.3 Input Parameters

The `xp_attitude_transform` CFI function has the following input parameters:

*Table 287: Input parameters of `xp_attitude_transform` function*

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>transform_cfg</code>	<code>xp_transform_cfg*</code>	-	Structure containing parameters used for the transformation	-	-
<code>attitude_def</code>	<code>xp_attitude_def*</code>	-	Structure containing: satellite nominal attitude, satellite attitude target, instrument attitude target and attitude type		

### 7.107.4 Output Parameters

The output parameters of the `xp_attitude_transform` CFI function are:

**Table 288: Output parameters of `xp_attitude_transform`**

C name	C type	Array Element	Description (Reference)	Unit (Format)	Allowed Range
<code>attitude_def</code>	<code>xp_attitude_def*</code>	-	Structure containing: satellite nominal attitude, satellite attitude target, instrument attitude target and attitude type (Input/Output parameter)	-	-
<code>ierr</code>	<code>long</code>	-	Error vector	-	-

### 7.107.5 Warnings and Errors

Next table lists the possible error messages that can be returned by the `xp_attitude_transform` CFI function after translating the returned error vector into the equivalent list of error messages by calling the function of the EO\_POINTING software library `xp_get_msg` (see [GEN\_SUM]).

This table also indicates the type of message returned, i.e. either a warning (WARN) or an error (ERR), the cause of such a message and the impact on the performed calculation.

The table is completed by the error code and value. These error codes can be obtained by translating the error vector returned by the `xp_attitude_transform` function by calling the function of the EO\_POINTING software library `xp_get_code` (see [GEN\_SUM]).

**Table 289: Error messages of `xp_attitude_transform` function**

Error type	Error message	Cause and impact	Error code	Error No
ERR	Error transforming quaternions to vectors	No computation performed	<code>XP_ATTITUDE_TRANSFORM_QUAT_2_VEC_ERR</code>	0
ERR	Error computing rotation matrix	No computation performed	<code>XP_ATTITUDE_TRANSFORM_GET_ROTATION_ERR</code>	1
ERR	Error transforming vectors to quaternions	No computation performed	<code>XP_ATTITUDE_TRANSFORM_VEC_2_QUAT_ERR</code>	2
ERR	Uninitialized attitude	No computation performed	<code>XP_ATTITUDE_TRANSFORM_UNINIT_ATTITUDE_ERR</code>	3
ERR	Only <code>XP_SAT_NOMINAL_ATT</code> , <code>XP_SAT_ATT</code> and <code>XP_INSTR_ATT</code> allowed	No computation performed	<code>XP_ATTITUDE_TRANSFORM_UNALLOWED_ATT_TYPE_ERR</code>	4
ERR	Transformation not supported for Star Tracker data	No computation performed	<code>XP_ATTITUDE_TRANSFORM_STAR_TRACKER_NOT_SUPPORTED_ERR</code>	5



## 8 RUNTIME PERFORMANCES

The library performance has been measured by dedicated test procedures run in 5 different platforms under the below specified machines:

<i>OS ID</i>	<i>Processor</i>	<i>OS</i>	<i>RAM</i>
LINUX64	Intel(R) Xeon(R) CPU E5-2470 0 @ 2.30GHz (16 cores)	GNU LINUX 2.6.24-16-generic (Ubuntu 8.04)	16 GB
LINUX32_LEGACY	Intel(R) Core(TM)2 Quad CPU Q8400 @ 2.66GHz	GNU LINUX 2.6.24-16-generic (Ubuntu 8.04)	4 GB
LINUX64_LEGACY	Intel(R) Core(TM)2 Quad CPU Q8400 @ 2.66GHz	GNU LINUX 2.6.24-16-generic (Ubuntu 8.04)	4 GB
MACIN64	Intel Core i7 4 cores @2,6 GHz	MAC OSX V10.9	16 GB
WINDOWS32	Intel(R) Xeon(R)CPU ES-2630 @ 2.40GHz 2.40GHz	Microsoft Windows 7	16 GB
WINDOWS64	Intel(R) Xeon(R)CPU ES-2630 @ 2.40GHz 2.40GHz	Microsoft Windows 7	16 GB

The table below shows the time (in milliseconds - ms) each function takes to be run under each platform:

<b>Function ID</b>	<b>WINDOWS32</b>	<b>WINDOWS64</b>	<b>LINUX64</b>	<b>LINUX64 LEGACY</b>	<b>LINUX32 LEGACY</b>	<b>MACIN64</b>
xp_attitude_init	0.002600	0.001900	0.000000	0.001000	0.001000	0.002000
xp_sat_nominal_att_init	0.001422	0.000966	0.000140	0.000180	0.000330	0.000230
xp_sat_nominal_att_init_file "5 Quaternions"	0.256000	0.222000	0.150000	0.190000	0.200000	0.190000
xp_sat_nominal_att_get_file	0.000231	0.000232	0.000170	0.000250	0.000280	0.000190
xp_sat_nominal_att_set_file	0.000385	0.000375	0.000170	0.000150	0.000360	0.000120
xp_sat_nominal_att_init_model	0.001460	0.001000	0.000100	0.000100	0.000300	0.000200
xp_sat_nominal_att_get_param	0.000053	0.000048	0.000020	0.000010	0.000030	0.000010

xp_sat_nominal_att set_param	0.000049	0.000050	0.000013	0.000012	0.000026	0.000008
xp_sat_att_matrix_i nit	0.001900	0.001400	0.000000	0.001000	0.001000	0.001000
xp_sat_att_init_har monic	0.001760	0.001080	0.000200	0.000300	0.000400	0.000200
xp_sat_att_init_file	0.253000	0.219000	0.160000	0.190000	0.210000	0.150000
xp_sat_att_angle_in it	0.001440	0.000981	0.000200	0.000240	0.000320	0.000200
xp_sat_att_get_angl es	0.000016	0.000014	0.000009	0.000009	0.000018	0.000005
xp_sat_att_set_angl es	0.000016	0.000013	0.000010	0.000010	0.000020	0.000010
xp_sat_att_quat_pl us_matrix_init	0.002090	0.001550	0.000500	0.000700	0.000800	0.000800
xp_sat_att_quat_pl us_angle_init	0.002230	0.001560	0.000700	0.000800	0.001200	0.001300
xp_sat_att_set_quat plus_matrix	0.000280	0.000270	0.000000	0.000100	0.000200	0.000100
xp_sat_att_set_quat plus_angle	0.001320	0.000280	0.000900	0.000200	0.000300	0.000100
xp_instr_att_init_ha rmonic	0.001760	0.001100	0.000200	0.000200	0.000400	0.000400
xp_instr_att_get_ha rmonic	0.000317	0.000095	0.000030	0.000030	0.000070	0.000020
xp_instr_att_set_ha rmonic	0.000320	0.000100	0.000100	0.000100	0.000100	0.000000
xp_instr_att_init_fil e	0.272000	0.246000	0.140000	0.200000	0.200000	0.160000
xp_instr_att_matrix init	0.001452	0.001234	0.000540	0.000820	0.000740	0.000660
xp_instr_att_get_m atrix	0.000042	0.000041	0.000012	0.000012	0.000024	0.000008
xp_instr_att_angle_ init	0.001436	0.000989	0.000110	0.000180	0.000390	0.000280
xp_instr_att_get_an gles	0.000016	0.000013	0.000010	0.000010	0.000020	0.000000
xp_instr_att_set_an gles	0.000016	0.000013	0.000010	0.000010	0.000020	0.000010
xp_attitude_comput e * target frame: XP INSTR ATT"	0.035200	0.030600	0.022000	0.028000	0.032000	0.014000
xp_attitude_get_id_ data	0.000182	0.000207	0.000040	0.000050	0.000070	0.000030
xp_atmos_init	1.008200	0.699800	0.246000	0.378000	0.426000	0.656000
xp_atmos_get_id_d	0.000010	0.000009	0.000000	0.000010	0.000010	0.000000



ata						
xp_dem_init	1.101000	0.927000	0.340000	0.570000	0.440000	0.510000
xp_dem_get_info	0.034300	0.027600	0.009000	0.012000	0.014000	0.011000
xp_dem_compute	0.008000	0.086000	0.000000	0.110000	0.140000	0.150000
xp_dem_id_configure * load tiles->set cache max size->free cache"	66.970001	74.089996	59.200001	110.099998	134.399994	57.099998
xp_get_attitude_data	0.001000	0.000800	0.000000	0.000000	0.000000	0.000000
xp_target_inter	0.007800	0.003600	0.002000	0.004000	0.008000	0.002000
xp_target_get_id_data	0.000760	0.000870	0.000500	0.000700	0.000800	0.000500
xp_target_extra_vector * No derivatives"	0.000475	0.000382	0.000250	0.000340	0.000630	0.000160
xp_target_ground_range	0.047600	0.041800	0.036000	0.046000	0.040000	0.034000
xp_target_incidence_angle	0.046600	0.041000	0.032000	0.038000	0.052000	0.018000
xp_target_range	0.013200	0.012400	0.006000	0.012000	0.014000	0.008000
xp_target_range_rate	0.026000	0.022000	0.020000	0.030000	0.030000	0.010000
xp_target_tangent	0.023800	0.015800	0.012000	0.014000	0.022000	0.006000
xp_target_altitude	0.021100	0.012800	0.010000	0.015000	0.021000	0.007000
xp_target_star	0.000000	0.000000	0.000000	0.000000	0.000000	1.000000
xp_target_extra_vector * 1st Derivates"	0.000486	0.000386	0.000259	0.000343	0.000645	0.000158
xp_target_tangent_moon	0.041000	0.034000	0.030000	0.040000	0.050000	0.010000
xp_target_generic	0.006360	0.002440	0.000900	0.001400	0.003400	0.001300
xp_target_station	0.009520	0.007590	0.004800	0.007000	0.007200	0.003700
xp_target_extra_main	0.021150	0.015260	0.009900	0.013900	0.016700	0.005500
xp_target_extra_aux	0.091000	0.078000	0.060000	0.080000	0.080000	0.080000
xp_target_extra_target_to_sun	0.031560	0.023330	0.019900	0.025400	0.034800	0.008700
xp_target_extra_target_to_moon	0.035250	0.025690	0.022500	0.033800	0.040300	0.011800
xp_target_extra_effect_target	0.018000	0.013000	0.010000	0.010000	0.010000	0.010000
xp_target_extra_specular_reflection	0.011430	0.008630	0.005900	0.008800	0.009500	0.003200

xp_target_sc	0.195000	0.165000	0.130000	0.170000	0.190000	0.080000
xp_target_reflected	16.368000	14.600000	9.250000	11.910000	15.080000	7.010000
xp_target_travel_time	0.029090	0.019300	0.015500	0.021800	0.027300	0.008400
xp_multi_target_inter	0.053000	0.040000	0.040000	0.040000	0.050000	0.020000
xp_multi_target_travel_time	0.081300	0.058400	0.026000	0.033000	0.043000	0.013000
xp_change_frame	0.034000	0.028800	0.018000	0.026000	0.030000	0.013000
xp_target_list_inter * (time per user target)"	0.009607	0.005784	0.018626	0.005882	0.023527	0.005882
xp_target_inter + xp_target_extra_main * (DEM target)"	0.039800	0.042800	0.046000	0.064000	0.062000	0.050000
xp_target_list_extra_vector * (time per user target - DEM target)"	0.018332	0.014606	0.008823	0.013724	0.013724	0.007842
xp_target_list_extra_main * (time per user target - DEM target)"	0.033036	0.025194	0.008823	0.011764	0.012744	0.012744
xp_target_list_extra_aux * (time per user target - DEM target)"	0.088619	0.073718	0.009803	0.023527	0.022547	0.037251
xp_target_list_extra_ef_target * (time per user target - DEM target)"	0.030977	0.024605	0.008823	0.012744	0.011764	0.012744
xp_target_list_extra_specular_reflection * (time per user target - DEM target)"	0.029703	0.023429	0.008823	0.011764	0.011764	0.010783
xp_target_list_extra_target_to_moon * (time per user target - DEM target)"	0.035683	0.027056	0.009803	0.013724	0.013724	0.010783
xp_target_list_extra_target_to_sun * (time per user target - DEM target)"	0.035585	0.027546	0.009803	0.012744	0.013724	0.011764
xp_gen_dem_max_altitude_file * 3x3 minitiles (9 minitiles/tile)"	28478.000000	37726.000000	20270.000000	45050.000000	40400.000000	32430.000000
xp_gen_dem_altitudes_from_ellipsoid * 1 tile. 30	25049878.000000	53282.000000	160.000000	29640.000000	86180.000000	18670.000000

harmonics"						
xp_attitude_transformation	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000
xp_gen_attitude_data * (sat nominal. 2 orbits. time_step=10 sec)"	72.540001	62.070000	46.299999	65.699997	70.400002	26.299999
xp_gen_attitude_file * (sat nominal. 2 orbits. time_step=10 sec)"	110.650002	95.449997	83.500000	132.399994	141.500000	74.500000

Note that when the value "0.000000" is defined for a function in a certain platform, it means that its running time is lower than 1 nano-second and so it can be considered as "0".

## 9 LIBRARY PRECAUTIONS

The following precaution shall be taking into account when using EO\_POINTING library:

- When a message like  
<LIBRARY NAME> >>> ERROR in *xp\_function*: Internal computation error # *n*  
or  
<LIBRARY NAME> >>> WARNING in *xp\_function*: Internal computation warning # *n*  
appears, run the program in **verbose** mode for a complete description of warnings and errors and call for maintenance if necessary.

## 10 USER REFRACTION FILE

The refraction table is needed to initialize the atmosphere id with an user initialization mode.

The file must contain the co-index of refraction at different geometric altitudes, starting from 0 Km. The altitude should be strict monotonic increasing.

The format of that file must be as follows (a text file without headers):

*Table 290: User refraction file format*

<u>1<sup>st</sup> column</u>	<u>2<sup>nd</sup> column</u>
<u>Geometric altitude [m]</u>	<u>Co-index of refraction N</u>
<u>0.000</u>	<u>262.049</u>
<u>1000.000</u>	<u>238.630</u>
<u>2000.000</u>	<u>216928</u>
<u>3000.000</u>	<u>195.392</u>
<u>...</u>	<u>...</u>
<u>90000.000</u>	<u>0.001</u>
<u>95000.000</u>	<u>0.000</u>
<u>100000.000</u>	<u>0.000</u>

Note in this table that:

- the relative index of refraction  $m = 1 + N \times 10^{-6}$ , where N is the co-index of refraction.
- The fields of each row must be separated by blanks (at least one).